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MATHEMATICS

1970

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Abstract

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UDC 517.949.2

MATHEMATICS

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ON A QUALITATIVE INVESTIGATION OF STABILITY IN THE LARGE AND INSTABILITY FOR ONE CLASS OF AMPLITUDE-PULSE SYSTEMS

(Presented by Academician V. I. Smirnov on 5 V 1969)

1°. Let us consider a system of difference equations consisting of the linear part

$$\begin{aligned} z[n+1] &= Az[n] + B\xi[n] + f(n, z[n]), \\ \sigma[n] &= C^*z[n] \end{aligned} \quad (S)$$

and the nonlinear part

$$\xi[n] = \varphi(n, \sigma[k] \mid k = 0, 1, \dots, n) \quad (n = 0, 1, 2, \dots), \quad (\varphi)$$

which we shall denote by the symbol (S, φ, f) , and in the case $f \equiv 0$ by the symbol (S, φ) . Here the constant matrices A, B, C , the vector-solution $z[n]$ of the system (S, φ, f) , and the vectors ξ, φ, σ have dimensions, respectively, $\nu \times \nu$, $\nu \times p$, $\nu \times m$, ν , p , p , m . The vector-function $f(n, z)$ of order ν satisfies the condition

$$\lim |f|/|z| = 0$$

as $|z| \rightarrow \infty$, uniformly in n , while the vector of nonlinearities φ may depend on n and $\sigma[k]$, $0 \leq k \leq n$. All quantities in (S, φ, f) are real. Equations (S) , (φ) describe the well-known amplitude-pulse systems of automatic control with nonlinear modulators.

Let the matrix A have no eigenvalues on the unit circle $|\lambda| = 1$, where λ is a complex parameter, and let the rank of the $\nu \times p\nu$ matrix

$$\|B, AB, A^2B, \dots, A^{\nu-1}B\|$$

be equal to ν .

Introduce into consideration a real quadratic form $F(\xi, \sigma)$ of the vectors ξ and σ . We shall say that for the system (S, φ) the **condition $\{F\}$ is satisfied** if,

for every solution $z[n]$ of the system (S, φ) and the corresponding $\xi[n], \sigma[n]$, one has

$$F(\xi[n], \sigma[n]) \geq 0 \quad (n = 0, 1, 2, \dots).$$

In the usual way, introduce the $m \times p$ matrix of transfer functions by the equality

$$\chi(\lambda) = C^*(A - \lambda I)^{-1}B,$$

where I is the identity matrix of order $\nu \times \nu$. Regarding, in $F(\xi, \sigma)$, the arguments ξ and σ as independent, extend the form $F(\xi, \sigma)$, preserving Hermitian character, to complex values of the arguments and put

$$\tilde{F}(\lambda, \tilde{\xi}) = F(\tilde{\xi}, \tilde{\sigma}),$$

where

$$\tilde{\sigma} = -\chi(\lambda)\tilde{\xi},$$

and $\tilde{\xi}$ is an arbitrary complex p -vector. We shall say that for the system (S, φ) the **condition $\{\tilde{F}\}$ is satisfied** if the quadratic form $\tilde{F}(\lambda, \xi)$ of the vector argument ξ is negative definite for all values of λ , $|\lambda| = 1$.

Consider the following two types of behavior of solutions of the system (S, φ) :

- (A) There exist numbers $c > 0$, $\varepsilon > 0$ such that, for any solution $z[n]$ of the system (S, φ) and any $n \geq n_0 \geq 0$,

$$|z[n]| \leq ce^{-\varepsilon(n-n_0)} \times |z[n_0]|, \quad |\xi[n]| \in l_2(0, \infty),$$

and, consequently, $\xi[n] \rightarrow 0$ as $n \rightarrow \infty$.

