



Soviet-era science, translated into English

MATHEMATICS

A. B. VASIL' EVA

1962

SovietRxiv

View the original and related papers at <https://sovietrxiv.org/items/ru-196201.91417>

Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.

Abstract

Full Text

MATHEMATICS

A. B. VASIL' EVA

AN EQUATION OF NEUTRAL TYPE WITH A SMALL DELAY

(Presented by Academician I. G. Petrovskii on III 8, 1962)

Consider the differential equation with deviating argument of neutral type ($\Delta t = \text{const} > 0$)

$$\dot{x}(t) = f(t, x(t), x(t - \Delta t), \dot{x}(t - \Delta t)) \quad (1)$$

with the initial condition

$$x = \varphi(t), \quad 0 \leq t \leq \Delta t. \quad (2)$$

We shall study the behavior, as $\Delta t \rightarrow 0$, of the solution of (1) satisfying condition (2). In the case where (1) does not contain $\dot{x}(t - \Delta t)$ on the right (then it becomes an equation with delayed argument), as $\Delta t \rightarrow 0$ the solution has a limit, and this limiting function satisfies the equation obtained if, in the original equation, one formally sets $\Delta t = 0$, together with the initial condition $x = \varphi(0)$ at $t = 0$ ⁽¹⁾. Moreover, under sufficient smoothness of the right-hand side of the equation and of the initial function $\varphi(t)$, for such a solution there is a valid asymptotic expansion in powers of Δt ⁽²⁾.

In the present note the main results of an investigation of the asymptotic properties of the solution of equation (1), determined by condition (2), as $\Delta t \rightarrow 0$, will be presented. This investigation shows that, under certain assumptions concerning the right-hand side of (1) (these assumptions include, besides the natural smoothness requirements, a special condition—the stability condition; see (3) below), for the solution $x(t, \Delta t)$ of equation (1) there is likewise a limiting transition as $\Delta t \rightarrow 0$, and the limiting function is constructed in the same way as in the above-mentioned case with delayed argument. In addition, asymptotic formulas will be written for x and \dot{x} , with a remainder term of order Δt^2 , uniform over the entire interval of variation of t under consideration. At the same time, in a neighborhood of the initial point $t = 0$, the presence of a boundary layer is detected. In general, in the asymptotic behavior of the solution of equation (1), in the structure of the asymptotic formulas, and in the nature of a number of estimates, there is a great similarity with phenomena occurring for

equations containing a small parameter multiplying the highest derivative (see, for example, ^(3,4)).

Let a continuous function $u = \Phi(t, x, y)$, which is a solution of the equation

$$u = f(t, x, y, u),$$

be defined in some rectangle $R : 0 \leq t \leq T, |x - \varphi(0)| \leq b, |y - \varphi(0)| \leq b$. Suppose that in the region $G : (t, x, y) \in R, |u - \Phi(t, x, y)| \leq b$, the function f is continuous together with the partial derivative with respect to u , and that the condition

$$\left| \frac{\partial f}{\partial u} \right| \leq a < 1, \tag{3}$$

is satisfied; we shall call this the stability condition. Assume that $\varphi(t)$ is continuously differentiable in a neighborhood of $t = 0$. Then the following holds:

Theorem 1. *If the above requirements are satisfied, then for sufficiently small $\Delta t \leq \Delta t_0$ there exists a unique solution $x(t, \Delta t)$ of equation (1), satisfying condition (2); it is continuous in t and uniformly bounded with respect to Δt on the interval of variation of $t : 0 \leq t \leq h$, where*

$$h = \min \left(T, \frac{b - \delta}{K} \right),$$

$\delta > 0$ is arbitrarily small, fixed as $\Delta t \rightarrow 0$, and

$$K = \max_G |f|.$$

Theorem 2. Under the same assumptions, there is a limiting transition

$$\lim_{\Delta t \rightarrow 0} x(t, \Delta t) = \bar{x}(t), \quad 0 \leq t \leq h, \tag{4}$$

where $\bar{x}(t)$ is a solution of the equation obtained from (1) by formally setting $\Delta t = 0$, satisfying the initial condition $\bar{x}(0) = \varphi(0)$.

In order to write asymptotic formulas for x and \bar{x} , we carry out some auxiliary constructions analogous to those done in ^(3,4). Write the original equation (1) in the form of a system ($\dot{x} = u, [x] = x(t - \Delta t), [u] = u(t - \Delta t)$)

$$u = f(t, x, [x], [u]),$$

$$\frac{dx}{dt} = u; \quad (5)$$

$$x = \varphi(t), \quad u = \dot{\varphi}(t), \quad 0 \leq t \leq \Delta t. \quad (6)$$

Introducing a new variable $\tau = t/\Delta t$, we rewrite (5) also in the form

$$u = f(\tau\Delta t, x, [x], [u]),$$

$$\frac{dx}{d\tau} = \Delta t u. \quad (7)$$

We shall seek a formal solution of system (7) in the form of an expansion in powers of Δt (by z we shall denote x and u together)

$$z = z_0 + \Delta t z_1 + \dots \quad (8)$$

Substituting this expansion into system (7), we obtain equations for determining z_0 and z_1 (to construct a formula with a remainder term of order Δt^2 , coefficients of subsequent orders are not needed)

$$u_0 = f(0, x_0, [x_0], [u_0]) \equiv f_0,$$

$$\frac{dx_0}{dt} = 0; \quad (9)$$

$$\Delta t u_1 = f_{t_0} t + f_{x_0}(\Delta t x_1) + f_{y_0}[\Delta t x_1] + f_{u_0}[\Delta t u_1],$$

