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# MATHEMATICS

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**Abstract**

**Full Text**

## MATHEMATICS

V. MIKHAILOV

### ON THE DIRICHLET PROBLEM AND THE FIRST MIXED PROBLEM FOR A PARABOLIC EQUATION

*(Presented by Academician I. G. Petrovskii on 6 IV 1961)*

#### I. Let us consider the equation

$$\frac{\partial u}{\partial t} - L_0(x, t, D)u - L_1(x, t, D)u = f(x, t), \quad (1)$$

where  $x = (x_1, \dots, x_n)$ ;  $D$  is the differentiation operator with respect to  $x$ ;  $L_0(x, t, D)$  and  $L_1(x, t, D)$  are linear differential operators:  $L_0(x, t, D)$  is a homogeneous operator of order  $2p$ , while  $L_1(x, t, D)$  is an operator of order  $(2p-1)$ .

We shall assume that

$$\inf_{\substack{(x,t) \in Q \\ |\alpha|=1}} |\operatorname{Re} L_0(x, t, i\alpha)| = \delta_0 > 0, \quad (2)$$

$$|\alpha|^2 = \sum \alpha_i^2;$$

$Q$  is the domain of variation of  $(x, t)$ ;  $\delta_0$  is some number.

In the domain  $Q$ , bounded by a sufficiently smooth closed surface  $\Gamma$ , it is required to find a solution of equation (1) satisfying on  $\Gamma$  the following conditions (the Dirichlet problem):

$$u|_{\Gamma} = \frac{\partial u}{\partial n} \Big|_{\Gamma} = \dots = \frac{\partial^{p-1} u}{\partial n^{p-1}} \Big|_{\Gamma} = 0, \quad (3)$$

where  $n$  is the interior normal lying in the plane  $t = \text{const}$  to the surface of intersection of this plane with the surface  $\Gamma$ .

We note that the class of equations (1) under consideration includes not only parabolic equations, but also "backward-parabolic" equations, since in formula (2) the sign of  $\operatorname{Re} L_0(x, t, i\alpha)$  is not fixed. For simplicity in formulating the

results of item I, we shall assume that the planes  $t = \text{const}$  touch the surface  $\Gamma$  only at two points  $B = (x^B, t^B)$  and  $H = (x^H, t^H)$  ( "upper" and "lower" ); at the remaining points of  $\Gamma$  (points of the "lateral surface" ) the tangent plane makes with the axis  $Ot$  an angle  $\gamma \neq \pi/2$ . Let

$$t = t^H + \varphi_H(x_1 - x_1^H, \dots, x_n - x_n^H), \quad t = t^B + \varphi_B(x_1 - x_1^B, \dots, x_n - x_n^B) \quad (4)$$

be the local equations of  $\Gamma$  in neighborhoods of the lower and upper points, respectively. Obviously,  $\varphi_H(x - x^H) \geq 0$ , while  $\varphi_B(x - x^B) \leq 0$  for sufficiently small  $|x - x^H|$  and  $|x - x^B|$ .

**Theorem 1.** For any function  $f(x, t) \in \mathcal{L}_2(Q)$ , the Dirichlet problem (1), (3) is uniquely solvable in the space

$$\mathcal{H} = W_{t, x_1, \dots, x_n, 2}^{(1, 2p, \dots, 2p)}(Q) \cap \overset{0}{W}_{t, x_1, \dots, x_n, 2}^{(0, p, \dots, p)}(Q),$$

if  $\varphi_H(x) = O(|x|^{2p})$  and  $\varphi_B(x) = O(|x|^{2p})$  as  $|x| \rightarrow 0$ .

For the solution of this problem the estimate

$$\|u\|_H \leq C \|f\|_{L_2(Q)},$$

is valid, where the constant  $C$  depends only on the boundary of the domain  $Q$  and on the coefficients of equation (1).

**Theorem 2.** If in condition (2)  $\text{Re } L_0(x, t, i\alpha) < 0$  (parabolicity), then in Theorem 1 the restriction on the order of  $\varphi_n(x)$  may be dropped; if  $\text{Re } L_0(x, t, i\alpha) > 0$  (inverse parabolicity), then the restriction on the order of  $\varphi_v(x)$  may be dropped.

