

# A PRIORI ESTIMATES AND HYPOELLIPTIC OPERATORS WITH MULTIPLE CHARACTERISTICS

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**Abstract**

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**MATHEMATICS**

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## A PRIORI ESTIMATES AND HYPOELLIPTIC OPERATORS WITH MULTIPLE CHARACTERISTICS

*(Presented by Academician I. G. Petrovskii on February 7, 1969)*

In the paper (<sup>1</sup>) L. Hörmander, for a second-order differential operator of the form

$$Pu = \sum_{j=1}^N X_j^2 u + iX_0 u + \gamma(x)u, \quad (1)$$

where  $X_j(x, D)$  ( $j = 0, 1, \dots, N$ ) are first-order differential operators with infinitely differentiable coefficients, obtained sufficient conditions for the existence of estimates

$$\sum_{j=1}^N \|X_j u\|_{(\varepsilon)}^2 + \|u\|_{(2\varepsilon)}^2 \leq C(K) \{ \|Pu\|_{(0)}^2 + \|u\|_{(0)}^2 \}, \quad u \in C_0^\infty(K), \quad (2)$$

where  $K$  is any compact set in the domain  $\Omega \subset R^n$  and the constant  $\varepsilon = \varepsilon(K) > 0$  (see (<sup>2</sup>)); it can be shown that Hörmander's conditions are also necessary in the class of operators of the form (1) for the existence of the estimate (2) with some  $\varepsilon(K) > 0$  ( $D_j = -i\partial/\partial x_j$ ,  $j = 1, \dots, n$ ;  $i^2 = -1$ ). In the paper (<sup>2</sup>) a simple proof of Hörmander's theorem was obtained. Using the same method, we shall consider the general case of second-order differential operators with nonnegative characteristic form, namely:

$$Lu \equiv \sum_{k,j=1}^n a^{kj}(x) D_k D_j u + iX_0(x, D)u + \gamma(x)u, \quad (3)$$

where  $a^{kj}(x)\xi_k\xi_j \geq 0$  for any point  $(x, \xi) \in \Omega \times S^{n-1}$ .

The question of global smoothness of generalized solutions of boundary-value problems for equation (3) was considered in the papers (<sup>3-6</sup>). We shall give

sufficient conditions for local smoothness of generalized solutions of equation (3).

In the domain  $\Omega \subset R^n$  consider the system of differential operators

$$\{L^{0(j)}, j = 1, \dots, n; \quad L_{(j)}^0, j = 1, \dots, n; \quad X_0 + L_{(j)}^{0(j)}\},$$

where

$$L^{0(j)}(x, D) \equiv \sum_k a^{kj}(x) D_k \quad (j = 1, \dots, n);$$

$$L_{(s)}^0(x, D) \equiv \sum_{k,j} \frac{\partial a^{kj}(x)}{\partial x_s} D_k D_j \quad (s = 1, \dots, n); \quad L_{(j)}^{0(j)} \equiv \sum_{k,j} \frac{\partial a^{kj}}{\partial x_j} D_k.$$

For any multi-index  $I = (\alpha_1, \dots, \alpha_k)$  ( $k \geq 1$ ), where  $\alpha_s = 0, 1, \dots, 2n$ , for any  $s = 1, \dots, k$  put:  $|I| = \sum_{s=1}^k \lambda_s$ , where  $\lambda_s = 2$  if  $\alpha_s = 0$ , and  $\lambda_s = 1$  if  $\alpha_s = 1, \dots, 2n$ , and let

$$A_I(x, D) \equiv \text{ad } A_{\alpha_1} \dots \text{ad } A_{\alpha_{k-1}} A_{\alpha_k},$$

where  $A_s(x, D) \equiv L^{0(s)}(x, D)$  ( $s = 1, \dots, n$ );  $A_{s+n}(x, D) \equiv L_{(s)}^0(x, D)$  ( $s = 1, \dots, n$ );  $A_0(x, D) \equiv X_0 + L_{(j)}^{0(j)}$  and  $\text{ad } AB = AB - BA$  for any pseudodifferential operators  $A, B$  (see, for example, (7)).

