

SUCCESSIVE APPROXIMATIONS FOR FINDING SADDLE POINTS

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Abstract

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MATHEMATICS

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SUCCESSIVE APPROXIMATIONS FOR FINDING SADDLE POINTS

(Presented by Academician L. V. Kantorovich on 9 I 1967)

1°. Statement of the problem. Of great interest is the problem of finding saddle points of functions ⁽¹⁻³⁾. The problem of finding the minimax of a continuously differentiable function was considered in ⁽⁴⁾.

Let $f(X, Y)$ be a function continuously differentiable on $\Omega_X \times \Omega_Y$, and let the sets $\Omega_X \subset E_n$ and $\Omega_Y \subset E_m$ be convex, closed, and bounded.

Let (X^*, Y^*) be a saddle point of the function $f(X, Y)$ on $\Omega_X \times \Omega_Y$, i.e., for all $X \in \Omega_X$, $Y \in \Omega_Y$,

$$f(X, Y^*) \leq f(X^*, Y^*) \leq f(X^*, Y); \quad (1)$$

then

$$f(X^*, Y^*) = \max_{X \in \Omega_X} f(X, Y^*) = \min_{Y \in \Omega_Y} f(X^*, Y). \quad (2)$$

We shall call the function $f(X, Y)$ **concave-convex** if, for every fixed $Y \in \Omega_Y$, the function $f_Y(X) \equiv f(X, Y)$ is concave in X on Ω_X , and for every fixed $X \in \Omega_X$, the function $f_X(Y) \equiv f(X, Y)$ is convex in Y on Ω_Y .

It is required to find a saddle point of the function $f(X, Y)$ on $\Omega_X \times \Omega_Y$.

As is not difficult to see, the following is true (for example, see ⁽⁵⁾).

Theorem 1. *In order that the point (X^*, Y^*) be a saddle point of the function $f(X, Y)$ on the set $\Omega_X \times \Omega_Y$, it is necessary (and if $f(X, Y)$ is concave-convex on $\Omega_X \times \Omega_Y$, also sufficient) that*

$$\max_{X \in \Omega_X} \left(\frac{\partial f(X^*, Y^*)}{\partial X} \right)^* (X - X^*) = \min_{Y \in \Omega_Y} \left(\frac{\partial f(X^*, Y^*)}{\partial Y} \right)^* (Y - Y^*) = 0. \quad (3)$$

Corollary. If $\Omega_X = E_n$, $\Omega_Y = E_m$, then condition (3) is replaced by the condition

$$\partial f(X^*, Y^*)/\partial X = \partial f(X^*, Y^*)/\partial Y = 0. \quad (4)$$

A point $(X^*, Y^*) \in \Omega_X \times \Omega_Y$ satisfying (3), or respectively (4) (if $\Omega_X = E_n$, $\Omega_Y = E_m$), is called a **stationary point** of the function $f(X, Y)$ on the set $\Omega_X \times \Omega_Y$.

2°. Let $\Omega_X = E_n$, $\Omega_Y = E_m$. Consider the systems of differential equations

$$dX(t)/dt \equiv \dot{X}(t) = \partial f(X, Y)/\partial X; \quad (5)$$

$$\dot{X}(0) = X_0 \in E_n; \quad (6)$$

$$dY(t)/dt \equiv \dot{Y}(t) = \partial f(X, Y)/\partial Y; \quad (7)$$

$$Y(0) = Y_0 \in E_m. \quad (8)$$

By $X(t, X_0, Y_0)$, $Y(t, X_0, Y_0)$ we denote the solutions of systems (5), (7) with the initial conditions (6), (8).

