

# THE OCCURRENCE OF DISCONTINUITIES IN THE CONTINUATION OF SOLUTIONS OF NONLINEAR MIXED PROBLEMS FOR THE STRING EQUATION

MATHEMATICS

1967

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**Abstract**

**Full Text**

UDC 517.946

*MATHEMATICS*

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## THE OCCURRENCE OF DISCONTINUITIES IN THE CONTINUATION OF SOLUTIONS OF NONLINEAR MIXED PROBLEMS FOR THE STRING EQUATION

*(Presented by Academician I. G. Petrovskii on 26 XII 1966)*

1°. In the present note the following nonlinear mixed problem is considered:

$$u_{xx} - u_{tt} = -\Phi(x, t, u); \quad (1)$$

$$u(x, 0) = \varphi(x), \quad u_t(x, 0) = \psi(x) \quad \text{for } 0 \leq x \leq 1; \quad (2)$$

$$a_0(u)u_x + b_0(u)u_t = f_0(t, u) \quad \text{for } x = 0; \quad (3)$$

$$a_1(u)u_x + b_1(u)u_t = f_1(t, u) \quad \text{for } x = 1. \quad (4)$$

In <sup>(1,2)</sup> it was shown that if the function  $u \in C_2^0(\bar{\Pi}_{T_0})$  is a solution of problem (1)–(4) in the rectangle

$$\Pi_{T_0} = \{0 \leq x \leq 1, 0 \leq t \leq T_0\} \quad (0 < T_0 < +\infty)$$

and

$$h_i(u(i, T_0)) \equiv b_i(u(i, T_0)) - (-1)^i a_i(u(i, T_0)) \neq 0 \quad (i = 0, 1), \quad (5)$$

then the solution  $u$  can be continued uniquely in the rectangle  $\Pi_{T_0+\Delta T}$  ( $\Delta T > 0$ ) with preservation of smoothness. Inequality (5) is an unnatural restriction in a number of physical problems (see, for example, <sup>(3)</sup>). Below the solvability of problem (1)–(4) is investigated in the case when, upon continuation in  $t$  of a smooth solution, inequality (5) for  $i = 0$  becomes an equality at some moment  $t = T^* \neq +\infty$ . It turns out that for  $t > T^*$  the solution of problem (1)–

(4) becomes nonunique, and discontinuities and loss of smoothness of solutions arise; moreover, increasing the smoothness and compatibility of the data of the problem (the functions  $\Phi, \varphi, \psi, a_i, b_i, f_i$ ) does not lead to unique continuability of the solution and to preservation of smoothness for  $t > T^*$ . In this connection, in the present work discontinuous and piecewise-smooth solutions of problem (1)–(4) are constructed for  $t > T^*$ . For the examples given in §4 it is shown that the discontinuous and piecewise-smooth solutions introduced below arise naturally if one studies the behavior of solutions of mixed problems obtained under small perturbations of the operator  $a_0(u)u_x + b_0(u)u_t$  and of the initial conditions, as the perturbations tend to zero.

Choose an arbitrary  $0 < T < 1$ . Put

$$R^1 = (-\infty, +\infty), \quad D_T^0 = \bar{\Pi}_T \times R^1, \quad D_T^1 = [0, T] \times R^1.$$

Let:

- 1) the functions  $\Phi \in C_1(D_1^0)$ ,  $f_i \in C_1(D_1^1)$ ,  $a_i, b_i \in C_1(R^1)$ ,  $\varphi \in C_2[0, 1]$ ,  $\psi \in C_1[0, 1]$ ;
- 2) the function  $h_0$  have only isolated and simple zeros on the interval  $R^1$ , while the function  $h_1$  have no zeros on the interval  $R^1$ .

Suppose that in the rectangle

$$\Pi_{T^*} = \{0 \leq x \leq 1, 0 \leq t < T^*\},$$

where  $0 < T^* < 1$ ,\* there exists a solution  $u \in C_2^0(\Pi_{T^*})$  of problem (1)–(4), and moreover

$$\sup_{\Pi_{T^*}} |u| < +\infty, \quad h_0(u(0, t)) \neq 0 \quad \text{for } 0 \leq t < T^*, \quad h_0(u(0, t)) \rightarrow 0$$

as  $t \rightarrow T^*$ .

