

# ONE-SIDED ESTIMATES UNDER CONDITIONS OF ASYMPTOTIC STABILITY OF SOLUTIONS OF DIFFERENTIAL EQUATIONS WITH UNBOUNDED OPERATORS

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**Abstract**

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*MATHEMATICS*

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## ONE-SIDED ESTIMATES UNDER CONDITIONS OF ASYMPTOTIC STABILITY OF SOLUTIONS OF DIFFERENTIAL EQUATIONS WITH UNBOUNDED OPERATORS

*(Presented by Academician I. N. Vekua, May 24, 1965)*

We consider the question of asymptotic stability in the sense of Lyapunov of the zero solution of the differential equation

$$dx/dt = A(t)x + f(t, x) \quad (1)$$

in a Banach space  $E$ .

**1. Auxiliary theorem.** By  $(l, x)$  we shall denote the values of the linear functional  $l \in E^*$  ( $E^*$  is the space conjugate to  $E$ ) on the element  $x$ . We shall assume that the norm in  $E$  is Gateaux differentiable:

$$\lim_{\lambda \rightarrow 0} \frac{\|x + \lambda h\| - \|x\|}{\lambda} = (\Gamma x, h),$$

where  $\Gamma x = \text{grad } \|x\|$ .

It is easy to verify that the operator  $\Gamma$  maps  $E$  into  $E^*$ , and moreover (see, for example, <sup>(1)</sup>)

$$(\Gamma x, x) = \|x\|, \quad \Gamma(\alpha x) = \Gamma x \quad (\alpha > 0). \quad (2)$$

If we put  $E = L_p(G)$ , then

$$\Gamma x = x|x|^{p-2}/\|x\|^{p-1}.$$

Consider a function  $\gamma(t)$  which, for all  $t \geq 0$  and  $x \in D$ , gives the estimate

$$(\Gamma x, A(t)x) \leq \gamma(t)\|x\|, \quad (3)$$

where  $D$  is an everywhere dense domain of definition of the operator  $A(t)$ .

Introduce the notation

$$\Omega_\gamma = \lim_{t \rightarrow \infty} \frac{1}{t} \int_0^t \gamma(s) ds, \quad \Omega = \inf \Omega_\gamma,$$

where the lower bound is taken over all functions  $\gamma(t)$  of the indicated class. The number  $\Omega$  will be called the **central characteristic exponent** (cf. (2)).

We shall assume that the operator  $f(t, x)$  satisfies the condition

$$(\Gamma x, f(t, x)) \leq \delta \|x\|. \quad (4)$$

**Theorem 1.** *For any  $\varepsilon > 0$  there exists a sufficiently small  $\delta > 0$  such that every solution  $x(t)$  of equation (1) with an operator satisfying condition (4) admits the estimate*

$$\|x(t)\| \leq \|x(0)\| C_\varepsilon \exp[(\Omega + 2\varepsilon)t],$$

where  $C_\varepsilon$  depends only on  $\varepsilon$ .

**Proof.** Let  $v(t) = \|x(t)\|$ . Then

$$dv(t)/dt = (\Gamma x, dx/dt) = (\Gamma x, A(t)x) + (\Gamma x, f(t, x)) \leq \gamma(t)\|x\| + \delta\|x\|,$$

i.e.,

$$dv(t)/dt \leq [\gamma(t) + \delta]v(t).$$

Applying the theorem on differential inequalities, from this we obtain

$$\|x(t)\| \leq \|x(0)\| \exp \left[ \int_0^t (\gamma(s) + \delta) ds \right]. \quad (5)$$

From the definition of  $\Omega$  we have: for a given  $\varepsilon > 0$  there exists a function  $\gamma(t)$  such that (3) is satisfied and at the same time

$$\Omega_\gamma < \Omega + \varepsilon,$$

i.e.,

$$\int_0^t \gamma(s) ds \leq C'_\varepsilon + (\Omega + \varepsilon)t.$$

Then, choosing  $\delta \leq \varepsilon$  and taking this last inequality into account, from (5) we obtain

$$\|x(t)\| \leq \|x(0)\| C_\varepsilon \exp[(\Omega + 2\varepsilon)t].$$

The theorem is proved.