- (B) In the space $\{z\}$ there exists a cone K of the form

$$z^*H_0z < 0,$$

where $H_0 = H_0^*$ is some matrix such that, for certain numbers $c > 0$, $\varepsilon > 0$ and for any solution $z[n]$ of the system (S, φ) satisfying the condition $z[n_0] \in K$, one has

$$|z[n]| \geq ce^{\varepsilon(n-n_0)}|z[n_0]|$$

for all $n \leq n_0 \geq 0$.

It is clear that case (A) means that the system (S, φ) is exponentially stable, while in case (B) the system (S, φ) is exponentially unstable.

2°. **Theorem 1.** (I). Suppose that for the system (S, φ) the conditions $\{F\}$ and $\{\tilde{F}\}$ are satisfied.

Then only the two above-indicated types of behavior of solutions of the system (S, φ) are possible: either (A), or (B).

(II). If for a system (S, ψ) , which differs from the system (S, φ) only in the vector of nonlinearities ψ , and for the system (S, φ) the conditions $\{F\}$ and $\{\tilde{F}\}$ are

satisfied simultaneously, then both systems have the same type of behavior of solutions: either (A), or (B). In this case the numbers $\varepsilon > 0$, $c > 0$ depend only on the coefficients of the linear part of the systems (S, φ) and (S, ψ) and on the quadratic form F .

Suppose that for the system (S, φ) the matrices A, B, C , the vector of nonlinearities φ , and, generally speaking, the coefficients of the quadratic form F depend on some real parameter a , $0 \leq a \leq 1$. Denote them by $A_a, B_a, C_a, \varphi_a, F_a$. Construct the form

$$\tilde{F}_a(\lambda, \tilde{\xi}) = F_a(\tilde{\xi}, \tilde{\sigma}),$$

where

$$\tilde{\sigma} = -C_a^*(A_a - \lambda I)^{-1} B_a \tilde{\xi}.$$

Theorem 2. Suppose that the coefficients of the form F_a , as well as A_a, B_a, C_a , depend continuously on a , and that for $0 \leq a \leq 1$ the conditions $\{F_a\}, \{\tilde{F}_a\}$ are satisfied. Then for all systems (S_a, φ_a) , $0 \leq a \leq 1$, either (A) or (B) holds, and the numbers $c > 0$, $\varepsilon > 0$ do not depend on a .

Theorem 3. Suppose that the system (S, φ) satisfies the conditions $\{F\}, \{\tilde{F}\}$ for some form F .

(I). Let case (A) hold for the system (S, φ) . Then in the space $\{z\}$ there exists an ellipsoid

$$\Phi\{z^* H_0 z < \text{const}\}$$

with matrix $H_0 = H_0^* > 0$, such that for the solutions of the system (S, φ, f) the following holds: a) from $z[n_0] \in \Phi$ it follows that $z[n] \in \Phi$ for $n \geq n_0$; b) for any solution $z[n]$ there is an $n_0 > 0$ for which $z[n_0] \in \Phi$.

(II). Let case (B) hold for the system (S, φ) . Then in the space $\{z\}$ there exists a domain

$$Q\{|z| \geq \text{const}, z^* H_0 z < 0\}$$

with Hermitian matrix H_0 , such that for all solutions of the system (S, φ, f) , if $z[n_0] \in Q$ and $n \geq n_0$, then

$$|z[n]| \geq \text{const} \cdot e^{\varepsilon(n-n_0)}, \quad \varepsilon > 0.$$

An analogous qualitative investigation of the behavior of solutions of the system (S, φ) under more stringent assumptions was carried out in the paper ⁽⁵⁾, where instability is understood in a weaker sense. Namely, in the space $\{z\}$ of states of the system there exists a vector a such that, for $z[0] = a$,

$$|z[n]| \rightarrow \infty \quad \text{as } n \rightarrow \infty.$$

3°. Theorems 1 and 2 are proved according to the scheme of the proofs of analogous Theorems 1-3 ⁽¹⁾ concerning the investigation of differential equations. The proof of assertion (I) of Theorem 3 is analogous to the proof of Theorem 4

⁽²⁾, while assertion (II) of Theorem 3 is established according to the scheme of the proof of case (B) of Theorem 1. The following lemmas are used.