\* Obviously, the inequality  $0 < T^* < 1$  does not restrict the generality.

**Lemma 1.** There exists  $\lim_{t \rightarrow T^*} u(0, t) = u^*$ , and  $h_0(u^*) = 0$ .

**2°.** In the domain  $D_{T^*}^1$  define the function

$$P(t, u) = f_0(t, u) - a_0(u)[\varphi'(t) + \psi(t)] - a_0(u) \int_0^t \Phi(t - \tau, \tau, u(t - \tau, \tau)) d\tau.$$

It can be shown that  $P \in C_1(D_{T^*}^1)$ . Put

$$P_0 = P(T^*, u^*), \quad P_{1,0} = P_t'(T^*, u^*), \quad P_{0,1} = P_u'(T^*, u^*),$$

$$Q_\delta^0 = \{0 \leq x \leq 1, 0 \leq t \leq \min(x + T^* - \delta, T^*)\}, \quad 0 < \delta \leq T^*.$$

Note that  $|P_0| < +\infty$ .

**Theorem 1.** Whatever  $P_0$  may be,  $\overset{0}{u} \in C(\overline{\Pi}_{T^*})$ .\*

**Theorem 2.** Let  $P_0 \neq 0$ . Then  $\overset{0}{u} \in C_2(\overline{Q}_\delta)$  for  $\delta > 0$ ,

$$\sup_{\overline{Q}_\delta} |D^1 u| \rightarrow \infty$$

as  $\delta \rightarrow 0$ , and

$$\sup_{\Pi_{T^*}} |D^1 u(x, t)| \sqrt{|t - (x + T^*)|} < +\infty.$$

One can construct examples of nonlinear mixed problems with arbitrarily smooth and well-compatible data for which Theorem 2 holds.

**Theorem 3.** Let  $P_0 = 0$ ,  $P_{1,0} \neq 0$ . Then  $\overset{0}{u} \in C_2(\overline{Q}_\delta)$  for  $\delta > 0$  and  $\overset{0}{u} \in C_1(\overline{\Pi}_{T^*})$ .

Choose an arbitrary  $T^* < T < 1$ . Put

$$\begin{aligned} \Omega_T &= \{(x, t) \in \Pi_T, t \neq x + T^*\}, \\ G_T^0 &= \{0 \leq x < T - T^*, x + T^* < t \leq T\}, \\ G_T^1 &= \Omega_T \setminus G_T^0. \end{aligned}$$

Let  $\mathfrak{M}_T$  be the set of functions  $u \in C(\overline{\Pi}_T)$  such that:

- 1)  $u \in C_1(\overline{G}_T^j)$  ( $j = 0, 1$ ),  $u_x + u_t \in C(\overline{\Pi}_T)$ , and, whatever closed domain  $\overline{D} \subseteq \Omega_T$  may be, the function  $u \in C_2(\overline{D})$ ;
- 2)  $u \equiv \overset{0}{u}$  in the rectangle  $\overline{\Pi}_{T^*}$ .

A function  $u \in \mathfrak{M}_T$  will be called a solution of problem (1)–(4) in the rectangle  $\overline{\Pi}_T$  if it satisfies equation (1) in the domain  $\Omega_T$  and equations (3), (4) for  $0 \leq t \leq T$ .\*\*

**Theorem 4.** Let  $P_0 = 0$ ,  $P_{1,0} \neq 0$ , and  $P_{1,0}h'_0(u^*) > 0$ . Then there exists a  $T^* < T < 1$  such that in the set  $\mathfrak{M}_T$  there exist two and only two solutions  $u_i$  ( $i = 1, 2$ ) of problem (1)–(4) in the rectangle  $\overline{\Pi}_T$ , moreover

$$u_1 \in C_1(\overline{\Pi}_T), \quad u_2 \in C_1(\Pi_T).$$

**Theorem 5.** Let  $P_0 = 0$ ,  $P_{1,0} \neq 0$ ,  $P_{1,0}h'_0(u^*) < 0$ \*\*\* and

$$P_{0,1}^2 + 4P_{1,0}h'_0(u^*) \neq 0.$$

Then there exists a  $T^* < T < 1$  such that in the set  $\mathfrak{M}_T$  there exists an infinite set of solutions of problem (1)–(4).

