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# Mathematics

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## Abstract

## Full Text

*Mathematics*

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# ON THE THEORY OF STATISTICALLY SIMILAR REGIONS

The theory of similar regions was founded by J. Neyman and E. Pearson in 1939. <sup>(1)</sup> (For definitions and results up to 1954, see <sup>(2)</sup>.) Some properties of similar regions of linear type were given in the author's preceding note <sup>(3)</sup>. Here we indicate one rather broad class of distributions that allow the construction of similar regions.

We consider Euclidean  $n$ -dimensional space  $E_n$  and on it a family of probability measures  $P_\theta$ , defined on one and the same  $\sigma$ -algebra. Let each measure  $P_\theta$  have a continuous probability density  $L(X, \theta)$  with respect to Lebesgue measure. We shall assume that the parameter  $\theta$  is a number lying in the interval  $(a, b)$ . A statistic  $t$  such that, for all  $\xi, \theta$ ,  $P(t < \xi)$  exists and does not depend on  $\theta$ , will be called zonal; the construction of similar regions and zonal statistics is essentially one and the same problem. If  $\theta_1, \dots, \theta_s$  is any finite set of values of the parameter, then statistics  $t$  that are zonal for this set of parameter values and take, with positive probability, values lying in a finite number of prescribed intervals can be constructed with the aid of A. A. Lyapunov's theorem (see <sup>(4)</sup>). We shall consider those families of measures  $P_\theta$  and the corresponding densities  $L(X, \theta)$  for which, starting from the indicated construction for a finite set of parameter values, we can also carry out the construction for  $\theta \in (a, b)$ .

In what follows we shall assume that all functions introduced by us possess the required smoothness conditions, ensuring the validity of the analytic operations carried out below.

Consider a system of scalar statistics  $V_1, V_2, \dots, V_r$  ( $r < n$ ). Suppose that, on any nonempty level surfaces  $V_1 = C_1, \dots, V_r = C_r$ , the measures  $P_\theta$  generated by the expression  $L(X, \theta) dX$  allow the introduction of a conditional distribution.

We shall suppose that a system of local coordinates  $\xi_1, \dots, \xi_{n-r}$  can be introduced on the indicated level surfaces in such a way that throughout  $E_n$  we obtain the system of coordinates  $(V_1, \dots, V_r; \xi_1, \dots, \xi_{n-r})$ .

Now require that  $L(X, \theta)$ , for  $\theta \in (a, b)$  and for all values of  $X$ , satisfy the differential equation:

$$p_0(V_1, \dots, V_r, \theta) \frac{\partial^k L(X, \theta)}{\partial \theta^k} + p_1(V_1, \dots, V_r, \theta) \frac{\partial^{k-1} L(X, \theta)}{\partial \theta^{k-1}} + \dots$$

$$\dots + p_k(V_1, \dots, V_r, \theta)L(X, \theta) + p_{k+1}(V_1, \dots, V_r, \theta) = 0. \quad (1)$$

The coefficients  $p_j(V_1, \dots, V_r, \theta)$  are assumed to be sufficiently smooth; on  $p_0(V_1, \dots, V_r, \theta)$  further analytic conditions are imposed, permitting the subsequent transformations.

Let, on the level surface corresponding to  $V_1, \dots, V_r$ , there exist a conditional probability density  $l(\xi_1, \dots, \xi_{n-r}, V_1, \dots, V_r, \theta)$ , so that  $L(X, \theta) = g(V_1, \dots, V_r, \theta)l(\xi_1, \dots, \xi_{n-r}, V_1, \dots, V_r, \theta)J$ , where  $g(V_1, \dots, V_r, \theta)$  is the joint density of the distribution of the statistics  $V_1, \dots, V_r$ ;  $J$  is the Jacobian of the transformation, of course not depending on  $\theta$ .

Under sufficiently general analytic conditions, for given values  $V_1, \dots, V_r$  the conditional probability density  $l(\xi_1, \dots, \xi_{n-r}, V_1, \dots, V_r, \theta)$ , which for brevity we shall denote by  $l(\xi, \theta)$ , will satisfy the equation

$$\rho_0(\theta) \frac{\partial^m}{\partial \theta^m} l(\xi, \theta) + \rho_1(\theta) \frac{\partial^{m-1}}{\partial \theta^{m-1}} l(\xi, \theta) + \dots + \rho_{m-1}(\theta) \frac{\partial l(\xi, \theta)}{\partial \theta} = 0, \quad (2)$$

where  $m = k + 2$ .

When the analytic conditions are specified, the existence of equation (2) for the conditional probability density is, of course, equivalent to the existence of a finite basis for  $l(\xi, \theta)$ :

$$l(\xi, \theta) = c_1(\xi)s_1(\theta) + \dots + c_m(\xi)s_m(\theta),$$

where  $V_1, \dots, V_r$  are regarded as fixed,  $s_j(\theta)$  depends only on  $\theta$ , and  $c_j(\xi)$  only on  $\xi$ . For what follows, however, it will be more convenient for us to use the language of differential equations.

