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Abstract

Full Text

MATHEMATICS

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ON THE GEOMETRIC THEORY OF THE SIMPLEST SINGULAR VARIATIONAL PROBLEM FOR AN $(n - 1)$ -FOLD INTEGRAL

(Presented by Academician I. G. Petrovskii, 20 IV 1961)

Let us consider the variational problem for an $(n - 1)$ -fold integral in parametric form:

$$I = \int_{Q(t^a)} \dots \int \Phi(\xi^\lambda, \xi_a^\lambda) dt^1 \dots dt^{n-1} \quad \left(\xi_a^\lambda = \frac{\partial \xi^\lambda}{\partial t^a} \right). \quad (1)$$

The requirement that the value of the integral (1) be invariant with respect to a transformation of the parameters,

$${}^*t^a = C^a(t^b) \quad \left(\text{Det } |C_b^a| > 0, C_b^a = \frac{\partial C^a}{\partial t^b} \right), \quad (2)$$

imposes a restriction on the integrand Φ :

$$\Phi(\xi^\alpha, \xi_b^\alpha C_a^b) = \text{Det } |C_a^b| \Phi(\xi^\alpha, \xi_c^\alpha). \quad (3)$$

It is easy to show that a function Φ satisfying condition (3) has the form

$$\Phi(\xi^\alpha, \xi_a^\lambda) = \mathfrak{H}(\xi^\lambda, \varepsilon_{\alpha\beta_1 \dots \beta_{n-1}} \xi_1^{\beta_1} \dots \xi_{n-1}^{\beta_{n-1}}), \quad (4)$$

where the function \mathfrak{H} is positive and positively homogeneous of the first degree with respect to the second group of arguments, and $\varepsilon_{\alpha\beta_1 \dots \beta_{n-1}}$ is the unit fundamental n -vector density of weight -1 . For the function (4), the integral (1) has the following form:

$$\sigma = \int_{Q(t^a)} \dots \int \mathfrak{H}(\xi^\lambda, \eta_\alpha) dt^1 \dots dt^{n-1} \quad \left(\eta_\alpha = \varepsilon_{\alpha\beta_1 \dots \beta_{n-1}} \xi_1^{\beta_1} \dots \xi_{n-1}^{\beta_{n-1}} \right). \quad (5)$$

Interpreting the variables ξ^α as coordinates of points in an n -dimensional geometric space X_n , we shall call every hypersurface of the form

$$\xi^\alpha = \xi^\alpha(t^a) \quad (6)$$

measurable if along it the integral (5) is meaningful. The value of the integral (5) for the hypersurface (6) is called its hyperarea¹.

The concept of the indicatrix of the variational problem (5) is introduced essentially in the same way as for a variational problem expressed by an ordinary integral². For fixed ξ^λ , consider the equation

$$\mathfrak{H}(\xi^\lambda, \eta_\alpha) = 1, \quad (7)$$

which defines a hypersurface in the hyperplane coordinates x in the space \mathfrak{E}_n of all contravariant vector densities of weight +1.

The variational problem (5) is called a **singular variational problem of singularity class r** , if the rank of the matrix

$$\|\mathfrak{H}^{\alpha\beta}\|, \quad \left(\mathfrak{H}^{\alpha\beta} = \frac{\partial^2 \mathfrak{H}}{\partial \eta_\alpha \partial \eta_\beta} \right) \quad (8)$$

is equal to $n - 1 - r$. For $r = 0$ the variational problem (5) is called **regular** ⁽¹⁾.

In the present note we shall be interested in the case when $r = 1$. Thus the indicatrices (7) will be hypersurfaces of the first class of singularity ⁽²⁾ in the composite manifold ⁽³⁾ $\mathfrak{E}_n(X_n)$.

The remarks just made show that in considering the geometric theory of a singular variational problem for $(n - 1)$ -fold integrals one must know the theory of a singular hypersurface of the 1st class of singularity in \mathfrak{E}_n . Since \mathfrak{E}_n , in a certain sense ⁽¹⁾, is a centro-affine space, one may make use of the centro-affine theory of a singular hypersurface of the 1st class of singularity ⁽²⁾.

