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**Abstract**

**Full Text**

*MATHEMATICS*

A. Cifligu, V. N. Maslennikova, and L. I. Kamynin

## ON THE APPLICABILITY OF THE FOURIER METHOD TO THE SOLUTION OF THE FIRST BOUNDARY-VALUE PROBLEM FOR A QUASILINEAR PARABOLIC EQUATION

*(Presented by Academician S. L. Sobolev on 10 IX 1959)*

In this note we consider a parabolic equation with a nonlinearity of the form

$$\frac{\partial u}{\partial t} = \frac{\partial}{\partial x} \left[ p(x) \frac{\partial u}{\partial x} \right] - q(x)u + \mu f(x, t, u(x, t)). \quad (1)$$

We assume that on the interval  $[0, l]$  the function  $p(x)$  is twice continuously differentiable, and  $q(x)$  is continuously differentiable, with  $p(x) \geq p_0 > 0$ . It is assumed that  $f(x, t, u)$  is continuous together with its derivatives  $\partial f / \partial x$ ,  $\partial f / \partial u$ ,  $\partial^2 f / \partial x^2$ ,  $\partial^2 f / \partial x \partial u$ , and  $\partial^2 f / \partial u^2$  with respect to all its arguments in the domain ( $0 \leq x \leq l$ ,  $0 \leq t \leq T$ ,  $|u| < \infty$ ); moreover, for  $0 \leq x \leq l$ ,  $0 \leq t \leq T$ , and  $|u| \leq K$ , the inequalities

$$|\partial^k f / \partial x^m \partial u^n| \leq F(T)\varphi(K), \quad k = 0, 1, 2, \quad m + n = k, \quad (2)$$

hold, where  $F(T)$  and  $\varphi(K)$  are nonnegative, nondecreasing functions of their arguments, defined for all positive  $T$  and  $K$  and finite for finite  $T$  and  $K$ . In addition, let  $f(x, t, u)$  satisfy

$$f(0, t, u) = f(l, t, u) = 0. \quad (3)$$

The first boundary-value problem for a non-self-adjoint parabolic equation with coefficients depending on  $u$  has been considered by a number of authors<sup>(5-8)</sup>. The purpose of our note is to apply the Fourier method and Schauder's method to the solution of the problem posed. As a result of applying the Fourier method, the problem is reduced to an infinite system of nonlinear integral equations, whose solution is obtained by Schauder's method (the fixed-point method). Two definitions of generalized solutions are introduced; to prove their existence and uniqueness, fewer restrictions on the initial data are required than for classical solutions.

First consider the classical formulation of the first boundary-value problem for equation (1), consisting in the determination of a solution  $u(x, t)$ , continuous together with the derivatives  $\partial u/\partial x$ ,  $\partial u/\partial t$ ,  $\partial^2 u/\partial x^2$  in the closed domain  $G$  ( $0 \leq x \leq l$ ,  $0 \leq t \leq T$ ), satisfying the initial condition

$$u(x, 0) = g(x) \tag{4}$$

and the boundary conditions

$$u(0, t) = u(l, t) = 0. \tag{5}$$

By the Fourier method, the solution of the first boundary-value problem (1), (4), (5) is sought in the form

$$u(x, t) = \sum_{n=1}^{\infty} A_n(t) X_n(x), \tag{6}$$

which reduces the problem (1), (4), (5) to the study of the infinite system of nonlinear integral equations

$$A_n(t) = c_n e^{-\lambda_n t} + \mu \int_0^t \int_0^l e^{-\lambda_n(t-\tau)} f \left( x, \tau, \sum_{k=1}^{\infty} A_k(\tau) X_k(x) \right) X_n(x) d\tau dx, \tag{7}$$

$n = 1, 2, \dots$ , where  $X_n(x)$  is a complete orthonormal system of eigenfunctions of the Sturm–Liouville problem

$$L(X) + \lambda X = 0; \tag{8}$$

$$X(0) = X(l) = 0; \tag{9}$$

$$L(X) \equiv \frac{d}{dx} \left[ p(x) \frac{dX(x)}{dx} \right] - q(x)X(x); \tag{10}$$

$$c_n = \int_0^l g(x) X_n(x) dx. \tag{11}$$

In what follows we use the well-known <sup>(1)</sup> properties of the eigenfunctions  $X_n(x)$  and eigenvalues  $\lambda_n$  of the Sturm–Liouville problem (8), (9).

**Lemma 1.** If  $f(x, t, u)$  satisfies (2), (3), and  $u(x, t)$  is measurable in  $t$  and continuous, together with  $\partial u/\partial x$ , in  $x$ , and in  $G$  satisfies the inequalities

$$|u(x, t)| \leq K; \quad (12)$$

$$|\partial u(x, t)/\partial x| \leq K; \quad (13)$$

$$|\partial u(x + \Delta x, t)/\partial x - \partial u(x, t)/\partial x| \leq K|\Delta x|, \quad (14)$$

then the Fourier coefficients of  $f(x, t, u(x, t))$  with respect to the system  $X_n(x)$  satisfy the inequality

$$|b_n(t)| \leq D/\lambda_n, \quad (15)$$

where the constant  $D$  depends on  $p(x)$ ,  $p'(x)$ ,  $q(x)$ ,  $K$ ,  $T$ .