$$\frac{d}{dt}(\Delta t x_1) = u_0. \quad (10)$$

We prescribe the initial conditions for determining u_0, x_0 in the form

$$u_0 = \dot{\varphi}(0), \quad 0 \leq t \leq \Delta t,$$

$$x_0|_{t=0} = \varphi(0). \quad (11)$$

Hence it follows that

$$x_0 \equiv \varphi(0),$$

$$u_0 = f(0, \varphi(0), \varphi(0), [u_0]), \quad (12)$$

$$u_0 = \dot{\varphi}(0), \quad 0 \leq t \leq \Delta t.$$

We prescribe the initial conditions for determining u_1, x_1 in the form

$$\Delta t u_1 = t \dot{\varphi}(0), \quad 0 \leq t \leq \Delta t,$$

$$\Delta t x_1|_{t=0} = 0. \quad (13)$$

Now construct a formal solution of system (5) also in the form of an expansion in powers of Δt

$$z = \bar{z}_0 + \Delta t \bar{z}_1 + \dots \quad (14)$$

In this case

$$\bar{u}_0 = f(t, \bar{x}_0, \bar{x}_0, \bar{u}_0) \equiv \bar{f}_0, \quad (15)$$

$$\dot{\bar{x}}_0 = \bar{u}_0.$$

To determine the solution of this equation, we impose the initial condition in the form

$$\bar{x}_0|_{t=0} = \varphi(0). \quad (16)$$

There is no need to prescribe an initial condition for \bar{u}_0 . The functions \bar{u}_1, \bar{x}_1 are determined by the equations

$$\begin{aligned} \bar{u}_1 &= \bar{f}_{x_0} \bar{x}_1 + \bar{f}_{y_0} (\bar{x}_1 - \dot{\bar{x}}_0) + \bar{f}_{u_0} (\bar{u}_1 - \dot{\bar{u}}_0), \\ \dot{\bar{x}}_1 &= \bar{u}_1. \end{aligned} \quad (17)$$

Here it is necessary to prescribe an initial condition for \bar{x}_1 . We set $\bar{x}_1|_{t=0}$ equal to a certain constant, which we choose in the following special way. Denote

$$\dot{\varphi}(0) = a, \quad f(0, \varphi(0), \varphi(0), u) = Fu, \quad f(0, \varphi(0), \varphi(0), Fu) = F^2u, \text{ etc.}$$

Consider the sequence

$$q_k = a + Fa + \dots + F^{k-1}a - kF^{ka}, \quad (18)$$

which converges by virtue of condition (3). Put

$$\bar{x}_1|_{t=0} = \lim_{k \rightarrow \infty} q_k. \quad (19)$$

Denote $\bar{z}_0(0) = \bar{z}_{00}$, $\dot{\bar{z}}_0(0) = \bar{z}_{10}$, $\bar{z}_1(0) = \bar{z}_{01}$, and form the expressions

$$Z_0 = z_0 + \bar{z}_0 - \bar{z}_{00}; \quad (20)$$

$$Z_1 = z_0 + \Delta t z_1 + \bar{z}_0 + \Delta t \bar{z}_1 - (\bar{z}_{00} + t\bar{z}_{10} + \Delta t \bar{z}_{01}). \quad (21)$$

Theorem 3. *If $f(t, x, y, u)$ satisfies the stability condition (3) and has continuous partial derivatives in G up to order $n+2$ inclusive, and if $\varphi(t)$ is continuously differentiable $n+2$ times in a neighborhood of $t=0$, then for the solution z of system (5) satisfying the initial conditions (6), the inequalities*

$$|z - Z_n| < c\Delta t^{n+1} \quad (n = 0, 1), \quad (22)$$

hold, where c is a certain constant independent of t and Δt , provided only that $\Delta t < \Delta t_0$, where Δt_0 is sufficiently small, and $0 \leq t \leq h$.

On the interval $t_0 \leq t \leq h$, where t_0 is arbitrarily small but fixed as $\Delta t \rightarrow 0$, the inequalities

$$|z - \bar{z}_0| < c\Delta t, \quad |z - (\bar{z}_0 + \Delta t \bar{z}_1)| < c\Delta t^2 \quad (23)$$

are valid.

Remark. In view of the fact that $x_0 = \varphi(0) = \bar{x}_0(0) = \bar{x}_{00}$, we have $X_0 \equiv \bar{x}_0$, and, consequently, (23) for x and $n=0$ is valid not only on $t_0 \leq t \leq h$, but also on the entire interval $0 \leq t \leq h$.

The theorem thus asserts that the expressions (20), (21) serve, for the solution under study, as asymptotic formulas with remainder terms of orders Δt and Δt^2 , respectively, which are uniform on the whole interval of variation of t under consideration. At the same time, inequalities (23) show that everywhere

except in an arbitrarily small neighborhood of the initial point $t = 0$, simpler expressions, \bar{z}_0 and $\bar{z}_0 + \Delta t \bar{z}_1$, can serve as asymptotic formulas with the same degree of accuracy.

Moscow State University
named after M. V. Lomonosov

Received
2 III 1962

REFERENCES

1. A. D. Myshkis, *UMN*, **4**, No. 5 (1949).
2. A. B. Vasil'eva, A. M. Rodionov, *Proceedings of the Seminar on Differential Equations with Deviating Argument*, vol. 1, Publishing House of the Peoples' Friendship University, 1961.
3. A. B. Vasil'eva, *Mathematical Collection*, **50** (92), 43 (1960).
4. A. B. Vasil'eva, *Asymptotic Methods in the Theory of Ordinary Differential Equations with Small Parameters at the Highest Derivatives*, Doctoral dissertation, Moscow State University, 1961.

Note: Figure translations are in progress. See original paper for figures.

Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.