Lemma 1. Let $V(z)$ be a continuous scalar function of the vector argument z , and let $V(0) = 0$. Consider the first difference

$$\Delta V = V(Az[n] + B\xi[n]) - V(z[n])$$

of the function $V(z)$ along the system (S, φ) . Suppose that the inequality

$$\Delta V \leq -W$$

holds, where $W(z[n], \xi[n])$ ($n = 0, 1, 2, \dots$) is a positive definite quadratic form of the vectors $z[n]$ and $\xi[n]$.

(I). If $V(z[n]) \geq 0$ ($n = 0, 1, \dots$) for some solution $z[n]$ of the system (S, φ) , then

$$|z[n]|, |\xi[n]| \in l_2(0, \infty)$$

and, consequently,

$$|z[n]| \rightarrow 0, \quad |\xi[n]| \rightarrow 0 \quad \text{as } n \rightarrow \infty.$$

(II). If $z[n] \rightarrow 0$ as $n \rightarrow \infty$, then $V(z[n]) > 0$ for $z[n] \neq 0$ ($n = 0, 1, \dots$).

(III). If $z[n] \neq 0$ as $n \rightarrow \infty$, then $V(z[n]) \rightarrow -\infty$ as $n \rightarrow \infty$.

Lemma 2. (generalized Kalman-Szegő-Popov lemma). Suppose constant matrices A, B of dimensions $\nu \times \nu$ and $\nu \times \rho$, respectively, are given, and a Hermitian form

$$\Omega(z, \xi, H) \equiv z^* H z - (Az + B\xi)^* H (Az + B\xi) + U(z, \xi),$$

where the $\nu \times \nu$ matrix $H = H^*$ is to be found, the form $U(z, \xi)$ is Hermitian, and the vectors

z and ζ have, respectively, orders ν and p , the rank of the $\nu \times p\nu$ -matrix $\|B, AB, \dots, A^{\nu-1}B\|$ is equal to ν . Then, for the existence of a matrix $H = H^*$ such that the form $\Omega(z, \zeta, H)$ is a positive definite form of the vectors z and ζ , it is necessary and sufficient that for all λ , $|\lambda| = 1$, such that $\det(A - \lambda I) \neq 0$, the form $U(-(A - \lambda I)^{-1}B\zeta, \zeta)$ be a positive definite form of the vector argument ζ .

Lemma 3. Consider the system

$$z[n+1] = f(n, z[n]),$$

where the ν -vector function $f(n, z)$ is bounded when the arguments lie in a bounded domain. Suppose that there exists a function $V(z)$, continuous in z , satisfying the conditions: 1) $V(z) \rightarrow \infty$ as $|z| \rightarrow \infty$; 2) there exist $\xi_0 > 0$ and a continuous function $\alpha(z) > 0$, defined for $|z| \geq \xi_0$, such that, for any solution

$z[n]$ of the system under consideration, when $|z[n]| \geq \xi_0$ one has $\Delta V \leq -\alpha(z[n])$. Choose a number $\eta > 0$ so that $F = E\{V(z) \leq \eta\} \supset E\{|z| \leq \xi_0\}$.

Then, for solutions $z[n]$ of the system under consideration, the following hold: a) from $z[n_0] \in F$ it follows that $z[n] \in F$ for $n \geq n_0$; b) every solution $z[n]$, starting from some instant n_0 , enters F .