One can construct examples of nonlinear mixed problems with arbitrarily smooth and well-compatible data for which Theorems 4 and 5 hold.

**3°.** Below, discontinuous solutions of problem (1)–(4) are constructed for  $t > T^*$  for any  $P_0$ . The introduction of discontinuous solutions in the case  $P_0 \neq 0$  is caused by the absence of continuous solutions in the rectangle  $\bar{\Pi}_T$  for any  $T > T^*$ . Indeed, independently of the value of  $P_0$ , for any  $T$  ( $0 < T \leq 1$ ) one can define the notion of a continuous generalized solution (c.g.s.) of problem (1)–(4) in the rectangle  $\bar{\Pi}_T$ . The function  $\overset{0}{u}$  is the unique c.g.s. in the rectangle  $\bar{\Pi}_T$  for any  $0 < T \leq T^*$ , and in the case  $P_0 = 0$ , for the corresponding  $T$ , all solutions are such,

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\* That is, the function  $u$  admits a continuous prolongation as  $t \rightarrow T^*$ .

\*\* The derivatives  $D^1 u$  at the point  $(0, T^*)$  should be understood as the corresponding one-sided derivatives.

\*\*\* It can be shown that if  $P_0 = 0$ ,  $P_{1,0} \neq 0$ , and  $P_{1,0} h'_0(u^*) < 0$ , then  $P_{0,1} \neq 0$ .

specified in Theorems 4 and 5. It can be shown that in the case  $P_0 \neq 0$  problem (1)–(4) does not have a n.g.s. in the rectangle  $\bar{\Pi}_T$  for any  $T > T^*$ , and increasing the smoothness and compatibility of the data of the problem does not lead to the existence of a n.g.s. The advisability of introducing discontinuous solutions in the case  $P_0 = 0$  is indicated by Example 2 given in §4.

Put

$$H_0(u) = \int_{\varphi(0)}^u h_0(\xi) d\xi, \quad J(t; u) = \int_0^t P(\tau, u(0, \tau)) d\tau.$$

**Lemma 2.** Whatever  $P_0$  may be,

$$H_0(u(0, t)) = J(t; u) \quad \text{for } 0 \leq t \leq T^*.$$

Suppose there exists at least one value  $\bar{u}^*$  different from  $u^*$  such that

$$H_0(\bar{u}^*) = J(T^*; u), \quad H'_0(\bar{u}^*) = h_0(\bar{u}^*) > 0.$$

Fix an arbitrary such value  $\bar{u}^*$ . Choose any  $T^* < T < 1$ .

Denote by  $\mathfrak{R}_T(\bar{u}^*)$  the set of functions such that: 1)  $u \in C_2(\overline{G_T^0})$ ,  $u \in C(\overline{G_T^1})$ ,  $u(0, T^* + 0) = \bar{u}^*$ ; 2)  $u \equiv \overset{0}{u}$  in the rectangle  $\bar{\Pi}_{T^*}$ .

We note that a function  $u \in \mathfrak{R}_T(\bar{u}^*)$  has a discontinuity of the first kind on the line  $t = x + T^*$  in a neighborhood of the point  $(0, T^*)$ .

**Theorem 6.** Let  $P_0 = 0$ . Then there exists  $T^* < T < 1$  such that in the set  $\mathfrak{R}_T(\bar{u}^*)$  there exists a unique function  $u \in C_1(\overline{G_T^1})$  which satisfies equation (1) in the domain  $\Omega_T$  and equations (3), (4) for  $0 \leq t \leq T$ .

