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CYBERNETICS AND THE THEORY OF CONTROL

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Fig. 1

Figure 1: Fig. 1

Abstract

Full Text

CYBERNETICS AND THE THEORY OF CONTROL

A. D. TALANTSEV

ON THE ALGEBRA OF POTENTIAL-PULSE OBJECTS

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1. In the logical investigation of various kinds of objects, one is usually interested in a discrete set of states characteristic of them. We shall confine ourselves here to considering objects for each of which no more than two states are distinguished (usually denoted by 1 and 0). We shall assume that information about the behavior of such objects in time is expressed in the form of quantized signals, a typical example of which is shown in Fig. 1a. The positive ordinate of the graph represents state 1, the negative ordinate state 0. This figure presents all the characteristic features of the behavior of an object in the small, i.e., in a neighborhood of an arbitrary instant of time. The behavior of an object similar to its behavior at the instant of time t_1 and denoted by 1_1 will be called a **positive potential**. The behavior of an object similar to its behavior at the instant of time t_2 and denoted by 0_1 will be called a **negative impulse**. The behavior of an object similar to its behavior at the instant of time t_3 and denoted by Δ_1 will be called a **positive transition**. The behavior of an object similar to its behavior at the instant of time t_4 and denoted by 0_0 will be called a **negative potential**. The behavior of an object similar to its behavior at the instant of time t_5 and denoted by 1_0 will be called a **positive impulse**. The behavior of an object similar to its behavior at the instant of time t_6 and denoted by Δ_0 will be called a **negative transition**. Impulses and transitions will be called **events of the object**. We shall consider potentials and events to be values of a certain logical variable, which it assumes as time passes. There are six values, forming the alphabet $\{1_1, 0_1, 1_0, 0_0, \Delta_1, \Delta_0\}$. A variable taking values from this alphabet will be called a **potential-pulse logical variable**. Objects described by variables of this kind will be called **potential-pulse objects**.

Fig. 1

We assume that potentials and events postulate the following rules of behavior of a potential-pulse object in the small.

1.1. *If at the instant of time t the object is in potential 1_1 , then on a time interval containing the instant t and not smaller than some fixed interval q , the object is also in potential 1_1 .*

1.2. *If at the instant of time t the object is in potential 0_0 , then on an interval containing the instant t and not smaller than q , the object is also in potential 0_0 .*

1.3. If at time t the event 1_0 occurred, then on the intervals $(t-q, t)$ and $(t, t+q)$ the object is in the potential 0_0 .

1.4. If at time t the event 0_1 occurred, then on the intervals $(t-q, t)$ and $(t, t+q)$ the object is in the potential 1_1 .

1.5. If at time t the event Δ_1 occurred, then on the interval $(t-q, t)$ the object is in the potential 1_1 , and on the interval $(t, t+q)$ —in the potential 0_0 .

1.6. If at time t the event Δ_0 occurred, then on the interval $(t-q, t)$ the object is in the potential 0_0 , and on the interval $(t, t+q)$ —in the potential 1_1 .

It follows from the rules of behavior in the small that the time interval between any two events cannot be less than the fixed interval q . To describe potential-pulse objects it is expedient to introduce a quantized time scale. We assume that events can occur only at instants of time corresponding to integers. In this case the initial and terminal points of the interval on which the behavior of the object is considered are excluded for events. In this case, on a time interval $m \cdot q$ (m an integer, q the unit of time) a potential-pulse variable is completely determined by its values at the instants of time $1, 2, \dots, \dots, m-1$.

We shall denote individual representatives of the set of potential-pulse variables by Z_1, Z_2, \dots, Z_n (variables of type Z). Two variables Z_i and Z_k are equal ($Z_i = Z_k$) if for every instant of time their values coincide. From the set of potential-pulse variables we single out the constants **1** and **0**. The first is equal to 1_1 at all instants of time, the second to 0_0 . A potential-pulse variable that has no pulses will be called a **potential logical variable** (a variable of type X). A potential-pulse variable that lacks the potential 1_1 will be called a **positive-pulse logical variable** (a variable of type Y^1). On an interval $m \cdot q$ there is realized a maximum of $2 \cdot 3^{n-1}$ variables of type Z , a maximum of 2^m variables of type X , and a maximum of 2^{m-1} variables of type Y^1 .