Assuming that the tangent hyperplanes of the singular hypersurface (7) do not pass through the center \mathfrak{E}_n , its equation in hyperplane coordinates can be represented in parametric form:

$$\eta_\alpha = l_\alpha(\eta^a) \quad (a, b, \dots = 1, 2, \dots, n - 2; \alpha, \dots, \omega = 1, 2, \dots, n). \quad (9)$$

The fundamental differential equations of the hypersurface (9) are written as follows ⁽²⁾:

$$\nabla_a l_\alpha = l_{aa}, \quad \nabla_b l_{aa} = -h_{ba} l_\alpha - \mathfrak{G}_{ba} \mathfrak{R}_\alpha, \quad (10)$$

$$\nabla_b \mathfrak{R}_\alpha = -\mathfrak{B}^c_b l_{\alpha c} - \mathfrak{B}_b l_\alpha, \quad (11)$$

where h_{ba} is a tensor, \mathfrak{G}_{ba} , \mathfrak{B}^c_b , \mathfrak{B}_a are ω -densities of weights $-\frac{2}{n-2}$ and $\frac{2}{n-2}$. The $n-1$ covariant vectors of the hypersurface l_α , $l_{\alpha a}$ and the ω -density \mathfrak{R}_α of weight $\frac{2}{n-2}$ are linearly independent. The covariant derivatives in (10) and (11) are taken with respect to the connection with coefficients

$$G_{ba}^c = \mathfrak{G}^{cd} \mathfrak{n}_d^\alpha \partial_b l_{\alpha a}, \quad (12)$$

where \mathfrak{n}_a^α is an ω -density of weight $-\frac{2}{n-2}$, satisfying the equations

$$l_\alpha \mathfrak{n}_a^\alpha = 0, \quad l_{\alpha a} \mathfrak{n}_b^\alpha = \mathfrak{G}_{ab}, \quad \mathfrak{R}_\alpha \mathfrak{n}_a^\alpha = 0, \quad (13)$$

and

$$\mathfrak{G}_{ab} \mathfrak{G}^{bd} = \delta_a^d. \quad (14)$$

Suppose that for $n > 3$ the tensor h_{ba} does not degenerate,

$$\mathfrak{h} = \text{Det} |h_{ba}| \neq 0. \quad (15)$$

As is known ⁽¹⁾, with each \mathfrak{E}_n one may associate a centro-affine space E_n , and conversely; moreover, if densities in these spaces of covariant, contravariant valencies and weights respectively p, q, \mathfrak{k} and p, q, k are involved, then the equality holds:

$$k = q - p - (n-1)\mathfrak{k}. \quad (16)$$

With the aid of the quantity

$$\mathfrak{A} = \left(\frac{1}{(n-1)!} \mathfrak{E}^{\alpha\beta\alpha_1 \dots \alpha_{n-2}} \mathfrak{E}^{a_1 \dots a_{n-2}} l_\alpha \mathfrak{R}_\beta l_{\alpha_1 a_1} \dots l_{\alpha_{n-2} a_{n-2}} \right)^2, \quad (17)$$

which is a scalar density of weight 2 in \mathfrak{E}_n , and, according to (16), of weight $-2(n-1)$ in E_n and of weight $\frac{2n}{n-2}$ on the hypersurface, we shall put in corres-

— quantities from \mathfrak{E}_n to the improper quantities from E_n (1) by means of the equalities

$$\tilde{l}_\alpha = |\mathfrak{h}|^{\frac{n}{2(n-1)(n-2)}} \mathfrak{A}^{-\frac{1}{2(n-1)}} l_\alpha(\eta^a), \quad (18)$$

$${}^* \tilde{l}_{aa} = |\mathfrak{h}|^{\frac{n}{2(n-1)(n-2)}} \mathfrak{A}^{-\frac{1}{2(n-1)}} l_{aa}(\eta^b), \quad (19)$$

$$\tilde{N}_\alpha = |\mathfrak{h}|^{-\frac{1}{2(n-1)}} \mathfrak{A}^{-\frac{1}{2(n-1)}} \mathfrak{R}_\alpha(\eta^b), \quad (20)$$

for which the derivational equations (10) and (11) take the form:

$$\nabla_a \tilde{l}_\alpha = {}^* \tilde{l}_{aa} - \frac{n}{(n-1)(n-2)} A_a \tilde{l}_\alpha, \quad (21)$$

$$\nabla_b {}^* \tilde{l}_{aa} = -\frac{n}{(n-1)(n-2)} A_b {}^* \tilde{l}_{aa} - h_{ba} \tilde{l}_\alpha - \tilde{g}_{ba} \tilde{N}_\alpha, \quad (22)$$

$$\nabla_a \tilde{N}_\alpha = -\tilde{V}_a^c {}^* \tilde{l}_{ac} - \tilde{W}_a \tilde{l}_\alpha + \frac{1}{n-1} A_a \tilde{N}_\alpha, \quad (23)$$

