



---

Soviet-era science, translated into English

# V. I. Derguzov

Let us consider the Hamiltonian equation

1963

SovietRxiv

---

View the original and related papers at <https://sovietrxiv.org/items/ru-196301.93028>

Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.

**Abstract**

**Full Text**

**V. I. Derguzov**

**On the Stability of Solutions of Hamiltonian Equations in Hilbert Space with Unbounded Periodic Operator Coefficients**

*(Presented by Academician V. I. Smirnov on 10 V 1963)*

Let us consider the Hamiltonian equation

$$J \frac{dx}{dt} = H(t)x \tag{1}$$

in the complete separable complex Hilbert space  $\mathfrak{H}$ . Here  $J$  is a bounded operator with bounded inverse, anti-Hermitian ( $J^* = -J$ );  $H(t)$  is an unbounded symmetric  $T$ -periodic operator, subject to certain general conditions formulated below. Equation (1) often occurs in applications <sup>(1)</sup>. In the case of a finite-dimensional space  $\mathfrak{H}$ , M. G. Krein found sufficient conditions for strong stability of the solutions of equation (1) in terms of the type of points of the spectrum of the monodromy operator <sup>(2)</sup>. I. M. Gelfand and V. B. Lidskii <sup>(3)</sup> showed that these conditions are also necessary (for another proof see <sup>(4)</sup>). In the present paper these results, with natural modifications, are carried over to equation (1).

1°. We shall assume that  $H(t)$  is equal to the sum of two operators

$$H(t) = H_0(t) + H_1(t), \tag{2}$$

where  $H_0(t)$  is a self-adjoint positive-definite operator,  $H_0^*(t) = H_0(t) \geq \beta I$  ( $\beta = \text{const} > 0$ ), and the following condition is satisfied:

A. The domain of definition  $D(H_0^{1/2})$  of the positive square root  $H_0^{1/2}(t)$  of the operator  $H_0(t)$  is constant, and for  $t, t' \in [0, T]$ , for any elements  $x, y \in D(H_0^{1/2})$ , the estimate

$$\left| (H_0^{1/2}(t)x, H_0^{1/2}(t)y) - (H_0^{1/2}(t')x, H_0^{1/2}(t')y) \right| \leq$$

$$\leq \text{const} \cdot |t - t'| \|H_0^{1/2}(t)x\| \cdot \|H_0^{1/2}(t)y\|$$

holds.

The operator  $H_1(t)$  is, in the following sense, subordinated to the operators  $J$  and  $H_0(t)$ :

B. For almost all  $t \in [0, T]$ , the symmetric operator  $H_1(t)$  is defined on the set  $D(H_0^{1/2})$ ; the operator

$$A(t) = H_0^{1/2}(0)J^{-1}H_1(t)H_0^{-1/2}(0), \quad (3)$$

is meaningful, is bounded for almost all  $t \in [0, T]$ , is strongly measurable on  $[0, T]$ , and  $\|A(t)\| \in \mathcal{L}(0, T)$ .

**Definition 1.** We shall call a function  $x(t)$  a **generalized solution** of equation (1) if it has the following properties:

- 1)  $x(t) \in D(H_0^{1/2})$  for all  $t$ , and the function  $H_0^{1/2}(0)x(t)$  is weakly continuous;
- 2) for almost all  $t$ , the function  $H_0^{-1/2}(0)Jx(t)$  is strongly differentiable, and  $x(t)$  satisfies, for these  $t$ , the equation

$$\frac{d}{dt} [H_0^{-1/2}(0)Jx(t)] = [H_0^{1/2}(t)H_0^{-1/2}(0)]^* H_0^{1/2}(t)x(t) + H_0^{-1/2}(0)H_1(t)x(t)$$

and, by weak continuity, the initial condition.