The space  $W_{t, x_1, \dots, x_n, 2}^{1, 2p, \dots, p}(Q)$  is the space of Slobodetskii <sup>(1)</sup>, and the space

$$\overset{0}{W}_{t, x_1, \dots, x_n, 2}^{(0, p, \dots, p)}(Q)$$

is the Hilbert space obtained by completing the set  $C_0^\infty(Q)$  (the set of infinitely differentiable functions in  $Q$  with compact support) with respect to the norm

$$\|u\|_{W_{t, x_1, \dots, x_n, 2}^{(0, p, \dots, p)}}^2 = \int_Q \dots \int_Q \left( u^2 + \sum_{s_1 + \dots + s_n = p} |D_{x_1}^{s_1} \dots D_{x_n}^{s_n} u|^2 \right) dx dt.$$

Let us note that for the heat equation ( $p = 1$ ) the conditions on the orders of  $\varphi_n(x)$  and  $\varphi_v(x)$  can be weakened by virtue of Petrovskii's theorem <sup>(2)</sup>; namely, one may require that for sufficiently small  $|x|$ ,  $\varphi_n(x) \geq \varphi_0(x)$ ,  $\varphi_v(x) \leq -\varphi_0(x)$ , where  $\varphi_0(x)$  is the solution of the equation  $|x|^2 = 4\varphi_0 \ln |\ln \varphi_0|$ .

The proof of Theorems 1 and 2 is based on the following auxiliary propositions:

**Lemma 1.** Let

$$\Omega = (|x - x^n| \leq 1, \quad t^n + \varphi_n(x - x^n) \leq t \leq t^n + \varphi_n(x - x^n) + 1), \quad (5)$$

$v(x, t) \in L_2(\Omega)$ ,  $v_t(x, t) \in L_2(\Omega)$ ,  $v(x, t)|_{t=t^n+\varphi_n(x-x^n)} = 0$ . Then for any function  $\varphi_n(x - x^n) \geq 0$  for  $|x - x^n| \leq 1$  we have

$$\iint_{\Omega} \frac{v^2(x, t)}{t^2} dx dt \leq 4 \iint_{\Omega} (v_t(x, t))^2 dx dt.$$

**Lemma 2.** For every  $\varepsilon > 0$  there exists  $C(\varepsilon) > 0$  such that all functions  $v(x, t)$  described in Lemma 1 and having  $v_{x_i} \in L_2(\Omega)$ ,  $i = 1, \dots, n$ , satisfy the inequality

$$\begin{aligned} & \iint_{\Omega} \frac{v^2(x, t)}{t^2} dx dt \leq \\ & \leq \varepsilon \iint_{\Omega} (v_t(x, t))^2 dx dt + C(\varepsilon) \left( \iint_{\Omega} (v(x, t))^2 dx dt + \iint_{\Omega} |\nabla u|^2 dx dt \right), \end{aligned}$$

provided only that  $\varphi_n(x - x^n)$  in the domain  $|x - x^n| \leq 1$  vanishes only at a finite number of points ( $C(\varepsilon)$  does not depend on the choice of the function  $v(x, t)$ ).

**Lemma 3.** Let a function  $u(x, t) \in \mathcal{H}(\Omega)$  be given in the domain  $\Omega$  (5). Then it can be continued into the domain

$$\Omega_1 = (|x - x^n| \leq 1, \quad 0 \leq t \leq t^n + \varphi_n(x - x^n)) \quad (6)$$

so that the newly obtained function in  $\Omega_1 + \Omega$  belongs to  $\mathcal{H}(\Omega_1 + \Omega)$ . Moreover, the following estimates hold:

$$\iint_{\Omega_1} |D^{2p-s} u|^2 dx dt \leq \frac{C_s}{m^{2s-1}} \sum_{r=1}^{2p-s} \iint_{\Omega} \frac{|D^r u|^2}{\psi_n^{2(2p-s)-2r}} \left( \frac{|x|}{\psi_n} \right)^{4p-2s-1} dx dt, \quad (7)$$

$s = 0, 1, \dots, 2p - 1$ ,

$$\iint_{\Omega_1} |u|^2 dx dt \leq \frac{C_{2p}}{m^{4p-1}} \iint_{\Omega^\varepsilon} |u|^2 \left( \frac{\psi_H}{|x|} \right) dx dt, \quad (8)$$

where  $C_k$ ,  $k = 0, \dots, 2p$  are certain constants;  $m$  is an arbitrary positive constant;  $\psi_H$  is the solution with respect to  $\rho$  of the equation  $t - t^H = \varphi_H(\rho\omega_1, \dots, \rho\omega_n)$ , with  $\omega_1^2 + \dots + \omega_n^2 = 1$ .

Lemma 1 is a generalization of Theorem 254 of the book <sup>(3)</sup> to the multidimensional case and can be proved by a similar method. In the proof of Lemma 2 some results of Khinchin and Marcinkiewicz on the theory of trigonometric series are used.

