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HYDROMECHANICS

A. A. ZAITSEV

1960

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Fig. 1

Figure 1: Fig. 1

Abstract

Full Text

HYDROMECHANICS

A. A. ZAITSEV

ON THE QUESTION OF THE STABILITY OF A VISCOUS FILM ON A SOLID BODY IN A GAS FLOW

(Presented by Academician I. I. Artobolevskii, 5 XI 1959)

§ 1. **Statement of the problem.** On the plane $y = 0$ (Fig. 1) there flows a layer $0 \leq y \leq h$ of a viscous heavy liquid with a linear velocity distribution

$$U = \frac{U_0}{h}y, \quad V = 0. \quad (1)$$

In the half-space $y > h$ there flows a viscous heavy gas with velocity

$$U_1 = U_1(y), \quad V_1 = 0. \quad (2)$$

Fig. 1

All parameters of the flow under study do not depend on the coordinate x . We shall denote parameters pertaining to the gas by the subscript 1, leaving without a subscript the parameters pertaining to the liquid layer. The pressure in the liquid and in the gas is distributed as follows:

$$P = P_0 - \rho g(y - h), \quad P_1 = P_0 - \int_0^y \rho_1(y)g dy, \quad (3)$$

where ρ and ρ_1 are the densities of the liquid and gas; g is the acceleration of gravity. On the interface $y = h$ the conditions

$$U_1(h) = U_0, \quad \mu_1 \frac{dU_1}{dy} = \mu \frac{U_0}{h}, \quad (4)$$

are satisfied, where μ and μ_1 are the corresponding viscosity coefficients.

We superpose small disturbances on the basic flow

$$u = U + u', \quad u_1 = U_1 + u'_1, \quad v = v', \quad v_1 = v'_1, \quad p = P + p', \quad p_1 = P_1 + p'_1, \quad (5)$$

whereupon the former interface $y = h$ assumes the form

$$y = h + h'(x, t). \quad (6)$$

On the interface we require the relations

$$u' = u'_1, \quad v' = v'_1, \quad v' = \frac{\partial h'}{\partial t} + U_0 \frac{\partial h'}{\partial x}, \quad p_\tau = p_{\tau 1}, \quad p - p_{n1} = K \frac{\partial^2 h'}{\partial x^2}, \quad (7)$$

where p_τ are the tangential stresses, and p_n the normal stresses on the interface; K is the coefficient of surface tension.

Introducing dimensionless parameters and the stream function ψ ,

$$\varepsilon = \mu_1/\mu, \quad \sigma = \rho_1/\rho, \quad T = K\rho h/\mu^2, \\ G = \rho^2 g h^3/\mu^2, \quad \text{Re} = U_0 h \rho/\mu, \quad N = \mu \rho_1/\mu_1 \rho = \sigma/\varepsilon \quad (8)$$

$$u' = \partial\psi/\partial y, \quad v' = -\partial\psi/\partial x, \quad (9)$$

we consider a particular form of the disturbances

$$h' = \delta e^{i\alpha(x-ct)}, \quad \psi = \delta f(y) e^{i\alpha(x-ct)}, \quad u'_1 = \delta u_1(y) e^{i\alpha(x-ct)}, \quad (10)$$

$$v' = \delta U_1(y) e^{i\alpha(x-ct)}, \quad p' = \delta p(y) e^{i\alpha(x-ct)}, \quad p'_1 = \delta p_1(y) e^{i\alpha(x-ct)},$$

where x and y are referred to h ; t to h/U_0 ; u' and v' to U_0 ; p to $\mu U_0/h$.

Using the linearized Navier–Stokes equations and all the preceding assumptions, we reduce the boundary conditions (7) to the form

$$f'(1) = u_1(1), \quad -i\alpha f(1) = v_1(1), \quad (11)$$

$$f(1) = c - 1, \quad (12)$$

$$f''(1) + \alpha^2(c - 1) = \varepsilon [u_1'(1) + \alpha^2(c - 1)],$$

$$f'''(1) - 3\alpha^2 f'(1) + i\alpha \operatorname{Re}(c - 1)[f'(1) + 1 - N] + \varepsilon [2\alpha^2 f'(1) - u_1''(1) + i\alpha v_1'(1)] - \sigma i\alpha \operatorname{Re}(c - 1)f'(1) = i\alpha [G(1 - \sigma) + \alpha^2 T] \frac{1}{\operatorname{Re}}. \quad (13)$$