**Theorem 7.** Let  $P_0 \neq 0$ . Then there exists  $T^* < T < 1$  such that in the set  $\mathfrak{R}_T(\bar{u}^*)$  there exists a unique function  $u$  having the following properties:

- 1)  $|D^1 u(x, t)| \rightarrow \infty$  as  $t - (x + T^*) \rightarrow -0$ ,

$$\sup_{G_T^1} |D^1 u(x, t)| \sqrt{|t - (x + T^*)|} < +\infty.$$

- 2) the function  $u$  satisfies equation (1) in the domain  $\Omega_T$  and equations (3), (4) for  $t \in [0, T^*)$ ,  $t \in [T^*, T]$ , and  $t \in [0, T]$ , respectively.

§4. In the examples given below the following nonlinear mixed problem is considered

$$u_{xx} = u_{tt}; \tag{6}$$

$$u(x, 0) = 0, \quad u_t(x, 0) = \psi(x) \quad \text{for } 0 \leq x \leq 1; \tag{7}$$

$$-u_x + \frac{\partial f(u)}{\partial u} u_t = 0 \quad \text{for } x = 0; \tag{8}$$

$$u_x = 0 \quad \text{for } x = 1, \tag{9}$$

where  $f(u) = \frac{5}{3}u^3 - \frac{5}{2}u^2 + \frac{11}{6}$ , and  $\psi(x)$  is a function of class  $C_1[0, 1]$ , chosen in each example in a special way and satisfying the compatibility conditions  $\psi^{(s)}(j) = 0$  ( $s, j = 0, 1$ ). Note that  $h_1(u) \equiv 1$ , while the equation  $h_0(u) = 0$  has two real roots

$$u_j^* = \frac{1}{2} + (-1)^j \frac{\sqrt{5}}{10} \quad (j = 1, 2).$$

**Example 1.** Choose an arbitrary function  $\psi$  such that: a)  $\psi(x) > 0$  for  $0 < x \leq \frac{3}{4}$ ; b) the function

$$\sigma(x) = f(0) + \int_0^x \psi(\xi) d\xi$$

is such that

$$\sigma(x) < u_1^* + f(u_1^*) \quad \text{for } 0 < x < \frac{1}{2}$$

and

$$\sigma\left(\frac{1}{2}\right) = u_1^* + f(u_1^*).$$

**Theorem 8.** Problem (6)–(9) has in the rectangle  $\Pi_{1/2}$  a unique solution  $u \in C_2(\Pi_{1/2})$ , moreover

$$h_0(u(0, t)) > 0 \quad \text{for } 0 \leq t < \frac{1}{2},$$

$$u(0, t) \rightarrow u_1^* \quad \text{as } t \rightarrow \frac{1}{2}, \quad P_0 \neq 0.$$

In the example under consideration  $T^* = \frac{1}{2}$ . It can be shown that the equation

$$H_0(u) = J(T^*; u)$$

has a unique root  $\bar{u}^*$ , different from the root  $u_1^*$ . Consequently, by Theorem 7, there exists  $T^* < T < 1$  such that the problem

(6)–(9) has in the rectangle  $\Pi_T$  a unique discontinuous solution  $u_p \in \mathfrak{R}_T(\bar{u}^*)$ . Let us now consider equation (6) with the initial conditions (7), the boundary condition (9), and the following boundary condition:

$$\mu u_{tt} - u_x + \frac{\partial f(u)}{\partial u} u_t = 0 \quad (\mu > 0) \quad \text{for } x = 0. \quad (10)$$

**Theorem 9.** There exists a  $\mu_0 > 0$  such that, for any  $0 < \mu < \mu_0$ , problem (6), (7), (9), (10) has in the rectangle  $\bar{\Pi}_T$  a unique solution  $u_\mu \in C_2(\bar{\Pi}_T)$ , and  $u_\mu \rightarrow u_p$  as  $\mu \rightarrow 0$  uniformly with respect to  $x, t$  in each closed domain  $\bar{D} \subset \Omega_T$ .

**Example 2.** Choose an arbitrary function  $\psi$  satisfying condition b) and such that  $\psi(x) > 0$  for  $0 \leq x < 1/2$ ,  $\psi(1/2) = 0$ ,  $\psi'(1/2) < 0$ .