**Theorem 1.** *If conditions A and B are satisfied for the operator (2), then equation (1) with the initial condition  $x(0) \in D(H_0^{1/2})$  has a unique generalized solution  $x(t)$ . The resolving operator  $X(t)$ , defined by the formula  $X(t)x(0) = x(t)$ , is representable in the form  $X(t) = H_0^{-1/2}(0)z(t)H_0^{1/2}(0)$ .*

The operator  $Z(t)$  is bounded together with its inverse uniformly in  $t \in [0, T]$  and satisfies the relation  $Z^*(t)FZ(t) = F$ , where

$$F = iH_0^{-1/2}(0)JH_0^{-1/2}(0). \quad (4)$$

By means of the resolution of the identity  $E_\lambda$  of the self-adjoint operator  $F$ , define the bounded operator

$$|F|^{1/2} = \int_{-\infty}^{+\infty} |\lambda|^{1/2} dE_\lambda, \quad (5)$$

whose inverse is unbounded.

Let the operator  $H_0(t)$  in formula (2) be fixed, and let  $M$  be the set of all operators  $H_1(t)$  satisfying condition B. Introduce in  $M$  the distance between the operators  $H_1 = H_1(t)$  and  $\tilde{H}_1 = \tilde{H}_1(t)$  by the formula

$$\rho(H_1, \tilde{H}_1) = \int_0^T \left\| |F|^{1/2}(A(t) - \tilde{A}(t))|F|^{-1/2} \right\| dt, \quad (6)$$

where the operator  $A(t)$  is defined by formula (3), and

$$\tilde{A}(t) = H_0^{1/2}(0)J^{-1}\tilde{H}_1(t)H_0^{-1/2}(0).$$

We note that for any pair of operators  $H_1(t)$  and  $\tilde{H}_1(t)$  in  $M$ ,  $\rho(H_1, \tilde{H}_1) < \infty$ . The latter assertion follows from the estimate

$$\left\| |F|^{1/2}(A(t) - \tilde{A}(t))|F|^{-1/2} \right\| \leq \|A(t) - \tilde{A}(t)\|,$$

valid for almost all  $t$ .

**Definition 2.** Equation (1) is called **stable** if, for every generalized solution  $x(t)$  of it, the estimate

$$\left\| |F|^{1/2}H_0^{1/2}(0)x(t) \right\| \leq \text{const} \cdot \left\| |F|^{1/2}H_0^{1/2}(0)x(0) \right\| \quad (7)$$

holds.

If, in addition, all equations (1) are stable under small changes of the operator  $H_1(t)$  in the metric (6), then equation (1) is called **strongly stable**.

The main result is formulated in the following theorem.

**Theorem 2.** Suppose that on the period  $[0, T]$  the coefficients of equation (1) satisfy the conditions of Theorem 1;  $X(t)$  and  $F$  are the operators defined in Theorem 1. In order that equation (1) be strongly stable, it is sufficient that the spectrum of the operator  $Y(T) = |F|^{1/2}Z(T)|F|^{-1/2}$  have no points of mixed kind.

The definition of the kind of points of the spectrum of the operator  $Y(T)$  is analogous to the finite-dimensional case and will be given below.

There exists an example showing that if, in inequality (7), the operator  $|F|^{1/2}$  is replaced by the identity operator  $I$ , then the assertion of Theorem 2 loses its force.

2°. **Definition 3.** If the operator  $Z$  is bounded together with its inverse and satisfies the relation  $Z^*FZ = F$ , then it is called  **$F$ -unitary**.

**Definition 4.** A bounded projector  $P$  satisfying the relation  $FP = P^*F$  is called a **projector of the first kind** (a **projector of the second kind**) with respect to the operator  $F$ , if  $(FPx, x) > 0$  ( $(FPx, x) < 0$ ) for every  $x = Px \neq 0$ .