where

$$\tilde{g}_{ba} = |\mathfrak{h}|^{-\frac{1}{n-2}} \mathfrak{G}_{ba}, \quad (24)$$

$$\tilde{V}_a^c = |\mathfrak{h}|^{-\frac{1}{n-2}} \mathfrak{V}_a^c, \quad (25)$$

$$\tilde{W}_a = |\mathfrak{h}|^{-\frac{1}{n-2}} \mathfrak{W}_a, \quad (26)$$

$$A_a = -\frac{1}{2} \nabla_a \ln |\mathfrak{h}|. \quad (27)$$

Alongside the tangent composite manifold of the first order $E_n(X_n)$, consider the composite manifold $\mathfrak{E}_n(X_n)$. The specification of the singular variational problem (5) entails the specification of a field of singular hypersurfaces in the composite manifold $\mathfrak{E}_n(X_n)$. Assuming now that, in (9)–(27), all the quantities considered also depend on ξ^α , the equations of the field of singular hypersurfaces may be written in the form

$$\eta_\alpha = l_\alpha(\xi^\lambda, \eta^a) \quad (28)$$

in hyperplane coordinates. Considering each hypersurface of the field (28) as X_{n-2} , we arrive at consideration of the composite manifold $X_{n+(n-2)}$. The principal task in studying this composite manifold is to find an invariant linear connection, determined by solving the Pfaff equations

$$d\eta^a + \Gamma^a = 0, \quad (29)$$

where $\Gamma_\alpha^a(\xi^\lambda, \eta^b) d\xi^\alpha$ are the required Pfaff forms.

Corresponding to the quantities (18)–(20) and (28), introduce into consideration n independent Pfaff forms:

$$\tilde{l} = \tilde{l}_\alpha(\xi^\lambda, \eta^b) d\xi^\alpha, \quad {}^*\tilde{l}_a = {}^*\tilde{l}_{aa}(\xi^\lambda, \eta^b) d\xi^\alpha, \quad \tilde{N} = \tilde{N}_\alpha(\xi^\lambda, \eta^a) d\xi^\alpha. \quad (30)$$

Representing the operator of base differentiation $(^3)$ in the form of the symbolic equality

$$D = {}^*\tilde{l}_a D^a + \tilde{l} D_{(n-1)} + \tilde{N} D_{(n)}, \quad (31)$$

and the required forms in the form of the expansion

$$\Gamma^a = \gamma^{ab} \tilde{l}_b + \gamma^a \tilde{l} + \delta^a \tilde{N}, \quad (32)$$

one can prove the following assertion.

If the indicatrices of the singular variational problem for an $(n-1)$ -fold integral are not cylindrical or conical surfaces, and their asymptotic cones are hypercones, while the tensor h_{ab} is nondegenerate, then the invariant linear connection in the composite manifold determined by the field of indicatrices, for $n > 3$, is uniquely determined from the conditions

$$[\tilde{l} D \tilde{l}] = 0, \quad [\tilde{N} D \tilde{l}] = 0, \quad D_{(n)} \tilde{g}_{ab} = 0, \quad (33)$$

where the square brackets denote the exterior product of forms in the sense of Cartan. For $n = 3$ the third condition is replaced by the condition

$$D_{(N)} \mathfrak{W}^{(3)} = 0, \quad (34)$$

where $\mathfrak{W}^{(3)}$ is a scalar density of weight 3, replacing the w -density \mathfrak{W}_a .

The linear connection in $X_{n+(n-2)}$ found in this way can be used to find conditions for reducibility of the field of singular hypersurfaces in $\mathfrak{E}_n(X_n)$ to a constant one, i.e. essentially the conditions for reducibility of the variational problem (5) to the case when the integrand contains no variables ξ^a . The conditions found are indicated by the following

Theorem. In order that the field of singular hypersurfaces of the type under consideration in $\mathfrak{E}_n(X_n)$ be reducible, by means of a suitable choice of coordinate systems, to a constant one, it is necessary and sufficient that, for $n > 3$, the linear connection in the composite manifold be a connection of zero curvature, that the fields of local objects G_{ab}^c , \tilde{g}_{ab} , and h_{ab} be constant with respect to this connection, and that the scalar φ be identically equal to zero, where φ is the coefficient of the bracket $[\tilde{l}\tilde{N}]$ in the expansion of $[D\tilde{l}]$.

For $n = 3$ the indicated conditions are simplified.

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