**Definition.** The system of operators  $(A_0, \dots, A_{2n})$  has at the point  $x_0 \in \Omega$  rank  $R_{(A_0, \dots, A_{2n})}(x_0) = k$ , if

$$\sum_{|I| \leq k-1} |A_I^0(x_0, \xi)| = 0 \quad \text{for some } \xi \in S^{n-1}; \quad (4)$$

$$\sum_{|I| \leq k} |A_I^0(x_0, \xi)| \neq 0 \quad \text{for every } \xi \in S^{n-1}, \quad (5)$$

where  $A_I^0$  is the principal part of the symbol  $\sigma(A_I)(x, \xi)$  of the operator  $A_I$  (see, for example, (7)),  $S^{n-1} = \{\xi \in R^n : \sum \xi_j^2 = 1\}$ .

**Remark.** It is easy to show that the definition of  $R_{(A_0, \dots, A_{2n})}(x)$  is invariant under infinitely differentiable changes of independent variables; moreover, if  $R_{(A_0, \dots, A_{2n})}(x) < \infty$  for every point  $x \in \Omega$ , then

$$R_L(K) = \sup_K R_{(A_0, \dots, A_{2n})}(x) = k(K) < \infty$$

for every compact set  $K \subset \Omega$ .

**Theorem 1.** If  $R_L(x) < \infty$  for every point  $x \in \Omega$ , then for every compact  $K \subset \Omega$  there exists a constant  $C(K)$  such that the inequality

$$\begin{aligned} \sum_{j=1}^n \left( \|L^{0(j)}u\|_{(\varepsilon(K))}^2 + \|L_{(j)}^0u\|_{(\varepsilon(K)-1)}^2 \right) + \|u\|_{(\varepsilon(K)+2^{1-R_L(K)})}^2 &\leq \\ &\leq C(K) \left( \|Pu\|_{(0)}^2 + \|u\|_{(0)}^2 \right), \quad u \in C_0^\infty(K), \end{aligned} \quad (6)$$

holds, where

$$\varepsilon(K) = \min \left( 1, 2^{1-R(K)} (2^{R(K)-1} - 1)^{-1} \right).$$

**Theorem 2.** If  $R_L(x) < \infty$  for every point  $x \in \Omega$ , then for every compact  $K \subset \Omega$ , every  $s \in \mathbb{R}^1$ , there exists a constant  $C(K, s)$  such that for every function  $u \in D'(\Omega)$  such that  $Lu \in H_{(s)}^{\text{loc}}$ , an estimate of the form

$$\|\varphi u\|_{(s+\varepsilon(K)+2^{1-R_L(K)})}^2 \leq C(K, s) \left( \|\varphi_1 Pu\|_{(s)}^2 + \|\varphi_1 u\|_{(\gamma)}^2 \right), \quad (7)$$

holds, where the functions  $\varphi, \varphi_1 \in C_0^\infty(K)$  and  $\varphi_1 \equiv 1$  in a neighborhood of  $\text{supp } \varphi$ ,  $\gamma = \text{const} < s + \varepsilon(K) + 2^{1-R_L(K)}$ .

**Theorem 3.** If  $R_L(x) < \infty$  for every point  $x$  of the manifold  $M$ , where  $L$  is a second-order differential operator with nonnegative characteristic form, defined on  $M$ , then  $L$  is a hypoelliptic operator.

The proof of Theorem 1, from which Theorems 2 and 3 can be obtained by known methods (see, for example, (10)), is based on the following auxiliary assertions.

**Lemma 1** (energy estimate). For every compact  $K \subset \Omega$  and every  $s \geq 0$  there exists a constant  $C(K, s)$  such that for every  $\mu$  ( $0 < \mu < 1$ ) the inequality

$$\begin{aligned} \sum_{j=1}^n \left( \|L^{0(j)}u\|_{(s)}^2 + \|L_{(j)}^0u\|_{(s-1)}^2 \right) + \|(X_0 + L_{(j)}^{0(j)})u\|_{(s-1/2)}^2 &\leq \\ &\leq C(K, s) \left\{ \frac{1}{\mu} \|Lu\|_{(0)}^2 + \mu \|u\|_{(2s)}^2 + C_\mu \|u\|_{(0)}^2 \right\}, \quad u \in C_0^\infty(K). \end{aligned} \quad (8)$$

For every  $s \in \mathbb{R}^1$  in the domain  $\Omega$  introduce the pseudodifferential operator  $\mathcal{E}_{(s)}$  with symbol

$$\sigma(\mathcal{E}_{(s)})(x, \xi) = \varphi(x)(1 + |\xi|^2)^{s/2},$$

where the function  $\varphi(x) \in C_0^\infty(\Omega)$  and  $\varphi \equiv 1$  in a neighborhood of the compact set  $K$ .

