

# ON THE EXISTENCE OF PERIODIC SOLUTIONS IN CERTAIN NONLINEAR SYSTEMS

Consider the system of differential equations

1961

SovietRxiv

---

View the original and related papers at <https://sovietrxiv.org/items/ru-196101.12221>

Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.

**Abstract**

**Full Text**

**MATHEMATICS**

**V. A. PLISS**

**ON THE EXISTENCE OF PERIODIC SOLUTIONS IN CERTAIN NONLINEAR SYSTEMS**

*(Presented by Academician V. I. Smirnov on 11 XI 1960)*

Consider the system of differential equations

$$\frac{dx}{dt} = Ax + F(x, t), \tag{1}$$

where  $x$  and  $F(x, t)$  are real  $n$ -dimensional vectors with components  $x_1, x_2, \dots, x_n$  and  $F_1(x, t), \dots, F_n(x, t)$ , respectively;  $A = \{a_{ij}\}$  is a real constant square matrix of order  $n$ . As to the function  $F(x, t)$ , it is assumed that it is continuous, has period  $2\pi$  in the variable  $t$ , and satisfies the uniqueness condition for solutions for all  $x, t$ .

The purpose of the present note is to establish sufficient conditions for the existence of a  $2\pi$ -periodic solution of system (1). M. A. Krasnosel'skii studied an analogous problem <sup>(1,2)</sup>. The conditions given below for the existence of  $2\pi$ -periodic solutions differ from those found by M. A. Krasnosel'skii in that, under these conditions, the matrix  $A$  may have imaginary eigenvalues.

Introduce the following notation. Let  $\xi$  be an  $n$ -dimensional vector with components  $\xi_1, \dots, \xi_n$ ; let  $B = \{b_{ij}\}$  be a square matrix of order  $n$ . Put

$$\|\xi\| = \sum_{i=1}^n |\xi_i|, \quad \|B\| = \sum_{i,j=1}^n |b_{ij}|.$$

**Theorem.** *If the matrix  $A$  has no eigenvalues of the form  $ki$  ( $k$  a natural number or zero,  $i$  the imaginary unit), and if the function  $F(x, t)$ , for sufficiently large  $\|x\|$ , satisfies the inequality*

$$\|F(x, t)\| < L\|x\|, \tag{2}$$

*where the positive constant  $L$  is sufficiently small, then system (1) has at least one  $2\pi$ -periodic solution.*

**Proof.** Denote by  $x(t, x^0, t_0)$  the solution of system (1) with initial data  $t_0, x^{(0)}$ . From estimates (2) it follows <sup>(3,4)</sup> that all solutions of system (1) can be continued for all times from  $-\infty$  to  $+\infty$ . Associate with the point  $x^{(0)}$  the point

$x(2\pi, x^{(0)}, 0)$ . Thus we obtain a topological transformation  $T$  of the space  $\{x\}$  into itself. Along with this transformation, consider the vector transformation  $v = T(x) - x$  with components  $v_1, v_2, \dots, v_n$ . It is clear that the fixed points of this transformation or, what is the same, the singular points of the field  $v$ , are the initial data of  $2\pi$ -periodic solutions, and conversely.

Now consider the linear system

$$\frac{dx}{dt} = Ax. \quad (3)$$

Without loss of generality, we may assume that the matrix  $A$  has canonical structure. Define, for system (3), a transformation  $T_0$  of the space  $\{x\}$  into itself, analogous to the transformation  $T$  for system (1). Denote by  $w = \{w_1, \dots, w_n\}$  the vector of the transformation  $T_0$ , i.e.  $w = T_0(x) - x$ . Let the matrix  $A$  have the following characteristic roots:  $\lambda_1 \pm i\mu_1, \lambda_2 \pm i\mu_2, \dots, \lambda_s \pm i\mu_s, \nu_1, \dots, \nu_{n-2s}$ , among which some may be equal. It is clear that

$$\frac{D(w_1, \dots, w_n)}{D(x_1, \dots, x_n)} = \begin{vmatrix} e^{2\pi\lambda_1} \cos 2\pi\mu_1 - 1 & -e^{2\pi\lambda_1} \sin 2\pi\mu_1 & 0 \dots 0 \\ e^{2\pi\lambda_1} \sin 2\pi\mu_1 & e^{2\pi\lambda_1} \cos 2\pi\mu_1 - 1 & 0 \dots 0 \\ \dots & \dots & \dots \\ \dots & \dots & \dots e^{2\pi\nu_{n-2s}} - 1 \end{vmatrix},$$

and by Laplace's theorem we have

$$\frac{D(w_1, \dots, w_n)}{D(x_1, \dots, x_n)} = \prod_{m=1}^s (1 - 2e^{2\pi\lambda_m} \cos 2\pi\mu_m + e^{4\pi\lambda_m}) \prod_{m=1}^{n-2s} (e^{2\pi\nu_m} - 1).$$