Suppose that the function $f(X, Y)$ is twice continuously differentiable and strictly concave-convex on $E_n \times E_m$. Then the matrices

$-\partial^2 f/\partial X^2$, $\partial^2 f/\partial Y^2$ are strictly positive definite, i.e., for any finite $(z_1, z_2) \in E_n \times E_m$ and for any $(X, Y) \in E_n \times E_m$

$$-z_1^* \left(\frac{\partial^2 f(X, Y)}{\partial X^2} z_1 \right) \geq m_1(X, Y) \|z_1\|^2, \quad m_1(X, Y) > 0; \quad (9)$$

$$z_2^* \left(\frac{\partial^2 f(X, Y)}{\partial Y^2} z_2 \right) \geq m_2(X, Y) \|z_2\|^2, \quad m_2(X, Y) > 0. \quad (10)$$

For any bounded set $S \subset E_n \times E_m$ there exist $m_1 > 0$ and $m_2 > 0$, depending on S , such that $m_1(X, Y) \geq m_1 > 0$, $m_2(X, Y) \geq m_2 > 0$ for all $(X, Y) \in S$.

By $M(X_0, Y_0) \subset E_n \times E_m$ we denote the set

$$\{(X, Y) \mid F(X, Y) \leq F(X_0, Y_0)\},$$

where

$$F(X, Y) = \frac{1}{2} [(\partial f(X, Y)/\partial X)^2 + (\partial f(X, Y)/\partial Y)^2].$$

Under the assumptions made, the following is valid.

Theorem 2. *If the set $M(X_0, Y_0)$ is bounded, then the solutions $X(t, X_0, Y_0)$, $Y(t, X_0, Y_0)$ of systems (5) and (7) converge to the unique saddle point.*

Systems (5), (7) give a “continuous” method for finding saddle points in the whole space. On the basis of this “continuous” method one can construct a number of discrete methods for finding saddle points. Let us consider one of the possible such methods.

Take arbitrary $(X_1, Y_1) \in E_n \times E_m$. Suppose that $M(X_1, Y_1)$ is bounded. Let (X_k, Y_k) have been found. Consider the rays

$$X_{k\alpha} = X_k + \alpha G_{Xk}, \quad \alpha \in [0, \infty),$$

$$Y_{k\beta} = Y_k - \beta G_{Yk}, \quad \beta \in [0, \infty),$$

where $G_{Xk} = \partial f(X_k, Y_k)/\partial X$, $G_{Yk} = \partial f(X_k, Y_k)/\partial Y$.

We have

$$F(X_{k\alpha}, Y_{k\beta}) = F(X_k, Y_k) + \alpha A_k + (\beta - \alpha) B_k - \beta C_k + O_k(\alpha, \beta), \quad (11)$$

where

$$A_k = \left(\frac{\partial f(X_k, Y_k)}{\partial X} \right)^* \left(\frac{\partial^2 f(X_k, Y_k)}{\partial X^2} \frac{\partial f(X_k, Y_k)}{\partial X} \right),$$

$$B_k = \left(\frac{\partial f(X_k, Y_k)}{\partial X} \right)^* \left(\frac{\partial^2 f(X_k, Y_k)}{\partial X \partial Y} \frac{\partial f(X_k, Y_k)}{\partial Y} \right),$$

$$C_k = \left(\frac{\partial f(X_k, Y_k)}{\partial Y} \right)^* \left(\frac{\partial^2 f(X_k, Y_k)}{\partial Y^2} \frac{\partial f(X_k, Y_k)}{\partial Y} \right),$$

$$\frac{O_k(\alpha, \beta)}{\sqrt{\alpha^2 + \beta^2}} \rightarrow 0 \quad \begin{matrix} \alpha \rightarrow +0 \\ \beta \rightarrow +0 \end{matrix} \quad \text{uniformly in } k,$$

and moreover

$$A_k < 0, \quad \text{if } G_{Xk} \neq 0,$$

$$C_k > 0, \quad \text{if } G_{Y_k} \neq 0.$$

If $B_k < 0$, set $\beta = 2\alpha$; if $B_k \geq 0$, set $\beta = \frac{1}{2}\alpha$. Then, if $2F(X_k, Y_k) = G_{X_k}^2 + G_{Y_k}^2 > 0$, for sufficiently small α and β we will have $F(X_{k\alpha}, Y_{k\beta}) < F(X_k, Y_k)$.