If now ε and σ are made to tend to zero in such a way that the limit $\lim_{\varepsilon \rightarrow 0, \sigma \rightarrow 0} (\sigma/\varepsilon) = N$ remains some finite quantity, then the boundary conditions (13) will not contain parameters characterizing the motion of the gas:

$$f''(1) = -\alpha^2(c - 1),$$

$$f'''(1) - 3\alpha^2 f'(1) + i\alpha \operatorname{Re}(c - 1)[f'(1) + 1 - N] = i\alpha (G + \alpha^2 T) \frac{1}{\operatorname{Re}}. \quad (14)$$

The latter expressions may be regarded as the result of expanding the quantities entering into conditions (13) in powers of the small parameters ε and σ , retaining only the first terms of the expansion.

At the solid wall we take the no-slip condition for the liquid

$$f(0) = f'(0) = 0. \quad (15)$$

Thus, the problem of the stability of a thin liquid film on a body in a gas stream, for sufficiently small ε and σ , reduces to the study of a particular form of the Orr–Sommerfeld equation ⁽¹⁾

$$f^{\text{IV}}(y) - 2\alpha^2 f''(y) + \alpha^4 f(y) - i\alpha \operatorname{Re}(y - c)[f''(y) - \alpha^2 f(y)] = 0 \quad (16)$$

with boundary conditions (12), (14), (15).

§ 2. Characteristic equation. We shall seek the solution of equation (16) in the form of a series in powers of the parameter $\lambda = \alpha \operatorname{Re}$

$$f(y) = \sum_{n=0}^{\infty} \lambda^n f_n(y). \quad (17)$$

Substituting (17) into equation (16) and equating coefficients of equal powers of λ , we obtain the system of differential equations

Fig. 2

Figure 2: Fig. 2

$$f_n^{IV} - 2\alpha^2 f_n'' + \alpha^4 f_n = F_n, \quad n = 0, 1, 2, \dots, \quad (18)$$

where

$$F_0 = 0, \quad F_n = i(y - c)[f_{n-1}'' - \alpha^2 f_{n-1}], \quad n = 1, 2, 3, \dots \quad (19)$$

This system is easily integrated in elementary functions successively, starting with $n = 0$. In order that the function $f(y)$ satisfy the boundary conditions (12), (14), (15), it is sufficient to require the fulfillment of the following relations for the solution of the system of equations (18), (19):

$$f_n(0) = f_n'(0) = 0, \quad n = 0, 1, 2, \dots, \quad f_0(1) = c - 1, \quad f_0''(1) = -\alpha^2(c - 1);$$

$$f_n(1) = f_n'(1) = 0, \quad n = 1, 2, 3, \dots; \quad (20)$$

$$f_0'''(1) - 3\alpha^2 f_0'(1) - i\alpha(G + \alpha^2 T) \frac{1}{\text{Re}} + i\lambda(c - 1)(1 - N) +$$

$$+ \sum_{n=1}^{\infty} \lambda^n [f_n'''(1) - 3\alpha^2 f_n'(1) + i(c - 1)f_{n-1}'(1)] = 0. \quad (21)$$

The general solution of the system of differential equations (18), (19) is

$$f_n(y) = \Phi_{n1}(y) \text{sh } \alpha y + \Phi_{n2}(y) \text{ch } \alpha y + \Phi_{n3}(y) y \text{sh } \alpha y + \Phi_{n4}(y) y \text{ch } \alpha y +$$

$$+ C_{n1} \text{sh } \alpha y + C_{n2} \text{ch } \alpha y + C_{n3} y \text{sh } \alpha y + C_{n4} y \text{ch } \alpha y, \quad (22)$$

where

$$\Phi_{n1} = -\frac{1}{2\alpha^3} \int_0^y F_n(\eta) (\text{ch } \alpha \eta - \alpha \eta \text{sh } \alpha \eta) d\eta,$$

$$\Phi_{n2} = \frac{1}{2\alpha^3} \int_0^y F_n(\eta) (\text{sh } \alpha \eta - \alpha \eta \text{ch } \alpha \eta) d\eta, \quad (23)$$

$$\Phi_{n3} = -\frac{1}{2\alpha^2} \int_0^y F_n(\eta) \text{sh } \alpha \eta d\eta, \quad \Phi_{n4} = \frac{1}{2\alpha^2} \int_0^y F_n(\eta) \text{ch } \alpha \eta d\eta.$$

Fig. 2

C_{nk} are constants of integration; $F_n(\eta)$ is determined by formulas (19).