By virtue of the condition of the theorem that in the case  $\lambda_m = 0$  one has  $\mu_m \neq k$  ( $k$  is a natural number or zero), we have

$$\frac{D(w_1, \dots, w_n)}{D(x_1, \dots, x_n)} \neq 0.$$

This proves (see, for example, (5)) that the index of the point  $x_1 = \dots = x_n = 0$  as a singular point of the field  $w(x)$  is equal to  $\pm 1$ . Moreover, from the inequality

$$D(w_1, \dots, w_n)/D(x_1, \dots, x_n) \neq 0$$

it follows that there exists a constant  $K > 0$  such that

$$\|w(x)\| \geq K\|x\|. \quad (4)$$

Let us now estimate the difference  $\|v(x^{(0)}) - w(x^{(0)})\|$  for sufficiently large values of  $\|x^{(0)}\|$ . It is clear that

$$v(x^{(0)}) - w(x^{(0)}) = x(2\pi, x^{(0)}, 0) - y(2\pi, x^{(0)}, 0), \quad (5)$$

where  $y(t, x^{(0)}, t_0)$  denotes the solution of system (3) with initial data  $t_0, x^{(0)}$ . Let  $Y(t)$  be the solution of the matrix equation

$$dY/dt = AY \quad (6)$$

such that  $Y(0) = I$ .

It is known (see, for example, (6)) that then the solution  $x(t, x^{(0)}, 0)$  of system (1) satisfies the integral equation

$$x(t, x^{(0)}, 0) = y(t, x^{(0)}, 0) + \int_0^t Y(t - \tau) F(x, \tau) d\tau. \quad (7)$$

Put

$$c_1 = \sup_{0 \leq t \leq 2\pi} \|y(t, x^{(0)}, 0)\|;$$

since  $y(t, x^{(0)}, 0)$  is a solution of the linear system (3), there exists a positive constant  $M$  such that  $c_1 \leq M\|x^{(0)}\|$ . Let, moreover,

$$c_2 = \sup_{0 \leq t \leq 2\pi} \|Y(t)\|.$$

Then from equality (7) we obtain

$$\|x(t, x^{(0)}, 0)\| \leq c_1 + c_2 \int_0^t \|F(x(\tau, x^{(0)}, 0), \tau)\| d\tau \quad \text{for } 0 \leq t \leq 2\pi.$$

Assuming that  $\|x^{(0)}\|$  is sufficiently large, from condition (2) we obtain

$$\|x(t, x^{(0)}, 0)\| < c_1 + c_2 L \int_0^t \|x(\tau, x^{(0)}, 0)\| d\tau \quad \text{for } 0 \leq t \leq 2\pi. \quad (8)$$

Hence, by a well-known lemma (see, for example, (6, 7)), we find

$$\|x(t, x^{(0)}, 0)\| < c_1 e^{c_2 L t} \quad (0 \leq t \leq 2\pi). \quad (9)$$

On the other hand, from equality (7) there follows the estimate

$$\|x(t, x^{(0)}, 0) - y(t, x^{(0)}, 0)\| \leq c_2 \int_0^t \|F(x, \tau)\| d\tau \quad (0 \leq t \leq 2\pi),$$

and hence, for sufficiently large  $\|x^{(0)}\|$ , taking into account (2), (9), we obtain

$$\|x(t, x^{(0)}, 0) - y(t, x^{(0)}, 0)\| < c_2 L c_1 \int_0^t e^{c_2 L t} dt = c_1 (e^{c_2 L t} - 1).$$

Hence and from (5) we conclude, in view of  $c_1 \leq M\|x^{(0)}\|$ ,

$$\|v(x^{(0)}) - w(x^{(0)})\| < M(e^{2\pi c_2 L} - 1)\|x^{(0)}\| \quad (10)$$

for sufficiently large  $\|x^{(0)}\|$ .

Let now  $R$  be a sphere of sufficiently large radius with center at the origin. We shall take the constant  $L$  so small that the inequality

$$K \geq M(e^{2\pi c_2 L} - 1) \quad (11)$$

is satisfied.

Then from estimates (4) and (10) it follows that at no point of the sphere  $R$  are the vectors  $v$  and  $w$  oppositely directed, and, moreover,  $v$  does not vanish at any point of the sphere  $R$ . It is then clear that the indices of the sphere  $R$  in the fields  $w$  and  $v$  coincide. We have already proved that the index of the point  $x_1 = \dots = x_n = 0$ , as a singular point of the field  $w(x)$ , is equal to  $\pm 1$ . But the sphere  $R$ , by virtue of inequality (4), contains no singular points of the field  $w$  other than  $x_1 = \dots = x_n = 0$ , and therefore its index in the field  $w$  is equal to  $\pm 1$ . Consequently, the index of the sphere  $R$  in the field  $v$  is also equal to  $\pm 1$ , and this means that the sphere  $R$  contains at least one singular point of the field  $v$ . Thus, system (1) has at least one  $2\pi$ -periodic solution. The theorem is proved.

Leningrad State University  
named after A. A. Zhdanov

Received  
28 X 1960

## References

1. M. A. Krasnosel' skii, DAN, **111**, No. 2 (1956).
2. M. A. Krasnosel' skii, DAN, **123**, No. 2 (1958).

3. N. P. Erugin, *Applied Mathematics and Mechanics*, **15**, issue 1 (1951).
4. A. Wintner, *Am. J. Math.*, **65**, No. 2, 277 (1945).
5. P. S. Aleksandrov, *Combinatorial Topology*, Moscow-Leningrad, 1947.
6. R. Bellman, *The Theory of Stability of Solutions of Differential Equations*, II, 1954.
7. V. V. Nemytskii, V. V. Stepanov, *Qualitative Theory of Differential Equations*, Moscow-Leningrad, 1949.

*Note: Figure translations are in progress. See original paper for figures.*

*Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.*