**2. Main theorem.** Using Theorem 1, we shall prove the following theorem, which gives conditions for the asymptotic stability of the zero solution of equation (1).

**Theorem 2.** *Let the operator  $f(t, x)$ , for small  $\|x\|$  and  $t \in [0, \infty)$ , satisfy the condition*

$$(\Gamma x, f(t, x)) \leq \mathcal{L}\|x\|^{1+\alpha} \quad (\alpha > 0). \quad (6)$$

Let  $\Omega < 0$ .

*Then the trivial solution of equation (1) is asymptotically stable.*

**Proof.** Choose  $\lambda > 0$  so that  $\Omega_1 = \Omega + \lambda < 0$ , and make the substitution

$$x(t) = \exp(-\lambda t)y(t).$$

Then

$$dy/dt = [A(t) + \lambda I]y + g(t, y), \quad (7)$$

where  $g(t, y) = \exp(\lambda t)f[t, \exp(-\lambda t)y]$ .

Taking into account (2) and condition (6), we have

$$\begin{aligned} (\Gamma y, g(t, y)) &= e^{\lambda t}(\Gamma y, f[t, e^{-\lambda t}y]) = \\ &= e^{\lambda t}(\Gamma[e^{-\lambda t}y], f[t, e^{-\lambda t}y]) \leq e^{\lambda t}\mathcal{L}\|e^{-\lambda t}y\|^{1+\alpha}, \\ (\Gamma y, g(t, y)) &\leq \mathcal{L}e^{-\lambda\alpha t}\|y\|^{1+\alpha}. \end{aligned} \quad (8)$$

From (2) and (3) it follows that

$$\begin{aligned} (\Gamma y, [A(t) + \lambda I]y) &= (\Gamma y, A(t)y) + \lambda(\Gamma y, y) = \\ &= (\Gamma y, A(t)y) + \lambda\|y\| \geq [\gamma(t) + \lambda]\|y\|, \end{aligned}$$

$$(\Gamma y, [A(t) + \lambda I]y) \geq [\gamma(t) + \lambda]\|y\|.$$

Consequently, the central exponent of the operator  $A(t) + \lambda I$  is equal to  $\Omega_1 = \Omega + \lambda$ , and therefore, choosing  $\varepsilon > 0$  so that  $\Omega_1 + 2\varepsilon < 0$ , one can choose a function  $\gamma(t)$  (according to the definition of  $\Omega$ ) satisfying inequality (3) and  $\Omega < \Omega_1 + \varepsilon < 0$ .

Let  $\delta > 0$  be such that  $\delta < \varepsilon$ . Choose the initial time  $t_0 > 0$  so large that, for  $t \geq t_0$  and small  $\|y\|$ , (8) gives

$$(\Gamma y, g(t, y)) \leq \delta\|y\|.$$

Thus the operator  $g(t, y)$  satisfies the conditions of Theorem 1; consequently,

$$\|y(t)\| \leq \|y(t_0)\|C_\varepsilon \exp[(\Omega_1 + 2\varepsilon)t].$$

Since  $\Omega_1 + 2\varepsilon < 0$ , the zero solution of equation (7) is asymptotically stable, and hence, a fortiori, the solution of equation (1) is asymptotically stable. The theorem is proved.

### 3. Examples

- 1) In the case when  $E = E^n$ , where  $A(t)$  is an  $n$ -dimensional Euclidean space, an analogous question was considered in paper <sup>(2)</sup>. However, even in this case the assertion of Theorem 2 is new, since, in contrast to <sup>(2)</sup>, here the nonlinear term is subject to a one-sided estimate.
- 2) As is known (see <sup>(3, 4)</sup>), if the operator  $A(t)$  satisfies condition (3) (and if  $\gamma(t) = \gamma^0 < 0$ ), then it is the infinitesimal generator of a strongly continuous semigroup, i.e. it is an "abstract elliptic operator." This fact means that, as a second example of equation (1), one may take a parabolic equation (of second and higher orders).

In conclusion, we note that a countable number of differential equations, integro-differential equations, etc., may also serve as examples of equation (1).

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*Note: Figure translations are in progress. See original paper for figures.*

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