The investigation of system (7) is carried out according to the scheme of the work <sup>(2)</sup> of one of the authors as follows. Consider the nonmetrizable complete linear topological space  $C^{(1)}$  of functions  $u(x, t)$  satisfying (5), continuous in  $x$  and  $t$  in the domain  $G$ , having partial derivatives  $\partial u/\partial x$ , continuous in  $x$  and measurable in  $t$ , with topology given by the operation of passage to the limit

$$\lim_{k \rightarrow \infty} \sup_{(x, t) \in G} |u(x, t) - u_k(x, t)| = 0, \quad (16)$$

$$\lim_{k \rightarrow \infty} \sup_{0 \leq x \leq l} |\partial u(x, t)/\partial x - \partial u_k(x, t)/\partial x| = 0 \quad (17)$$

(for any fixed  $t$  from  $[0, T]$ ). In  $C^{(1)}$  consider the closed convex set  $C_k^{(1)}$  of elements of  $C^{(1)}$  satisfying (12), (13), and (14), where  $K$  is a constant. On  $C_k^{(1)}$  define a nonlinear operator  $A$  ( $v = Au$ ) in such a way that, if  $u \in C_k^{(1)}$  and is given with the aid of (6), then

$$v(x, t) = \sum_{n=1}^{\infty} B_n(t) X_n(x),$$

where  $B_n(t)$  is determined with the aid of  $u(x, t)$  from

$$B_n(t) = c_n e^{-\lambda_n t} + \mu \int_0^t \int_0^l e^{-\lambda_n(t-\tau)} f(x, \tau, u(x, \tau)) X_n(x) d\tau dx, \quad n = 1, 2, \dots$$

The range of values of the operator  $A$  then lies in  $C^{(1)}$ .

**Theorem 1.** For sufficiently small  $\mu$ , the operator  $A$  maps the convex set  $C_k^{(1)}$  in  $C^{(1)}$  into its compact part.

**Theorem 2.** If  $f(x, t, u)$  satisfies (2), (3), then, for  $\mu$  sufficiently small, there exists at least one invariant point of the mapping  $v = Au$ .

**Theorem 3.** The infinite system (7) has a unique solution  $A_n(t)$ ,  $n = 1, 2, \dots$ , in the class of continuous functions satisfying the conditions  $|A_n(t)| \leq Aa_n$ , where  $\sum_{n=1}^{\infty} a_n < \infty$ , if  $f(x, t, u)$  is continuous in  $x, t$ , and satisfies a Lipschitz condition in  $u$ .

**Theorem 4.** If  $p(x), q(x), f(x, t, u)$  satisfy the requirements formulated at the beginning of the note;  $g(x)$  is three times continuously differentiable and satisfies conditions (9) and  $L(g) = 0$  for  $x = 0$  and  $x = l$ , then, for sufficiently small  $\mu$ , there exists in  $G$  a unique classical solution of the first boundary-value problem (1), (4), (5), representable in the form (6).

**Remark.** Since we impose no restrictions on the character of the behavior of  $\partial f / \partial u$ , it is not surprising (see (3)) that the existence and uniqueness of the classical solution of the first boundary-value problem (1), (4), (5) have been proved for small  $\mu$ .

**Theorem 5** (correctness). Classical solutions  $u_1(x, t), u_2(x, t)$  of the first boundary-value problem for equation (1), satisfying (5), (12), and the initial conditions

$$u_1(x, 0) = g_1(x); \quad (18)$$

$$u_2(x, 0) = g_2(x) \quad (19)$$

for sufficiently small  $\mu$  will differ in modulus by an arbitrarily small amount in  $G$ , if  $|g_1(x) - g_2(x)|, |g_1'(x) - g_2'(x)|$  are sufficiently small for all  $x$  on  $[0, l]$ .

**Theorem 6.** If  $u_1(x, t), u_2(x, t)$  are classical solutions in  $G$  of the first boundary-value problem (1), (5), representable in the form (6), satisfying (12) and the initial conditions (19), (20), then for  $0 \leq t \leq T$

$$\int_0^l [u_1(x, t) - u_2(x, t)]^2 dx \leq A \int_0^l [g_1(x) - g_2(x)]^2 dx, \quad (20)$$

where the constant  $A$  depends only on  $K$  and  $T$ .

**Definition 1.** A continuous function  $u(x, t)$  will be called a **generalized solution of the first boundary-value problem** (1), (4), (5), if  $u(x, t)$  is the limit, uniformly convergent in  $G$  as  $m \rightarrow \infty$ , of a sequence of classical solutions

$u_m(x, t)$ , representable in the form (6), of equation (1) with boundary conditions (5) and initial data

$$u_m(x, 0) = g_m(x) \quad (21)$$

such that  $g_m(x)$  converges uniformly on  $[0, l]$  to  $g(x)$ .