Using the boundary conditions (20), we find the constants of integration C_{nk} , $n = 0, 1, 2, \dots$; $k = 1, 2, 3, 4$. Substituting the solution thus obtained, which contains no constants of integration, into relation (21), we find the characteristic equation. Neglecting in this equation the terms containing powers of λ higher than the second, we obtain the approximate characteristic equation

$$(c-1)[Q_{00} + \lambda^2(Q_{22}c^2 + Q_{21}c + Q_{20})] + i\left[\lambda(c-1)(Q_{11}c + Q_{10} + 1 - N) - \frac{\alpha}{\text{Re}}(G + \alpha^2T)\right] = 0, \quad (24)$$

where Q_{ik} are real quantities depending only on α .

§ 3. Neutral curves, critical Reynolds number. Taking c to be real, we separate in equation (24) the real and imaginary parts; then we obtain the system of equations

$$(c-1)[Q_{00} + \alpha^2 \text{Re}^2(Q_{22}c^2 + Q_{21}c + Q_{20})] = 0, \quad (25)$$

$$(c-1)(Q_{11}c + Q_{10} + 1 - N) \text{Re}^2 - (G + \alpha^2T) = 0. \quad (26)$$

If $G \equiv T \equiv 0$, then (25) and (26) are satisfied for $c = 1$ for arbitrary Re and α , but in this case the imaginary part of c is identically equal to zero, whereas loss of stability occurs when the sign of the imaginary part of c changes. Therefore we shall exclude this case from consideration.

If $c \neq 1$, then from equation (25) we find

$$\text{Re} = \sqrt{-\frac{Q_{00}}{\alpha^2(Q_{22}c^2 + Q_{21}c + Q_{20})}}. \quad (27)$$

Substituting (27) into (26), we obtain a quadratic equation with respect to c

$$c^2 [Q_{00}Q_{11} + \alpha^2Q_{22}(G + \alpha^2T)] + c [Q_{00}(Q_{10} + 1 - N - Q_{11}) + \alpha^2Q_{21}(G + \alpha^2T)] - Q_{00}(Q_{10} + 1 - N) - \alpha^2Q_{20}(G + \alpha^2T) = 0. \quad (28)$$

The roots of this equation are c_1 and c_2 . Substituting c_1 and c_2 into (27), we find, respectively, Re_1 and Re_2 . The curves of the dependence of Re on α are customarily called

Fig. 3

neutral. In the case $G \geq 0$, the neutral curves have the form shown in Fig. 2 ($N = 0$, $T = 500$). The minimum value $\min \text{Re}(\alpha) = \text{Re}_{\text{cr}}$ is called the critical

Fig. 3

Figure 3: Fig. 3

Reynolds number. In the case $G < 0$ we shall not have Re_{cr} without some additional condition, since in this case, in addition to the neutral curves of the former form, there is the straight line

$$\alpha = \sqrt{-G/T},$$

and the region of instability will lie below this straight line. In the subsequent calculations we set $G = 0$. This is justified by the fact that G enters all formulas only in the form of the combination $G + \alpha^2 T$; thus, the case $G > 0$ can be obtained from the case $G = 0$ by a corresponding increase in T .

Figure 3 gives the results of calculating Re_{cr} as a function of the parameters T and N ($a - \text{Re}_{1\text{cr}}$, $b - \text{Re}_{2\text{cr}}$, $c - \text{Re}_{\text{cr}}$).

The Reynolds number can be written in the form $\text{Re} = \rho h^2 \tau / \mu^2$, where $\tau = \mu U_0 / h$ is the shear stress on the surface of the layer. The value of τ can be calculated using boundary-layer theory in the gas, or found from experiment; then, knowing the critical Reynolds number, we can determine the thickness of the stable liquid layer on the body.

The calculations were carried out on the "Strela" electronic computer.

Received
31 X 1959

REFERENCES

1. **Lin Chia-chiao**, *Theory of Hydrodynamic Stability*, IL, 1958.

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