Lemmas 1 and 3 are proved analogously to Lemmas 1⁽¹⁾ and 1⁽²⁾. The simple proof of Lemma 2, different from the proof in ⁽³⁾, consists in reducing it to Lemma 2⁽¹⁾. Setting

$$P = (A + \rho I)^{-1}(A - \rho I), \quad Q = (I - P)B,$$

$$z = \frac{1}{\rho}(I - P) \left(x - \frac{1}{2}B\zeta \right),$$

$$\xi = 1/2\zeta, \quad \lambda = \rho(1 + i\omega)/(1 - i\omega),$$

where $-\infty \leq \omega \leq +\infty$, and the number ρ , $|\rho| = 1$, is such that $\det(A + \rho I) \neq 0$, we obtain

$$(Az + B\zeta)^*H(Az + B\zeta) - z^*Hz = 2 \operatorname{Re} x^*H(Px + Q\xi).$$

It is easy to verify that all the conditions of Lemma 2 are thereby transformed into the corresponding conditions of Lemma 2⁽¹⁾, from which the assertion of the lemma being proved follows. This device was used by Yu. A. Dmitriev in ⁽⁴⁾, where an analogous lemma was formulated for a Hermitian form $U(z, \zeta)$ of a vector variable z and a scalar variable ζ of a special kind, under the assumption that the eigenvalues of the matrix A lie inside the unit circle, except perhaps for a single eigenvalue on the unit circumference.

4°. Proof of Theorem 1. (I). Construct the function $V(z) = z^*Hz$, where H is a Hermitian matrix satisfying the conditions of Lemma 1. We have $\Delta V = -\Omega(z, \zeta, H) - F(\zeta, \sigma)$, where Ω has the form indicated in Lemma 2, and $U(z, \zeta) = -F(\zeta, \sigma)$ with σ from (S) . From condition $\{F\}$ the condition of Lemma 2 follows. Therefore there exists a matrix $H = H^*$ such that $\Omega(z, \zeta, H)$ is a positive definite form of z and ζ . From condition $\{\tilde{F}\}$ it follows that $\Delta V \leq -\Omega(z, \zeta, H)$. If $z[n] \rightarrow 0$ as $n \rightarrow \infty$, then, by Lemma 1, $V(z[n]) > 0$ ($n = 0, 1, \dots$). Let the number $\varepsilon > 0$ be such that $\Omega \geq (1 - e^{-2\varepsilon})V$. Then $\Delta V + (1 - e^{-2\varepsilon})V \leq 0$, whence $V(z[n]) \leq e^{-2\varepsilon n}V(z[0])$, $|z[n]| \leq ce^{-\varepsilon n}|z[0]|$ with some $c > 0$.

By Lemma 1, in addition, we have $|\zeta[n]| \in l_2(0, \infty)$, and, consequently, $\zeta[n] \rightarrow 0$ as $n \rightarrow \infty$. Thus, in this case, (A) holds.

Suppose now that $z[n] \not\rightarrow 0$ as $n \rightarrow \infty$. Then, by Lemma 1, $V(z[n]) \rightarrow -\infty$ as $n \rightarrow \infty$, i.e. the set $K\{V(z) < 0\}$ is nonempty. Let $z[0] \in K$; then $V(z[n]) < 0$ for $n = 0, 1, 2, \dots$. Represent $V(z)$ in the form $V(z) = V_1(z) - V_2(z)$, where

the quadratic forms $V_1(z)$ and $V_2(z)$ are nonnegative. Choose $\varepsilon > 0$ so that $\Omega \geq (e^{2\varepsilon} - 1)V_2$. Then $-\Delta V \geq \Omega \geq (e^{2\varepsilon} - 1)V_2 \geq (e^{2\varepsilon} - 1)(-V)$. Hence $-V(z[n]) \geq e^{2\varepsilon n}(-V(z[0]))$ and $|z[n]| \geq ce^{\varepsilon n}|z[0]|$. Consequently, case (B) holds.

(II). In the proof of point (I) only the conditions $\{F\}$ and $\{\tilde{F}\}$ were used, but not the concrete form of the nonlinearities φ , i.e. assertion (A) of Theorem 1 is valid.