2. We shall investigate functions of potential-pulse variables. A function of potential-pulse variables is itself a potential-pulse variable. We shall confine ourselves to consideration of the class of functions whose definition follows below.

Definition. A function of potential-pulse variables is stationary if, for any instants of time, the values of the function corresponding to the same sets of values of the arguments coincide.

As is evident, for stationary functions the assignment table does not depend on time. We note that the property of stationarity and the rules of behavior in the

small eliminate arbitrariness in assigning the values of a function for different sets of argument values. For stationary functions the following processing rules are observed:

2a) sets of values of the arguments from the alphabet $\{1_1 0_0\}$ can pass into function values only from the alphabet $\{1_1 0_0\}$;

2b) sets of values of the arguments from the alphabet $\{1_1 0_0 1_0 0_1\}$ can pass into function values only from the alphabet $\{1_1 0_0 1_0 0_1\}$;

2c) sets of values of the arguments containing at least one of the values Δ_1, Δ_0 can pass into values from the full alphabet $\{1_1, 0_0, 1_0 0_1 \Delta_1 \Delta_0\}$.

Operators realizing stationary functions will be called **filters**. Corresponding to the number of arguments $1, 2, \dots, n$, filters will be called **single-input** (with **one input**), **two-input** (with **two inputs**), ..., **n-input** (with n inputs). Since the greatest restriction is imposed on the processing of potentials, the specification of a filter should begin with those sets into which only potentials enter.

Four important one-input filters are defined by Table 1.

Table 1

Z	1_1	0_0	1_0	0_1	Δ_1	Δ_0
pZ	1_1	0_0	0_0	1_1	Δ_1	Δ_0
dZ	0_0	0_0	0_0	0_0	1_0	0_0
iZ	0_0	0_0	1_0	0_0	0_0	0_0
NZ	0_0	1_1	0_1	1_0	Δ_0	Δ_1

The filter p “cleanses” a potential-pulse variable of pulses (Fig. 1). It transforms a variable of type Z into a variable of type X . We shall call it a **potentiality** filter. The filter d marks, by pulses 1_0 , the transitions Δ_1 of a variable of type Z (Fig. 1). We shall call it a filter of **positive transition**. The filter i marks, by pulses 1_0 , the pulses 1_0 of a variable of type Z (Fig. 1). We shall call it a filter of **positive pulseness**. The filters d and i transform variables of type Z into variables of type Y^1 . The filter N “inverts” a potential-pulse variable. We shall call it a filter of **logical negation**.

In what follows we shall use the following notation: by γ we denote any symbol of the alphabet $\{1_1 0_0 1_0 0_1 \Delta_1 \Delta_0\}$; by β , any symbol of the alphabet $\{1_0 0_1 \Delta_1 \Delta_0\}$; by α , any symbol of the alphabet $\{1_1 0_0\}$.

Table 2

Z_1	Z_2	$Z_1 \& Z_2$
1_1	γ	γ
0_0	γ	0_0
1_j	1_0	1_0

Z_1	Z_2	$Z_1 \& Z_2$
1_0	β	0_0
0_1	β	β
Δ_i	Δ_i	Δ_i
Δ_1	Δ_0	0_0

$$\beta \neq 1_0, \quad i = 1, 0,$$

$$\gamma_1 \& \gamma_2 = \gamma_2 \& \gamma_1 \dots (T_2)$$

Table 3

Z_1	Z_2	$Z_1 \vee Z_2$
0_0	γ	γ
1_1	γ	1_1
0_1	0_1	0_1
0_1	β	1_1
1_0	β	β
Δ_i	Δ_i	Δ_i
Δ_1	Δ_0	1_1

$$\beta \neq 0_1, \quad i = 1, 0,$$

$$\gamma_1 \vee \gamma_2 = \gamma_2 \vee \gamma_1 \dots (T_3)$$

Table 2 and relation (T_2) define a two-input filter $\&$, which we shall call **universal conjunction**. Table 3 and relation (T_3) define a two-input filter \vee , which we shall call **universal disjunction**.