**Definition 5.** Suppose the entire spectrum of the operator  $Z$  can be surrounded by a finite number of closed contours  $\Gamma_j$ , pairwise nonintersecting and not intersecting the spectrum of  $Z$ , each of which is located symmetrically with respect to the unit circle. Suppose that each of the projectors

$$P_j = \frac{1}{2\pi i} \int_{\Gamma_j} (\xi I - Z)^{-1} d\xi,$$

is a projector of the first or second kind with respect to  $F$ . Then one says that the  $F$ -unitary operator  $Z$  has no points of spectrum of mixed kind.

**Definition 6.** The operator  $Z$  is called **stable** if

$$\| |F|^{1/2} Z^n |F|^{-1/2} x \| \leq \text{const} \cdot \|x\| \quad (x \in D(|F|^{-1/2}))$$

for  $n = \pm 1, \pm 2, \dots$ . If, in addition, all  $F$ -unitary operators from some neighborhood of  $Z$  in the uniform operator topology are stable, then  $Z$  is called **strongly stable**.

One can give an example of an  $F$ -unitary operator  $Z$ , having no spectral points of mixed type, for which the set of norms of integral powers is unbounded. However, the following holds:

**Theorem 3.** *In order that an  $F$ -unitary operator  $Z$  be strongly stable, it is sufficient that it have no spectral points of mixed type.*

**Theorem 4.** *If  $Z$  is an  $F$ -unitary operator, then the operators*

$$Y = |F|^{1/2} Z |F|^{-1/2}, \quad Y^{-1} = |F|^{1/2} Z^{-1} |F|^{-1/2}, \quad (8)$$

*defined on the set  $D(|F|)^{-1/2}$ , are bounded. If  $\lambda$  and  $(\bar{\lambda})^{-1}$  are regular points of the operator  $Z$ , then they will also be regular points for the operator  $Y$ .*

It is now clear that Theorem 3 asserts the boundedness of the powers of the operators  $Y$  and  $Y^{-1}$ , obtained from the operator  $Z$  by formulas (8).

By means of the resolution of the identity  $E_\lambda$  of the operator  $F$ , introduce the bounded symmetric operator, together with its inverse,

$$G = \int_0^{+\infty} dE_\lambda - \int_{-\infty}^0 dE_\lambda. \quad (9)$$

From Theorem 4 there follows

**Corollary.** *If an  $F$ -unitary operator  $Z$  has no spectral points of mixed type, then the  $G$ -unitary operator  $Y$ , obtained by formulas (8) from the operator  $Z$ , has no spectral points of mixed type.*

Examples show the possibility of a case in which an  $F$ -unitary operator  $Z$  has spectral points of mixed type, while the  $G$ -unitary operator  $Y$ , defined from  $Z$  by formulas (8), has no spectral points of mixed type. In particular, this indicates that Theorem 3, applied to the  $G$ -unitary operator  $Y$ , has a wider range of application than the same theorem applied to the  $F$ -unitary operator  $Z$ . Since the operator  $G$  is bounded together with its inverse, Theorem 3, applied to the  $G$ -unitary operator  $Y$ , asserts the boundedness of the powers of the operator  $Y$ .

It can be shown that small changes of the operator  $H_1(t)$  in the metric (6) correspond to small changes, in the uniform operator topology, of the  $G$ -unitary operator  $Y(t)$  defined in Theorem 2. Using Theorem 4 and Theorem 3 applied to the  $G$ -unitary operator  $Y(t)$ , it is easy to prove Theorem 2.

Received  
2 V 1963

## REFERENCES

1. V. V. Bolotin, *Dynamic stability of elastic systems*, Moscow, 1956.
2. M. G. Krein, *In memory of A. A. Andronov*, Publishing House of the USSR Academy of Sciences, 1955, p. 413.
3. I. M. Gel' fand, V. B. Lidskii, UMN, 10, issue 1 (63), 3 (1955).
4. V. A. Yakubovich, Vestn. LGU, No. 13, issue 3 (1958).
5. V. I. Derguzov, V. A. Yakubovich, DAN, 151, No. 6 (1963).

*Note: Figure translations are in progress. See original paper for figures.*

*Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.*