Let  $\psi(\xi)$  be a continuous function of  $\xi_1, \dots, \xi_{n-r}$  such that the conditional mathematical expectation exists:

$$\int \dots \int \psi(\xi)l(\xi, \theta) d\xi = u_\psi(\theta) = u_\psi. \quad (3)$$

Put  $du_\psi/d\theta = w_\psi$ ; under sufficiently general conditions one may interchange the operators of differentiation with respect to  $\theta$  and integration with respect to the parameter  $\xi$ , so that the equation obtained is

$$\rho_0(\theta) \frac{d^{m-1}}{d\theta^{m-1}} w_\psi + \rho_1(\theta) \frac{d^{m-2}}{d\theta^{m-2}} w_\psi + \dots + \rho_{m-1}(\theta) w_\psi = 0. \quad (4)$$

Let, for  $\theta \in (a, b)$ ,  $w_1(\theta), w_2(\theta), \dots, w_{m-1}(\theta)$  be a set of its fundamental solutions. We have:

$$w_\psi = w_\psi(\theta) = c_1^{(\psi)} w_1(\theta) + \dots + c_{m-1}^{(\psi)} w_{m-1}(\theta). \quad (5)$$

Under sufficiently general conditions there will be segments  $[\theta_i^0 - \varepsilon, \theta_i^0 + \varepsilon] \subset (a, b)$  ( $i = 1, 2, \dots, m-1$ ) such that if  $\theta_i \in [\theta_i^0 - \varepsilon, \theta_i^0 + \varepsilon]$  and  $w_\psi(\theta_i) = 0$  ( $i = 1, 2, \dots, m-1$ ), then, by virtue of relation (5),  $c_j^{(\psi)} = 0$  ( $j = 1, 2, \dots, m-1$ ) and  $w_\psi(\theta) = 0$  for  $\theta \in (a, b)$ .

Take such segments and in each of them take two distinct points  $\theta'_i$  and  $\theta''_i$ . Consider  $2m-2$  conditional probability measures generated by  $l(\xi, \theta)$ , where  $\theta = \theta'_i$  or  $\theta = \theta''_i$  ( $i = 1, 2, \dots, m-1$ ). For this finite family of measures, according to A. A. Lyapunov's theorem<sup>(4)</sup>, construct a conditional zonal statistic  $t = t(\xi)$ . Put  $\psi = \psi(\xi) = \exp i\tau t$ , where  $\tau$  is a scalar parameter. Then  $u_\psi(\tau, \theta)$  is the characteristic function of  $t$ . At the same time we have:  $\Re u_\psi(\tau, \theta'_i) = \Re u_\psi(\tau, \theta''_i)$ ;  $\Im u_\psi(\tau, \theta'_i) = \Im u_\psi(\tau, \theta''_i)$ .

By Rolle's theorem there will be points  $\theta_i \in [\theta'_i, \theta''_i]$  such that

$$\frac{d}{d\theta} \Re u_\psi(\tau, \theta) = 0$$

at  $\theta = \theta_i$ ; from (5) and the preceding it follows that then

$$\frac{d}{d\theta} \Im u_\psi(\tau, \theta) = 0$$

for  $\theta \in (a, b)$ , and the same holds for

$$\frac{d}{d\theta} \Im u_\psi(\tau, \theta),$$

so that  $u_\psi(\tau, \theta)$  does not depend on  $\theta$ , and  $t = t(\xi)$  is a conditional zonal statistic on the level surface with given  $V_1, \dots, V_r$ . Under sufficiently general analytic assumptions we can carry out such a construction on every level surface and cut out similar zones there, and then paste them together over all level surfaces, as is done in J. Neyman's theory of structures (see<sup>(5)</sup>).

Let us consider some particular cases.

1. The case  $k = 1$ . In (1) this is a differential equation of the first order. With a special choice of the coefficients in equation (1) we obtain

$$L(X, \theta) = \exp(T_1(X) + \theta T_2(X) + h(\theta)).$$

This is the case of the existence of sufficient statistics under a natural parametrization.

2.

$$\frac{\partial}{\partial \theta} \frac{L(X, \theta)}{g(V_1, \dots, V_r, \theta)} = 0.$$

This is the general case of sufficient statistics  $V_1, \dots, V_r$  and of the existence of J. Neyman structures.

3. The quantity  $L(X, \theta)/g$  satisfies a linear differential equation of some order with coefficients depending only on  $\theta$ . In this case, which includes the preceding one, the statistics  $V_1, \dots, V_r$  may be called quasi-sufficient. It is possible to describe the construction of similar regions quite fully.
4. The case of repeated sampling  $x_1, \dots, x_r$  for  $x_j$  having the (one-dimensional) distribution density

$$\mu(x, \theta) = \left( \exp \sum_{j=1}^M h_j(\theta) T_j(x) \right) \left( \sum_{i=0}^N \varphi_i(x) g_i(\theta) \right). \quad (6)$$

This is the case of a family that previously had sufficient statistics and was then “spoiled” by perturbation terms of a fairly general kind. It is useful for studying the power of statistical tests based on similar regions.

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- <sup>5</sup> E. Lehmann, Testing Statistical Hypotheses, N. Y., 1959.

*Note: Figure translations are in progress. See original paper for figures.*

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