Consider the system  $(Q_0, \dots, Q_{2n})$  of first-order pseudodifferential operators, where  $Q_j = L^{0(j)}$  ( $j = 1, \dots, n$ );  $Q_0 = X_0 + L_{(j)}^{0(j)}$ ,  $Q_{n+j} = L_{(j)}^0 \mathcal{E}_{(-1)}$  ( $j = 1, \dots, n$ ).

**Lemma 2.** For every compact  $K \subset \Omega$ , every integer  $k \geq 1$ , and every  $s$  ( $0 \leq s < 1/2^{k-1}$ ) there exists a constant  $C(K, k, s)$  such that for

for any  $\mu$  ( $0 < \mu < 1$ ) the inequality

$$\sum_{|I|=k} \|Q_{Iu}\|_{(s-1+2^{1-k})}^2 \leq C(K, k, s) \times \left\{ \frac{1}{\mu} \|Lu\|_{(0)}^2 + \mu \|u\|_{(2s)}^2 + \mu \|u\|_{(2^{k-1}s)}^2 + C_\mu \|u\|_{(0)}^2 \right\}, \quad u \in C_0^\infty(K). \quad (9)$$

From the condition  $R_L(K) < \infty$  it follows that there exists a neighborhood  $O_x \subset \Omega$  of the point  $x$  and a finite system of operators  $(Q_{I_1}, \dots, Q_{I_l})$ , ( $|I_j| \leq R$  for any  $j \leq l$ ), which is elliptic in the domain  $U_x$ . Therefore the following is valid.

**Lemma 3.** If  $R_L(x) < \infty$ , then there exists a neighborhood  $U_x \subset \Omega$  of the point  $x$  such that an estimate of the form

$$\|u\|_{(s+2^{1-R_L(x)})}^2 \leq C_1 \left\{ \sum_{|I| \leq R_L(x)} \|Q_{Iu}\|_{(s-1+2^{1-|I|})}^2 + \|u\|_{(s)}^2 \right\}, \quad u \in C_0^\infty(O_x). \quad (10)$$

From Lemmas 1-3 follows the proof of Theorem 1.

In papers <sup>(8,9)</sup>, for a scalar pseudodifferential operator  $P$  and any compact set  $K \subset \Omega$ , algebraic necessary and sufficient conditions were obtained for the existence of estimates of the form:

$$\|u\|_{(m-\delta)}^2 \leq C(K) \{ \|Pu\|_{(0)}^2 + \|u\|_{(0)}^2 \}, \quad u \in C_0^\infty(K), \quad (11)$$

where  $m$  is the order of the operator  $P$  and  $0 \leq \delta < 3/4$ .

We shall consider the class of pseudodifferential operators  $P$  of order  $m$ , satisfying the following conditions:

1.  $p^0(x, \xi) \geq 0$  for any point  $(x, \xi) \in \Omega \times S^{n-1}$ .
2.  $p^1(x, \xi) = -\overline{p^1(x, \xi)}$  for any point  $(x, \xi) \in N$ , where

$$N = \{(x, \xi) \in \Omega \times S^{n-1}; p^0(x, \xi) = 0\},$$

and  $p^\nu(x, \xi)$  are the terms homogeneous of order  $m - \nu$  in the asymptotic expansion in  $\xi$  of the symbol  $\sigma(P)(x, \xi)$  of the operator  $P$  as  $\xi \rightarrow \infty$  (see, for example, (7)).

Applying the method of localization of pseudodifferential operators proposed in paper (8), we obtain algebraic necessary and sufficient conditions for the existence, for any compact set  $K \subset \Omega$ , in the class of operators satisfying conditions 1, 2, of estimates of the form

$$\|\varphi u\|_{(m+s-1)}^2 \leq C(K, s) \{ \|\varphi_1 P u\|_{(s)}^2 + \|\varphi_1 u\|_{(\gamma)}^2 \} \quad (12)$$

for any function  $u \in D'(\Omega)$  such that  $P u \in H_{(s)}^{loc}$ , where the functions  $\varphi, \varphi_1 \in C_0^\infty(K)$ ;  $\varphi_1 \equiv 1$  in a neighborhood of  $\text{supp } \varphi$ ;  $\gamma = \text{const} < m + s - 1$ .

