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# Mathematics

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**Abstract**

**Full Text**

*Mathematics*

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## ELLIPTIC EQUATIONS WITH SINGULAR COEFFICIENTS

(Presented by Academician I. N. Vekua, March 4, 1961)

**1. Notation.**  $E$  is  $n$ -dimensional Euclidean space;  $x = (x_1, x_2, \dots, x_n)$ ;  $f(x) = f(x_1, x_2, \dots, x_n)$ ,  $dx = dx_1, dx_2, \dots, dx_n$ ,  $r(x, t) = (\sum_{i=1}^n (x_i - t_i)^2)^{1/2}$ ,  $\rho(x) = r(x, 0)$ ;  $S(D)$  is the class of bounded measurable functions with norm  $\|f\|_{S(D)} = \sup_{x \in D} |f(x)|$ ,  $S(\beta, D)$  is the class of functions representable in the form  $f(x) = \rho^{-\beta}(x)f_0(x)$ , where  $f_0(x) \in S(D)$ . If the norm  $\|f\|_{S(\beta, D)} = \|f_0\|_{S(D)}$  is introduced, then  $S(\beta, D)$  will be isometric to  $S(D)$ .

Let there be  $p$  distinct points  $c_1, c_2, \dots, c_p$  inside and on the boundary of the domain  $D$ , and let  $\rho_i(x) = r(x, c_i)$ . By  $\Pi(x)$  we denote the distance from the point  $x$  to the set  $c_1, c_2, \dots, c_p$ , i.e.

$$\Pi(x) = \min\{\rho_1(x), \rho_2(x), \dots, \rho_p(x)\};$$

$S(\beta, \Pi, D)$  is the class of functions of the form  $f(x) = \Pi^{-\beta}(x)f_0(x)$ , where  $f_0(x) \in S(D)$ , with norm  $\|f\|_{S(\beta, \Pi, D)} = \|f_0\|_{S(D)}$ ;  $K$  is a cone with vertex at the point 0 and infinite in one direction;  $q(K, \alpha, \beta) = \int_K \rho^{-\beta}(y)r^{n-\alpha}(y, I) dy$ , where  $0 < \alpha < n$ ,  $\alpha < \beta < n$ ;  $I$  is a point of the unit sphere,  $I \in K$ . If  $K = E$ , then we shall write  $q(E, \alpha, \beta) = q(\alpha, \beta)$ .

**2. A new class of integral equations.** Let  $D$  be an arbitrary bounded or unbounded domain. We first consider the simplest operator

$$T\varphi = \rho^{-\alpha}(x) \int_D r^{\alpha-n}(x, t)\varphi(t) dt, \quad (1)$$

where  $0 < \alpha < n$  and 0 is an interior point of the domain  $D$ .

**Theorem 1.** *Formula (1) defines a linear (not completely continuous) operator in the Banach spaces  $S(\beta, D)$ ,  $\alpha < \beta < n$ , and*

$$\|T\|_{S(\beta, D)} = q(\alpha, \beta).$$

**Generalization.** Let there be several singular points  $c_1, c_2, \dots, c_p$ , which may lie both inside and on the boundary of the domain. If the domain is unbounded, then the infinitely distant point is also included among the singular points; it, in turn, may be interior or boundary and is denoted by  $c_{p+1}$ .

Then the formula

$$T_{\Pi}\varphi = \Pi^{-\alpha}(x) \int_D r^{\alpha-n}(x, t)\varphi(t) dt$$

defines a linear operator in  $S(\beta, \Pi, D)$ ,  $\alpha < \beta < n$ , and

$$q(K_i, \alpha, \beta) \leq \|T_{\Pi}\|_{S(\beta, \Pi, D)} \leq Bq(V_i, \alpha, \beta), \quad i = 1, 2, \dots, p + 1,$$

where  $K_i, V_i$  are the cones of tangency and visibility of the domain  $D$  from the point  $c_i$ ; the constant  $B$  does not depend on the domain.

If the point  $c_i$  is interior, we put  $K_i = V_i = E$ .