Proof of Theorem 2. From the proof of Theorem 1 it follows that, for the system $(S_\alpha, \varphi_\alpha)$, there exists a function $V(z) = z^*H_\alpha z$ satisfying the conditions of Lemma 1. Let $\alpha_0 \in [0, 1]$. Then ΔV , in view of the system $(S_\alpha, \varphi_\alpha)$ for $\alpha \in \Delta(\alpha_0)$, where $\Delta(\alpha_0)$ is a sufficiently small open interval containing α_0 , has the form

$$\Delta V = -\Omega_\alpha - F_\alpha,$$

where

$$\Omega_\alpha = -(A_\alpha z + B_\alpha \xi)^* H_\alpha (A_\alpha z + B_\alpha \xi) + z^* H_\alpha z - F_\alpha$$

is a positive definite quadratic form.

Then, by what has been proved, for all systems $(S_\alpha, \varphi_\alpha)$, $\alpha \in \Delta(\alpha_0)$, either case (A) or case (B) holds. Choosing from the system of $\Delta(\alpha)$, $\alpha \in [0, 1]$, a finite covering $\Delta_1, \dots, \Delta_k$, we obtain the assertion of Theorem 2.

Proof of Theorem 3. (I). Consider the function $V(z) = z^* H z$ with Hermitian matrix H . Suppose that, for the system (S, φ) , the solution $z[n] \rightarrow 0$ as $n \rightarrow \infty$. From the proof of Theorem 1,

$$\Delta V \leq -\Omega(z, \xi, H),$$

where Ω is a positive definite form in z and ξ . Then, by Lemma 1, $V(z) > 0$ for $z \neq 0$. Apply this same function $V(z)$ to the investigation of the system (S, φ, f) . We have

$$\Delta V = -\Omega(z, \xi, H) - F + f^* H f + 2 \operatorname{Re} f^* H (Az + B\xi).$$

Choose a number $\delta > 0$ such that $\Omega \geq \delta(|z|^2 + |\xi|^2)$. Since $\lim |f|/|z| = 0$ as $|z| \rightarrow \infty$, there exists a sufficiently large number ξ_0 such that, for $|z| \geq \xi_0$,

$$f^* H f + 2 \operatorname{Re} f^* H A z \leq \frac{1}{2} \delta |z|^2, \quad 2 \operatorname{Re} f^* H B \xi \leq \frac{1}{4} \delta (|z|^2 - |\xi|^2).$$

Then, for $|z| \geq \xi_0$, it is true that

$$\Delta V \leq -\frac{1}{4} \delta |z|^2.$$

By Lemma 3 we are convinced of the validity of (I) of Theorem 3.

(II). Suppose that, for (S, φ) , case (B) holds. By Lemma 1, $V(z[n]) \rightarrow -\infty$ as $n \rightarrow \infty$ for $z[n] \not\rightarrow 0$ as $n \rightarrow \infty$, i.e., the set $z^* H z < 0$ is nonempty. From the conditions $\{F\}$ and $\{\tilde{F}\}$, for sufficiently large ξ_0 , when $|z| \geq \xi_0$ it will hold that

$$-\Delta V = \Omega + F - f^* H f - 2 \operatorname{Re} f^* H (Az + B\xi) \equiv W,$$

where the quadratic form W is positive definite, i.e.,

$$\Delta V \leq -W < 0.$$

Consequently, if

$$z[0] \in \{z^* H z < 0\}$$

and $|z| > \xi_0$, then

$$V(z[n]) < 0.$$

Let $V = V_1 - V_2$, where the quadratic forms V_1 and V_2 are nonnegative. Choose a number $\varepsilon > 0$ such that

$$W \geq (e^{2\varepsilon} - 1)V_2.$$

Then

$$-\Delta V \geq W \geq (e^{2\varepsilon} - 1)V_2 \geq (e^{2\varepsilon} - 1)(-V).$$

Hence

$$|z[n]| \geq \text{const} \cdot e^{\varepsilon n}.$$

Received
21 IV 1969

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