Lemma 3 is proved with the aid of a special adaptation of the Whitney-Hestenes method <sup>(4)</sup> for extending functions across a curvilinear boundary of a domain in the case when straightening the boundary is undesirable (here this is connected with the nonequivalence of the variables  $t$  and  $x_1, \dots, x_n$ ).

Lemmas 1, 2, 3 are also valid for a neighborhood of the point  $B = (x^B, t^B)$ ; in this case the domains  $\Omega$  and  $\Omega_1$  must be situated below the plane  $t = t^B$ .

The proof of Theorem 1 is based on Theorem 3 on an a priori estimate for a smooth solution of equation (1) under condition (3).

**Theorem 3.** If problem (1), (3) has a sufficiently smooth solution  $u(x, t)$  and the conditions of Theorem 1 on the orders  $\varphi_H(x)$  and  $\varphi_B(x)$  as  $|x| \rightarrow 0$  are satisfied, then

$$\|u\|_{\mathcal{H}(Q)} \leq C\|f\|_{\mathcal{L}^2(Q)} + C_1\|u\|_{\mathcal{L}^2(Q)}. \quad (9)$$

Let us illustrate the proof of Theorem 3 on the example of the one-dimensional heat equation

$$\mathcal{L}u \equiv u_t - (a(x, t)u_x)_x = f(x, t). \quad (10)$$

We multiply both sides of (10) by  $u_t$  and integrate over the domain  $Q$ . After integration by parts we obtain

$$\|u_t\|_{\mathcal{L}^2(Q)}^2 - \frac{1}{2} \iint_Q a_t u_x^2 dx dt + \frac{1}{2} \int_{\Gamma_1 - \Gamma_2} a u_x^2 dx = (f, u_t)_{\mathcal{L}^2(Q)}, \quad (11)$$

where  $\Gamma_1$  and  $\Gamma_2$  are respectively the upper and lower parts of the contour  $\Gamma$  (the  $t$ -axis is directed upward). From (11), for any  $\varepsilon_1 > 0$  it follows that

$$\|u_t\|_{\mathcal{L}^2(Q)}^2 \leq \varepsilon_1 (\|u_x\|_{\mathcal{L}^4(Q)}^2 + \|u_t\|_{\mathcal{L}^2(Q)}^2) + \frac{A}{2} \int_{\Gamma_1 + \Gamma_2} u_x^2 dx + C_1(\varepsilon_1)\|f\|^2 + C_2(\varepsilon_1)\|u\|^2. \quad (12)$$

Splitting  $\Gamma_2$  by the point  $H = (0, 0)$  into two parts  $\Gamma_{21}$  and  $\Gamma_{22}$  with equations  $x = \psi_1(t)$  and  $x = \psi_2(t)$ , respectively ( $\psi_i(t) = O(\sqrt{t})$ ,  $\psi_i'(t) = O(1/\sqrt{t})$ ) as

$t \rightarrow 0$ ;  $0 \leq \psi_1(t) \leq b_1$ ,  $-b_2 \leq \psi_2(t) \leq 0$ ,  $\psi_1(a_1) = b_1$ ,  $\psi_2(a_2) = -b_2$ ), we obtain

$$\int_{\Gamma_2} u_x^2 dx \leq C \left( \int_0^{a_1} \frac{u_x^2}{\sqrt{t}} \Big|_{\Gamma_{21}} dt + \int_0^{a_2} \frac{u_x^2}{\sqrt{t}} \Big|_{\Gamma_{22}} dt \right) = C \iint_{\Omega_{11} + \Omega_{12}} \frac{\partial}{\partial x} (u_x^2) \frac{dx dt}{\sqrt{t}}, \quad (13)$$

where  $\Omega_{11}$  and  $\Omega_{12}$  are the right and left parts of the domain  $\Omega_1$  of Lemma 3. (We note that the extension of the function  $u(x, t)$  (Lemma 3) to the domain  $\Omega_{11} + \Omega_{12}$  may be assumed to be identically zero, together with a sufficient number of derivatives, for  $x = b_1$  and  $x = -b_2$ .) From (13), with the aid of (7), (8), and Lemma 2, for any  $\varepsilon_2 > 0$  we obtain

$$\begin{aligned} \int_{\Gamma_2} u_x^2 dx &\leq 2C \iint_{\Omega} \frac{u_{xx} u_x}{\sqrt{t}} dx dt \leq \varepsilon_2 \|u_{xx}\|_{\mathcal{L}^2(Q)}^2 + C_3(\varepsilon_2) \iint_{\Omega} \frac{u^2}{t^2} dx dt \leq \\ &\leq \varepsilon_2 \|u_{xx}\|_{\mathcal{L}^2(Q)}^2 + \varepsilon C_3(\varepsilon_2) \|u_t\|_{\mathcal{L}^2(Q)}^2 + C(\varepsilon) C_3(\varepsilon_2) (\|u\|_{\mathcal{L}^2(Q)}^2 + \|u_x\|^2). \end{aligned}$$