Find $\alpha_k \in [0, \infty)$ from the condition

$$F(X_{k\alpha_k}, Y_{k\beta(\alpha_k)}) = \min_{\alpha \in [0, \infty)} F(X_{k\alpha}, Y_{k\beta(\alpha)})$$

and set

$$X_{k+1} = X_{k\alpha_k}, \quad Y_{k+1} = Y_{k\beta(\alpha_k)}.$$

We proceed analogously further.

It can be shown that $X_k \xrightarrow[k \rightarrow \infty]{} X^*$, $Y_k \xrightarrow[k \rightarrow \infty]{} Y^*$, and (X^*, Y^*) is a saddle point of the function $f(X, Y)$ on $E_n \times E_m$.

Remark. As in the ordinary gradient method, one need not seek, at each step, the minimum of $F(X_{k\alpha}, Y_{k\beta})$ on $[0, \infty)$, but may set $X_{k+1} = X_{k\alpha_k}$, $Y_{k+1} = Y_{k\beta(\alpha_k)}$, where $\alpha_k \in [\varepsilon_0, \varepsilon_1]$, $\varepsilon_1 > \varepsilon_0 > 0$, are certain fixed quantities independent of k .

3°. Let $\Omega_X \subset E_n$, $\Omega_Y \subset E_m$ be strictly convex, bounded and closed sets. Then consider the functions

$$\psi(X, Y) = \max_{z \in \Omega_X} (\partial f(X, Y) / \partial X)^*(z - X), \quad (12)$$

$$\varphi(X, Y) = \min_{z \in \Omega_Y} (\partial f(X, Y) / \partial Y)^*(z - Y). \quad (13)$$

For all $(X, Y) \in \Omega_X \times \Omega_Y$, $\psi(X, Y) \geq 0$; $\varphi(X, Y) \leq 0$. Since Ω_X, Ω_Y are strictly convex sets, for fixed (X, Y) there exists a unique point $\theta_1(X, Y) \in \Omega_X$ and a unique point $\theta_2(X, Y) \in \Omega_Y$ such that

$$\psi(X, Y) = (\partial f(X, Y) / \partial X)^*(\theta_1(X, Y) - X),$$

$$\varphi(X, Y) = (\partial f(X, Y) / \partial Y)^*(\theta_2(X, Y) - Y).$$

The vector functions $\theta_1(X, Y)$ and $\theta_2(X, Y)$ are continuous on $\Omega_X \times \Omega_Y$. Consider the systems of differential equations

$$dX(t)/dt \equiv \dot{X}(t) = \theta_1(X(t), Y(t)) - X(t); \quad (14)$$

$$X(0) = X_0; \quad (15)$$

$$dY(t)/dt \equiv \dot{Y}(t) = \theta_2(X(t), Y(t)) - Y(t); \quad (16)$$

$$Y(0) = Y_0. \quad (17)$$

If $X_0 \in \Omega_X$, $Y_0 \in \Omega_Y$, then the solutions $X(t) \equiv X(t, X_0, Y_0)$, $Y(t) \equiv Y(t, X_0, Y_0)$ of the systems (14), (16) (the solutions exist and are continuous by Peano's theorem) belong, for $t \in [0, \infty)$, respectively to the sets Ω_X and Ω_Y .

Theorem 3. *If $f(X, Y)$ is a strictly concave-convex function, then the solutions of the systems (14), (16) for $(X_0, Y_0) \in \Omega_X \times \Omega_Y$ converge to the unique saddle point.*

On the basis of the "continuous" method (14), (16) for finding a saddle point, one can develop discrete methods for searching for saddle points. We give one of them.