**Theorem 10.** In the rectangle  $\Pi_{1/2}$  there exists a unique solution  $u \in C_2(\Pi_{1/2})$  of problem (6)–(9), and  $h_0(u(0, t)) > 0$  for  $0 \leq t < 1/2$ ,  $u(0, t) \rightarrow u_1^*$  as  $t \rightarrow 1/2$ ;  $P_0 = 0$ ,  $P_{1,0} \neq 0$ ,  $P_{1,0} h'_0(u_1^*) > 0$ .

As in Example 1,  $T^* = 1/2$ .

**Theorem 11.** Let  $T$  be the number indicated in Theorem 4. For any  $\varepsilon > 0$ , one can specify a  $\mu_0(\varepsilon) > 0$  such that, for any  $0 < \mu < \mu_0(\varepsilon)$ , problem (6), (7), (9), (10) has in the rectangle  $\bar{\Pi}_T$  a unique solution  $u_\mu \in C_2(\bar{\Pi}_T)$ , and

$$\max_{\bar{\Pi}_T} |u_\mu - u_2| < \varepsilon,$$

where  $u_2$  is the solution of problem (6)–(9) appearing in Theorem 4.

As in Example 1, the existence is established of such a  $T^* < \bar{T} < 1$  that in the rectangle  $\bar{\Pi}_{\bar{T}}$  problem (6)–(9) has a unique discontinuous solution  $u_p \in \mathfrak{R}_{\bar{T}}(\bar{u}^*)$ , where  $\bar{u}^*$  is the unique root, distinct from  $u_1^*$ , of the equation  $H_0(u) = J(T^*; u)$ .

**Theorem 12.** Whatever closed domain  $\bar{D} \subset G_{\bar{T}}^1$  is given, for any  $\varepsilon > 0$  one can specify a  $\delta_0(\varepsilon) > 0$  such that, for any  $0 < \delta < \delta_0(\varepsilon)$ , there exist  $0 < T^*(\delta) < T^*$  and a function  $\psi_\delta(x) \in C_1[0, 1]$  satisfying the relations

$$\bar{D} \subset \Gamma_\delta = \{0 \leq x \leq 1, 0 \leq t \leq \min(x + T^*(\delta), \bar{T})\},$$

$$\sum_{s=0,1} \max_{0 \leq x \leq 1} |\psi_\delta^{(s)}(x) - \psi^{(s)}(x)| < \delta$$

and such that problem (6)–(9), with initial conditions  $u(x, 0) = 0$ ,  $u_t(x, 0) = \psi_\delta(x)$ :

- 1) has in the rectangle  $\bar{\Pi}_{T^*(\delta)}$  a unique solution  $u^\delta \in C_2(\bar{\Pi}_{T^*(\delta)})$ , with  $h_0(u^\delta(0, t)) > 0$  for  $0 \leq t < T^*(\delta)$ ,  $u^\delta(0, t) \rightarrow u_1^*$  as  $t \rightarrow T^*(\delta)$ ;  $P_0 \neq 0$ ;
- 2) has in the rectangle  $\bar{\Pi}_{\bar{T}}$  a unique discontinuous solution  $u_p^\delta \in \mathfrak{R}_{\bar{T}}(\bar{u}_\delta^*)^*$ , where  $\bar{u}_\delta^*$  is the unique root, distinct from  $u_1^*$ , of the equation  $H_0(u) = J(T^*(\delta); u^\delta)$ , and

$$\max_{\Gamma_\delta} |u_R - u_p^\delta| < \varepsilon, \quad \max_{\substack{0 \leq x \leq \bar{T} - T^* \\ x + T^* \leq t \leq \bar{T}}} |u_p - u_p^\delta| < \varepsilon.$$

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at Gorky State University  
named after N. I. Lobachevsky

Received  
22 XII 1966

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\* Here, in the definition of the domains  $\Omega_T$ ,  $G_T^i$  ( $i = 0, 1$ ) and the set  $\mathfrak{R}_{\bar{T}}(\bar{u}_\delta^*)$ , one should put  $T^* = T^*(\delta)$ ,  $\bar{u}^* = \bar{u}_\delta^*$ ,  $u = u^\delta$ .

*Note: Figure translations are in progress. See original paper for figures.*

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