**Theorem 2.** If  $K(x, t) \in S(D \times D)$ , then the formula

$$K\varphi = \Pi^{-\alpha}(x) \int_D r^{\alpha-n}(x, t)K(x, t)\varphi(t) dt$$

defines a linear operator in  $S(\beta, \Pi, D)$ ,  $\alpha < \beta < n$ , and

$$\mu_i q(K_i, \alpha, \beta) \leq \|K\|_{S(\beta, \Pi, D)} \leq Mq(V_i, \alpha, \beta), \quad (2)$$

where

$$M = \sup_{x, t \in D} |K(x, t)|, \quad \mu_i = \lim_{x \rightarrow c_i} \lim_{t \rightarrow c_i} |K(x, t)|, \quad i = 1, 2, \dots, p + 1.$$

**Theorem 3.** If  $K(x, t)$  is continuous for  $x \neq t$  and  $\overline{\lim}|K(x, t)| = 0$  at all singular points, then the operator  $K\varphi$  is completely continuous in  $S(\beta, \Pi, D)$ ,  $\alpha < \beta < n$ , for every  $\beta$ .

Theorems 1-3 make it possible to give certain criteria for the solvability of the equation (cf. (8,6)).

$$\varphi(x) + \int_D \frac{K(x, t)}{\Pi^{\alpha}(x) r^{n-\alpha}(x, t)} \varphi(t) dt = f(x), \quad (3)$$

where  $f(x) \in S(\beta, \Pi, D)$ ,  $\beta < n$ . For sufficiently small  $K(x, t)$  the solution exists and is unique, but this cannot be achieved by making the domain  $D$  small. Under the conditions of Theorem 3 the Fredholm theorems are valid. However, from Theorems 1 and 3 there follows a more general assertion.

**Theorem 4.** Let  $K(x, t)$  be continuous for  $x \neq t$  and at all singular points. If

$$\sum_{i=1}^{p+1} |K(c_i, c_i)| q(V_i, \alpha, \beta) < 1, \quad (4)$$

then the Fredholm theorems are valid for equation (3).

**3. The manifold of solutions.** Consider the elliptic equation of second order

$$Lu \equiv \Delta u + \sum_{i=1}^n \frac{a_i(x)}{\rho(x)} u'_{x_i} + \frac{b(x)}{\rho^2(x)} u = 0. \quad (5)$$

The point  $x = 0$  (as well as  $x = \infty$ ) is called its **regular singular point** if the functions  $a_i(x)$ ,  $i = 1, 2, \dots, n$ ,  $b(x)$  are bounded at this point, and a **weak singularity** if, as  $\rho \rightarrow 0$ ,  $a_i(x), b(x) = O(\rho^\varepsilon)$ ,  $\varepsilon > 0$  (as  $\rho \rightarrow \infty$ ,  $O(\rho^{-\varepsilon})$ ).

To study the manifold of solutions we put

$$u(x) = - \int_D \psi(r) \varphi(t) dt + h(x), \quad (6)$$

where  $\psi(r)$  is the fundamental solution of Laplace' s equation and  $h(x)$  is an arbitrary function. Substituting (6) into (5), we obtain for  $\varphi(x)$  an integral equation of the form (3), where  $f(x)$  is arbitrary,  $K = K_1 + K_2$ , and \*

$$K_1(x, t) = -\frac{1}{\omega_n} \frac{\sum_{i=1}^n r'_{x_i} a_i(x)}{\rho(x) r^{n-1}(x, t)}, \quad K_2(x, t) = \frac{b(x)}{\omega_n(n-2)} \frac{1}{\rho^2(x) r^{n-2}(x, t)}. \quad (7)$$

\* Henceforth the case  $n = 2$ ,  $b(0) \neq 0$  is everywhere excluded.

For a local investigation of a regular singular point, take as  $D$  a sufficiently small neighborhood of it and pass from  $x = 0$  to  $x = \infty$ . Then Theorem 2 immediately implies:

**Theorem 5.** *If  $\lim_{x \rightarrow 0} a_i(x)$ ,  $i = 1, \dots, n$ , and  $\lim_{x \rightarrow 0} b(x)$  are sufficiently small, then there always exist solutions continuous at the singular point.*

Consider equations with two regular singular points. By translations and inversions we can always move them to the points  $0, \infty$ , so that the equation takes the form (5), where  $a_i(x), b(x)$  are defined and bounded in the whole space  $E$ . In this case, and also for the case  $p > 2$  of singular points, we put  $D = E$  in (6). From Theorems 2 and 4 we obtain a number of results, of which we shall present one that has some connection with Schrödinger' s problem known in quantum mechanics:

**Theorem 6.** *If, of two regular singular points, one is a weak singularity, and at the other  $a_i(x), b(x)$  are continuous and small, then equation (5) has a continuum of solutions continuous in the whole space, including both singular points.*

**4. The first boundary-value problem.** Let  $D$  be a bounded domain whose boundary consists of a finite number of Lyapunov surfaces. If  $G(x, t)$  is the Green's function of the Laplace operator, then we shall also require that (cf. (1<sup>2</sup>))

$$|G'_{x_i}(x, t)| \leq Hr^{1-n}, \quad i = 1, \dots, n. \quad (8)$$

The formulation of the first boundary-value problem is: for the given values  $u(x) = \psi(x)$  on the boundary of the domain, find solutions of the equation  $Lu = \rho^{-2}(x)g(x)$ ,  $g(x) \in S(D)$ , regular everywhere in  $D$  except at the point  $x = 0$ , and admitting at this point a singularity whose order is restricted by the condition  $\Delta u \in S(\beta, D)$ ,  $\beta < n$ .

As usual, reducing the boundary values to zero and setting

$$u(x) = - \int_D G(x, t)\varphi(t) dt,$$

we obtain for  $\varphi(x)$  the integral equation (3) with kernels of type (7) (see (9)).

**Theorem 7.** *Let  $b(x) = O(\rho^\varepsilon)$ ,  $\varepsilon > 0$ ,  $n \geq 2$ . If the  $a_i(x)$ ,  $i = 1, \dots, n$ , and either  $b(x)$  or the domain  $D$  are sufficiently small, then the boundary-value problem has a unique solution, continuous at the singular point.*

*If the number  $\beta$  is fixed by the conditions  $2 < \beta < n$ ,*

$$Hq(1, \beta) \sum_{i=1}^n \sup_{x \in D} |a_i(x)| + \frac{q(2, \beta)}{\omega_n(n-2)} \sup_{x \in D} |b(x)| < 1,$$

*then the boundary-value problem has a unique solution  $u(x) \in S(\beta - 2, D)$ .*

**Theorem 8.** *If  $a_i(x)$ ,  $i = 1, 2, \dots, n$ , and  $b(x)$  are continuous at the singular point and*

$$Hq(1, \beta) \sum_{i=1}^n |a_i(0)| + \frac{q(2, \beta)}{\omega_n(n-2)} |b(0)| < 1$$

*(and for  $n = 2$ , moreover,  $b(x) = O(\rho^\varepsilon)$ ,  $\varepsilon > 0$ ), then the Fredholm theorems hold for the first boundary-value problem.*

**Theorem 9.** *If  $b(x) \leq 0$  in the domain  $D$ , then under the conditions of Theorem 8 the boundary-value problem is solvable uniquely and the solution is bounded at the singular point.*

The proof of this theorem is based on the generalized maximum principle (10).

Consider the equation

$$\Delta u + \sum_1^n A_i(x)u'_{x_i} + B(x)u = F(x) \quad (9)$$

with several regular singular points  $c_1, c_2, \dots, c_p$  and  $c_{p+1} = \infty$ , which may lie both inside and on the boundary of the domain, being a point of smoothness or a conical point of the surface. In other words, let  $A_i(x) \in S(1, \Pi, D)$ ,  $i = 1, \dots, n$ ;  $B(x), F(x) \in S(\alpha, \Pi, D)$ ,  $\alpha \leq 2$ , where  $\Pi(x) = \min_{1 \leq i \leq p} \{r(x, c_i)\}$ . Suppose that the Green's function of the Laplace equation still satisfies conditions (8).

Then theorems of the type 7, 8, 9 hold. Let us note only that if the singular points lie on the boundary of the domain, then in theorem 9 one cannot assert uniqueness and boundedness of the solution. The results also extend to equations of noncanonical form.

The present work is a further development of the author's papers <sup>(6,7)</sup>, in which the generalized Cauchy–Riemann system and the integral equations associated with it were studied. Singularities below the first order and somewhat more general classes of coefficients were considered in <sup>(4,5)</sup>. If (5) is multiplied by  $\rho^2(x)$ , then one may speak of degeneration of the order of the equation. Degenerations of various types have been the subject of many works; see, for example, <sup>(11,12)</sup>. However, all these works do not cover equations (5).

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