Take arbitrary $X_1 \in \Omega_X$, $Y_1 \in \Omega_Y$. Suppose X_k, Y_k have been found ($X_k \in \Omega_X$, $Y_k \in \Omega_Y$). Let $\theta_{1k} = \theta_1(X_k, Y_k)$, $\theta_{2k} = \theta_2(X_k, Y_k)$. If $H(X_k, Y_k) = 0$, then the point (X_k, Y_k) is a saddle point, and the process is finished. If, however, $H(X_k, Y_k) > 0$, then consider the segment in Ω_X $X_{k\alpha} = X_k + \alpha(\theta_{1k} - X_k)$, $\alpha \in [0, 1]$, $X_{k\alpha} \in \Omega_X$, and the segment in Ω_Y $Y_{k\beta} = Y_k + \beta(\theta_{2k} - Y_k)$, $\beta \in [0, 1]$, $Y_{k\beta} \in \Omega_Y$. We have

$$h_1(\alpha, \beta) \equiv H(X_{k\alpha}, Y_{k\beta}) = H(X_k, Y_k) + \alpha A_k +$$

$$+(\beta - \alpha)B_k - \beta C_k + O_k(\alpha, \beta),$$

where

$$A_k = (\theta_{1k} - X_k)^* \frac{\partial^2 f(X_k, Y_k)}{\partial X^2} (\theta_{1k} - X_k),$$

$$B_k = (\theta_{2k} - Y_k)^* \frac{\partial^2 f(X_k, Y_k)}{\partial Y \partial X} (\theta_{1k} - X_k),$$

$$C_k = (\theta_{2k} - Y_k)^* \frac{\partial^2 f(X_k, Y_k)}{\partial Y^2} (\theta_{2k} - Y_k),$$

$$O_k(\alpha, \beta) / \sqrt{\alpha^2 + \beta^2} \xrightarrow{\alpha \rightarrow +0, \beta \rightarrow +0} 0 \quad \text{uniformly in } k.$$

If $B_k < 0$, then we set $\beta = 2\alpha$. In this case we consider the function $h_2(\alpha) \equiv h_1(\alpha, 2\alpha)$, find $\alpha_k \in [0, 1/2]$ such that $h_2(\alpha_k) = \min_{\alpha \in [0, 1/2]} h_2(\alpha)$, and set

$$X_{k+1} = X_k + \alpha_k(\theta_{1k} - X_k), \quad Y_{k+1} = Y_k + 2\alpha_k(\theta_{2k} - Y_k).$$

If, on the other hand, $B_k \geq 0$, then we set $\beta = 1/2\alpha$ and consider the function $h_3(\alpha) \equiv h_1(\alpha, 1/2\alpha)$. We find $\alpha_k \in [0, 1]$ such that $h_3(\alpha_k) = \min_{\alpha \in [0, 1]} h_3(\alpha)$ and set

$$X_{k+1} = X_k + \alpha_k(\theta_{1k} - X_k), \quad Y_{k+1} = Y_k + 1/2\alpha_k(\theta_{2k} - Y_k).$$

It is clear that in both cases $X_{k+1} \in \Omega_X$, $Y_{k+1} \in \Omega_Y$, and if $H(X_k, Y_k) > 0$, then $H(X_{k+1}, Y_{k+1}) < H(X_k, Y_k)$.

Thus we construct the sequences $\{X_k\}$, $\{Y_k\}$. The sequence $\{H_k\}$, $H_k = H(X_k, Y_k)$, is monotonically decreasing and therefore converges. Let $H^* = \lim_{k \rightarrow \infty} H_k$. Then $H_k \geq H^*$.

Theorem 4. *The sequences $\{X_k\}$, $\{Y_k\}$ constructed above converge to a saddle point of the function $f(X, Y)$ on the set $\Omega_X \times \Omega_Y$.*

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Note: Figure translations are in progress. See original paper for figures.

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