



Soviet-era science, translated into English

MATHEMATICS

1961

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Abstract

Full Text

MATHEMATICS

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TOPOLOGICAL AND ASYMPTOTIC EQUIVALENCE OF SYSTEMS OF DIFFERENTIAL EQUATIONS

(Presented by Academician P. S. Aleksandrov on 20 V 1961)

In the work ⁽¹⁾ the topological equivalence of the systems

$$\frac{dx}{dt} = Ax + f(x) \tag{1}$$

$$\frac{dy}{dt} = Ay, \tag{2}$$

was established, where A is a constant square matrix of order n , having no eigenvalues with zero real part; x, y , and $f(x)$ are n -dimensional vectors, and $f(x)$ satisfies, in a neighborhood of the singular point $x = 0$, a Lipschitz condition with a sufficiently small constant. More precisely: it was proved that there exists a homeomorphism $y = \Phi(x)$, mapping a certain neighborhood G_1 of the point $x = 0$ onto a certain domain G_2 and transforming solutions of one system into solutions of the other. Moreover, the corresponding solutions turn out simultaneously to be either O^+ -curves, or O^- -curves, or saddle curves.

The finer properties of the solutions of system (2), under the assumptions made concerning $f(x)$, are, generally speaking, not inherited by system (1), and the trajectories corresponding by virtue of Φ may have different asymptotics.

However, if near the origin the vector $f(x)$ is subject to requirements more stringent than the Lipschitz condition, namely, if for all x' and x'' small in norm the inequality *

$$|f(x') - f(x'')| \leq g(r) |x' - x''|, \tag{3}$$

holds, where $r = \max\{|x'|, |x''|\}$, and as $r \rightarrow 0$ $g(r) \rightarrow 0$ sufficiently rapidly, then, as is known ⁽²⁻⁶⁾, the O -curves of systems (1) and (2) are asymptotically equivalent. But even in this case the homeomorphism Φ does not guarantee similarity in the asymptotic behavior of the corresponding trajectories.

In the present work conditions are stated under which there exists a homeomorphism Φ^* free of this drawback. Before giving the precise formulation of the theorem, let us recall the definitions.

The **characteristic exponent**, or simply the **exponent**, of a vector $x(t)$ is

$$\overline{\lim}_{t \rightarrow +\infty} \frac{1}{t} \ln |x(t)|.$$

The **minus-exponent** of a vector $x(t)$ is

$$\overline{\lim}_{t \rightarrow -\infty} \frac{1}{t} \ln |x(t)|.$$

* Here $|x| = (x, x)^{1/2}$ is the norm of the vector x . The scalar product is understood to be equal to the sum of the products of the corresponding coordinates.

It is clear that if the exponent (or minus-exponent) is negative, then $x(t)$ tends to 0 as $t \rightarrow +\infty$ (or as $t \rightarrow -\infty$).

Two vectors $x(t)$ and $y(t)$ are called **analogous** as $t \rightarrow +\infty$ (as $t \rightarrow -\infty$) if the ratio of their norms tends, as $t \rightarrow +\infty$ (as $t \rightarrow -\infty$), to unity, while the difference between their direction cosines tends to zero.

The **deviation** of x from y , or simply the **deviation**, is the ratio

$$\frac{|x(t) - y(t)|}{|y(t)|}.$$

It is quite clear that the analogy of $x(t)$ and $y(t)$ is equivalent to the fact that their deviation tends to zero as $t \rightarrow \infty$, or to the fact that

$$x(t) = y(t) + z(t), \quad (4)$$

where $|z(t)| = o(|y(t)|)$ as $t \rightarrow +\infty$ (or as $t \rightarrow -\infty$).

Two systems of differential equations are called **homeomorphic in the domains** G_1 and G_2 if there exists a topological correspondence between G_1 and G_2 under which the trajectories of the first system lying in G_1 go over into trajectories of the second system, and conversely.

Theorem. *If:*

- a) *the matrix A has no eigenvalues with zero real parts;*
- b) *$f(0) = 0$;*
- c) *in some neighborhood of the point $x = 0$, $f(x)$ satisfies condition (3), and for $0 < r \leq r_0 < 1$*

$$g(r) \leq L_0 \frac{r^\alpha}{|\ln r|^{(2+\alpha)m+1+\beta+\eta}}, \quad (5)$$

where $m+1$ is the number equal to the order of the maximal “box” in the Jordan form of A , and $L_0 \geq 0$, $\alpha \geq 0$, $\beta \geq 0$, $\eta > 0$ are certain constants, then:

- 1) systems (1) and (2) are homeomorphic in certain domains containing the origin;
- 2) the corresponding O -curves are analogous;
- 3) the deviation of the corresponding O^+ -curves as $t \rightarrow +\infty$ is $O(e^{\alpha\omega t} t^{-(m+\beta+\eta)})$, where ω is their exponent; for the corresponding O^- -curves the deviation as $t \rightarrow -\infty$ is $O(e^{\alpha\omega|t|} |t|^{-(m+\beta+\eta)})$, where ω is their minus-exponent.

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Received
16 V 1961

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