Estimating similarly the integral over  $\Gamma_1$ , from (12) and equation (10), after choosing sufficiently small  $\varepsilon_1, \varepsilon_2$ , and then  $\varepsilon$ , we obtain the required estimate (9). In the multidimensional case the arguments remain essentially similar to those given above, but in the appropriate place one must use the a priori estimates for elliptic operators from work <sup>5</sup> for an equation of the 2nd order and from <sup>6</sup> for an equation of arbitrary order.

The proof of existence and uniqueness of the solution of the Dirichlet problem (1), (3) is carried out according to the following plan: first one constructs a generalized solution from

${}^0W_{(t, x_1, \dots, x_n, 2)}^{(0, p, \dots, p)}(Q)$  (the construction of this solution is carried out by a method analogous to Vishik's method <sup>7</sup> for solving a mixed problem), then its smoothness is proved under the corresponding smoothness of the right-hand side  $f(x, t)$ . In doing this, to prove smoothness inside  $Q$  one should use the results of <sup>8</sup> or <sup>9</sup>, in a neighborhood of nonhorizontal parts of the boundary  $\Gamma$ —the results of <sup>9</sup>, and in neighborhoods of the points  $H$  and  $B$ —Lemmas 1 and 2.

After this, uniqueness of the smooth solution is proved and, thanks to Theorem 3 on the a priori estimate, by means of passage to the limit in the integral identity defining the generalized solution, Theorem 1 is finally proved.

- II. Let equation (1) be parabolic (sign  $\text{Re } L_0(x, t, i\alpha) = 1$  in (2)), and let the boundary  $\Gamma$  of the domain  $Q$  consist of three parts: in the upper and lower parts, of pieces  $T_v$  and  $T_n$  of planes (the points  $B$  and  $H$  of the preceding item are replaced by the planes  $T_v : t = t^B$  and  $T_n : t = t^H$ ) and of the lateral surface  $\Gamma_b$  ( $\Gamma = T_v + T_n + \Gamma_b$ ); the part  $T_n$  may be absent

(Theorem 2).  $\Gamma_b$  is assumed to be such that in some neighborhood  $U_0$  of any of its points  $(x_0, t_0)$  the equation of  $\Gamma_b$  can be represented in a form uniquely solved with respect to one of  $x = (x_1, \dots, x_n)$ . It is convenient to introduce in  $U_0$  local coordinates  $(\xi, \tau)$ ,  $\xi = (\xi_1, \dots, \xi_n)$ , so that the origin of coordinates lies at the point  $(x_0, t_0)$ ,  $\xi_1$  changes in the direction of  $n$ ,  $\tau$  in the direction of  $t$ , and the remaining  $\xi_2, \dots, \xi_n$  in the plane tangent to  $\Gamma_b$  at the point  $(x_0, t_0)$ .

We shall say that  $\Gamma_b$  at  $(x_0, t_0)$  satisfies the Lipschitz condition of order  $\alpha$ ,  $0 < \alpha \leq 1$ , if the local equation of  $\Gamma_b$  in  $U_0$  has the form

$$\tau = C_1 |\xi_1|^{1/\alpha} + o(\xi_1^{1/\alpha}), \quad C_1 \neq 0.$$

Consider the first mixed problem for equation (1), i.e., the problem of finding such a solution of (1) in  $Q$  that

$$u|_{\Gamma_b} = \dots = \frac{\partial^{p-1} u}{\partial n^{p-1}} \Big|_{\Gamma_b} = 0, \quad u|_{T_n} = 0 \quad (14)$$

(the condition on  $T_n$  is absent if  $T_n$  degenerates into the point  $H$ ).

**Theorem 4.** *Problem (1)–(14) is uniquely solvable for any  $f(x, t) \in \mathcal{L}_2(Q)$  in the space  $\mathcal{H}(Q)$  (Theorem 1), if  $\Gamma_b$  satisfies the Lipschitz condition of order  $\gamma$ ,  $\gamma \geq 1/2p$ , at each of its points.*

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*Note: Figure translations are in progress. See original paper for figures.*

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