For any point  $(x, \eta)$  of the characteristic manifold  $N$ , consider the symmetric matrix

$$\mathfrak{A}(x, \eta) = \begin{pmatrix} p^{0(kj)}(x, \eta) & p^{0(k)}(x, \eta) \\ p^{0(j)}(x, \eta) & p^0_{(kj)}(x, \eta) \end{pmatrix} \quad (k, j = 1, \dots, n),$$

where for any multiindices  $\alpha, \beta$  ( $|\alpha| + |\beta| = 2$ )

$$p_{(\beta)}^{\nu(\alpha)}(x, \xi) = \partial_x^\beta \partial_\xi^\alpha p^\nu(x, \xi).$$

By virtue of condition 1 the matrix  $\mathfrak{A}(x, \eta)$  is positive semidefinite at any point  $(x, \eta) \in N$ . Let

$$\{Y_j = (a_1^j, \dots, a_n^j, b_1^j, \dots, b_n^j), j = 1, \dots, 2n\}$$

be an orthonormal system of eigenvectors of the matrix  $\mathfrak{A}(x, \eta)$ , and let

$$\{Y_j^+, j \leq s(x, \eta)\}$$

be the set of eigenvectors corresponding to the positive eigenvalues of this matrix;

$$I(x, \eta) \equiv \left| p_{(j)}^{0(j)}(x, \eta) - i p^1(x, \eta) \right| + \sum_{j,k}^{S(x,\eta)} \left| \sum_{l=1}^n (a_l^j b_l^k - a_l^k b_l^j) \right|.$$

**Theorem 4.** A necessary and sufficient condition for the existence, for the operator  $P$  with conditions 1, 2, for every compact  $K \subset \Omega$ , of the estimate

$$\|u\|_{(m-1)}^2 \leq C(K) \{ \|P u\|_{(0)}^2 + \|u\|_{(0)}^2 \}, \quad u \in C_0^\infty(K), \quad (13)$$

is the fulfillment of the inequality

$$I(x, \eta) > 0 \quad \text{for every point } (x, \eta) \in N. \quad (14)$$

**Theorem 5.** If the pseudodifferential operator  $P$  satisfies conditions 1, 2 and (14), then for every compact  $K \subset \Omega$  there exists a constant  $C(K)$  such that the inequality

$$\begin{aligned} \|u\|_{(m-1)}^2 + \sum_{s=1}^n \|P^{(s)}u\|_{(1/2)}^2 + \|P_{(s)}u\|_{(-1/2)}^2 &\leq \\ &\leq C(K)\{\|Pu\|_{(0)}^2 + \|u\|_{(0)}^2\}, \quad u \in C_0^\infty(K). \end{aligned} \quad (15)$$

From estimate (15) (see, for example, <sup>10</sup>) it follows:

**Theorem 6.** If the differential operator  $P$  with infinitely differentiable coefficients satisfies conditions 1, 2 and (14), then for every compact  $K \subset \Omega$  and every  $s \in \mathbb{R}^1$  there exists a constant  $C(K, s)$  such that for any function  $u \in D'(\Omega)$  such that  $Pu \in H_{(s)}^{\text{loc}}$ , the estimate

$$\|\varphi u\|_{(s+m-1)}^2 \leq C(K, s)\{\|\varphi_1 Pu\|_{(s)}^2 + \|\varphi_1 u\|_{(\gamma)}^2\},$$

holds, where the functions  $\varphi, \varphi_1 \in C_0^\infty(K)$  and  $\varphi_1 \equiv 1$  on  $\text{supp } \varphi$ ;  $\gamma = \text{const} < s + m - 1$ .

**Theorem 7.** A differential operator  $P$  satisfying conditions 1, 2 and (14) is hypoelliptic in  $\Omega$ .

**Remark.** For a differential operator  $P$  of second order of the form (1), condition (14) is equivalent to the following inequality:

$$|X_0(x, \xi)| + \sum_{j,k=1}^N |[X_j, X_k](x, \xi)| > 0 \quad \text{for every point } (x, \xi) \in N.$$

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