**Theorem 7.** If  $g(x)$  satisfies (9) and has  $g'(x), g''(x)$ , with  $g''(x)$  square-integrable on  $[0, l]$ , then, for sufficiently small  $\mu$ , there exists at least one generalized solution  $u(x, t)$ , in the sense of Definition 1, of the first boundary-value problem (1), (4), (5).

To prove Theorem 7, one constructs a sequence of classical solutions  $u_m(x, t)$  of problem (1), (5), satisfying the initial conditions (21), where

$$g_m(x) = \sum_{k=1}^m c_k X_k(x)$$

( $c_k$  are the Fourier coefficients of  $g(x)$  (11)). The classical solutions are sought in the form

$$u_m(x, t) = \sum_{k=1}^m A_k^{(m)}(t) X_k(x),$$

which leads to the question of the existence of a solution of a finite system of nonlinear integral equations. A linear nonmetrizable complete topological space  $R$  of functions  $u(x, t)$ , defined on  $G$ , continuous in  $x$ , measurable in  $t$ , satisfying (5), is introduced, with topology specified by the limiting transition

$$\lim_{k \rightarrow \infty} \sup_{0 \leq x \leq l} |u(x, t) - u_k(x, t)| = 0.$$

In  $R$  one considers a compact convex set  $D$  of elements  $u$  from  $R$ , satisfying (12) and  $|u(x + \Delta x, t) - u(x, t)| \leq L|\Delta x|$ . On  $D$

one considers the operator  $A_m$  ( $v = A_m u$ ), defined as follows: if  $u \in D$ , then put

$$v(x, t) = \sum_{k=1}^m B_k^{(m)}(t) X_k(x),$$

where  $B_k^{(m)}(t)$  is determined with the help of  $u(x, t)$  from

$$B_k^{(m)}(t) = c_k e^{-\lambda_k t} + \mu \int_0^t \int_0^l e^{-\lambda_k(t-\tau)} f(x, \tau, u(x, \tau)) X_k(x) d\tau dx, \quad k = 1, 2, \dots, m.$$

The proof of the existence of a solution of the equation  $u = A_m u$  in the complete linear topological, but nonmetrizable, space  $R$  reduces to the application of Schauder's principle in a complete linear metric space by means of a device of A. N. Tikhonov (4).

**Theorem 8** (correctness of the generalized solution). *If there exists a generalized solution, in the sense of Definition 1, of the first boundary-value problem (1), (4), (5), then it is unique in the class of functions continuous on  $G$ , provided the initial function is continuous on  $[0, l]$  and satisfies (9).*

**Theorem 9.** *If  $u_1(x, t)$ ,  $u_2(x, t)$  are generalized, in the sense of Definition 1, solutions of the first boundary-value problem (1), (5) with initial data (18), (19), then, for  $\mu$  sufficiently small,  $|u_1(x, t) - u_2(x, t)|$  will be arbitrarily small in  $G$ , provided  $|g_1(x) - g_2(x)|$ ,  $|g'_1(x) - g'_2(x)|$  are sufficiently small for all  $x$  in  $[0, l]$ .*

**Definition 2.** A bounded function  $u(x, t)$ , for which

$$\int_0^l u^2(x, t) dx$$

is continuous with respect to  $t$  on  $[0, T]$ , will be called a **generalized solution in  $G$  of the first boundary-value problem** (1), (4), (5), if in  $G$  there exists a uniformly bounded sequence of classical solutions  $u_m(x, t)$ , representable in the form (6), of the first boundary-value problem (1), (5) with initial data (21) such that

$$\lim_{m \rightarrow \infty} \int_0^l [g(x) - g_m(x)]^2 dx = 0$$

and, uniformly in  $t$  ( $0 \leq t \leq T$ ),

$$\lim_{m \rightarrow \infty} \sup_{0 \leq t \leq T} \int_0^l [u(x, t) - u_m(x, t)]^2 dx = 0.$$

**Theorem 10.** *If there exists a generalized, in the sense of Definition 2, solution  $u(x, t)$  in  $G$  of the first boundary-value problem (1), (4), (5), then it is unique in the class of bounded functions  $v(x, t)$  for which*

$$\int_0^l v^2(x, t) dx$$

is continuous with respect to  $t$ . The initial function  $g(x)$  is here assumed continuous on  $[0, l]$  and satisfying (9).

**Theorem 11.** *If  $g(x)$  satisfies (9) and is continuously differentiable, then, for  $\mu$  sufficiently small, there exists at least one generalized, in the sense of Definition 2, solution  $u(x, t)$  of the first boundary-value problem (1), (4), (5), and moreover  $|u(x, t)| \leq K$ . For this generalized solution the inequality (20) also holds.*

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*Note: Figure translations are in progress. See original paper for figures.*

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