The set of potential-pulse variables with the operations $p, d, i, N, \&$, and \vee forms a certain algebraic system, which we shall call the **algebra of potential-pulse objects**. The question naturally arises as to the functional completeness of the system of filters $p, d, i, N, \&$, and \vee . The following assertion is true.

Theorem. *Any filter with n inputs can be represented by means of a formula using the filters $p, d, i, N, \&$, and \vee .*

Let $\Phi(Z_1, \dots, Z_n)$ be an arbitrary filter with n inputs. Below, instead of the symbol N we shall use the symbol $\bar{}$, instead of the symbol $\&$ —the sym-

...by the symbol \cdot . We shall further assume that

$$Z^{1_1} = pZ, \quad Z^{0_0} = p\bar{Z}, \quad Z^{1_0} = iZ, \quad Z^{0_1} = i\bar{Z}, \quad Z^{\Delta_1} = dZ, \quad Z^{\Delta_0} = d\bar{Z}.$$

The following relation holds:

$$\begin{aligned} \Phi(Z_1, \dots, Z_n) = & \\ = & \left(\sum_{1_1} Z_1^{\alpha_1} \dots Z_n^{\alpha_n} \right) \cdot \left(\sum_{0_1} Z_{i_1}^{\alpha_{i_1}} \dots Z_{i_{k-1}}^{\alpha_{i_{k-1}}} \cdot Z_{i_k}^{\beta_{i_k}} \dots Z_{i_n}^{\beta_{i_n}} \right) \vee \quad (1) \\ & \vee \sum_{1_0} Z_{i_1}^{\alpha_{i_1}} \dots Z_{i_{k-1}}^{\alpha_{i_{k-1}}} \cdot Z_{i_k}^{\alpha_{i_k}} \dots Z_{i_n}^{\beta_{i_n}}. \end{aligned}$$

Here \sum_{1_1} denotes the universal disjunction over those sets $\alpha_1, \dots, \alpha_n$ for which $\Phi(\alpha_1, \dots, \alpha_n) = 1_1$; \sum_{0_1} denotes the universal disjunction over those sets $\alpha_{i_1}, \dots, \alpha_{i_{k-1}}, \beta_{i_k}, \dots, \beta_{i_n}$ for which $\Phi(\alpha_{i_1}, \dots, \alpha_{i_{k-1}}, \beta_{i_k}, \dots, \beta_{i_n}) = 0_1$; \sum_{1_0} denotes the universal disjunction over those sets $\alpha_{i_1}, \dots, \alpha_{i_{k-1}}, \beta_{i_k}, \dots, \beta_{i_n}$ for which $\Phi(\alpha_{i_1}, \dots, \alpha_{i_{k-1}}, \beta_{i_k}, \dots, \beta_{i_n}) = 1_0$. For \sum_{0_1} and \sum_{1_0} : $i_j = 1, \dots, n$, where $j = 1, \dots, k, \dots, n$ and $k = 1, \dots, n$. The right-hand side of (1) will be called the **perfect normal form** for an n -input filter.

It is interesting to note that for filters transforming variables of type X into variables of type X (filters of type $X-X$), the disjunctions \sum_{0_1} and \sum_{1_0} are equal to 0, and the right-hand side of (1) becomes the perfect disjunctive normal form for functions of Boolean algebra. Thus, Boolean algebra is a subalgebra of the algebra of potential-pulse objects. The number of filters with n inputs grows extremely rapidly as n increases. There are exactly 40 one-input filters. The number M of filters with n inputs is estimated by the inequalities:

$$2^{4^n} < M < 2^{6^n}. \quad (2)$$

3. If potential-pulse variables are modeled by electrical quantities of a definite type, then the filters p, d, i are realized by electrical filters. The filter p corresponds to a low-pass filter, the filter d to a medium-frequency filter ("band-pass filter"), and the filter i to a high-pass filter. The system of filters p, d, i possesses, as is evident, "physical completeness," i.e., the ability to process the full frequency spectrum. In papers ^(1, 2), technical applications of the so-called homogeneous potential-pulse circuits (filters of type $X-Y$) were considered. The present note generalizes the results of those papers.

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