



Soviet-era science, translated into English

Reports of the Academy of Sciences of the USSR

1960

SovietRxiv

View the original and related papers at <https://sovietrxiv.org/items/ru-196001.07369>

Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.

Abstract

Full Text

Reports of the Academy of Sciences of the USSR

1960, Volume 131, No. 6

MATHEMATICS

A. S. SHVARTS

STABILITY OF STATIONARY VALUES

(Presented by Academician P. S. Aleksandrov, 21 XII 1959)

Let a group G act on a differentiable manifold E , and let a differentiable function J , invariant with respect to the group G , be defined on E (the manifold E may be infinite-dimensional, i.e., a locally Banach space, for example, a sphere in Hilbert space). By virtue of the invariance of the function J with respect to the group G , one may regard J as a function on the space of trajectories E/G and obtain stronger estimates of the number of stationary points of the function J than those which hold for an arbitrary function on the manifold E ⁽¹⁾. M. A. Krasnosel' skii posed the question: can one use the invariance of the function J with respect to the group G in order to give an estimate of the number of stationary values of functions close to the function J , but no longer invariant with respect to the group G ? In other words, the problem may be formulated as follows: estimate the number of stationary values of the function J that are stable under small perturbations of the function J (the perturbations need not be invariant with respect to the group G). The present note is devoted to the solution of this problem (M. A. Krasnosel' skii solved ⁽²⁾ the problem posed by him in the case when the manifold E is a sphere in Hilbert space and the group G consists of the identity transformation and the central symmetry).

In what follows we shall call a topological space a space; a continuous real-valued function, a function; a smooth manifold, a finite-dimensional closed smooth manifold; a differentiable function, a twice differentiable function; and a fiber space, a locally trivial fiber space. By $\{f \geq \alpha\}$ ($\{f < \alpha\}$) is denoted the set of points at which the function f assumes values $\geq \alpha$ ($< \alpha$).

Let f be a function defined on a space X . A number α is called a critical value of the function f if the embedding of the set $\{f < \alpha\}$ into the set $\{f \leq \alpha\}$ is not a weak homotopy equivalence (this definition differs somewhat from the usual one).

Let $p : E \rightarrow B$ be a fiber space; J a function on the base B ; \tilde{J} a function on the total space E , defined by the formula $\tilde{J} = Jp$ (the function \tilde{J} is constant on the fibers of the fibration $p : E \rightarrow B$; conversely, every function constant on

the fibers can be obtained in the manner described above from a function on the base).

Theorem 1. *The set of critical values of the function J coincides with the set of critical values of the function \tilde{J} .*

For the proof it suffices to refer to the following simple assertion.

Proposition 1. *If B_1 is a subset of the base B of the fibration $p : E \rightarrow B$, then the embedding of the set B_1 in B is a weak homotopy equivalence if and only if the embedding of the set $p^{-1}(B_1)$ in E is a weak homotopy equivalence.*

Corollary 1. If, under the hypotheses of Theorem 1, E is a smooth manifold and the function \tilde{J} is differentiable, then every critical value α of the function J is a stable stationary value of the function \tilde{J} , provided the set $\{\tilde{J} \leq \alpha\}$ is a neighborhood retract. (The number α is called a stable stationary value of the function \tilde{J} if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that every differentiable function K on the manifold E satisfying the condition $|\tilde{J}(x) - K(x)| < \delta$ for all $x \in E$ has a stationary value differing from α by less than ε .)

Theorem 2. *Let E and B be smooth manifolds; let $p : E \rightarrow B$ be a differentiable fibration with fiber F ; let J be a differentiable function on B ; $\tilde{J} = Jp$. Suppose that the function \tilde{J} has s stationary values, to which there correspond sets of stationary points of dimensions k_1, k_2, \dots, k_s (we assume that the numbers k_i are arranged in decreasing order). Then the number of stable stationary values of the function \tilde{J} is bounded below by the largest number t for which*

$$k_1 + k_2 + \dots + k_{t-1} < \text{cat } B + (t-1)(\dim F - 1).$$

In the case when $\text{cat } B = \dim B + 1$, this estimate cannot be improved.

Let M be a smooth manifold; let f be a differentiable function on M ; let α be a stationary value of the function f . The set of stationary points of the function f at which the function takes the value α will be denoted by $S_\alpha(f)$. We shall say that the set of stationary points corresponding to the stationary value α of the function f stably has dimension $\geq k$, and shall write $s \dim S_\alpha(f) \geq k$, if for every $\varepsilon > 0$ there exists a $\delta > 0$ such that any function g satisfying the condition

$$|f(x) - g(x)| + |\text{grad}(f(x) - g(x))| < \delta$$

for all $x \in M$, either has a stationary value differing from α by less than ε , with a set of stationary points of dimension $\geq k$, or has several stationary values differing from α by less than ε (we assume that a Riemannian metric has been introduced on M in some way, and denote by $|\text{grad}(f(x) - g(x))|$ the length of the gradient vector).

Proposition 2. *If there exists a neighborhood V of the set $S_\alpha(f)$ such that for some $\varepsilon > 0$ one can find cohomology classes*

$$\xi \in H_c(\bar{V} \setminus \{f \leq \alpha - \varepsilon\}, A); \quad \eta \in H^k(\bar{V} \setminus \{f \leq \alpha - \varepsilon\}, B),$$

such that the cohomology classes ξ and $\xi \cdot \eta$ cut out nonzero cohomology classes on the set $\bar{V} \cap \{f \leq \alpha\} \setminus \{f \leq \alpha - \varepsilon\}$ and zero cohomology classes on the set $(\bar{V} \cap \{f \leq \alpha\} \setminus U) \setminus \{f \leq \alpha - \varepsilon\}$, where U is an arbitrary neighborhood of the set $S_\alpha(f)$, then $s \dim S_\alpha(f) \geq k$.

By $H(X, A) [H_c(X, A)]$ is denoted the cohomology group (with compact supports) in the sense of Alexander-Spanier with coefficients in the local system A ; the product of cohomology classes $\xi \cdot \eta$ is regarded as an element of the group

$$H_c(\bar{V} \setminus \{f \leq \alpha - \varepsilon\}, A \otimes B).$$

In the case when the hypotheses of Proposition 2 are satisfied, we shall write $h \dim S_\alpha(f) \geq k$; using this notation, Proposition 2 can be written in the form of the inequality:

$$s \dim S_\alpha(f) \geq h \dim S_\alpha(f).$$

Let E and B be smooth manifolds; let $p : E \rightarrow B$ be a differentiable fibration; let J be a differentiable function on B ; $\tilde{J} = Jp$. It is easy to prove to verify that the sets of stationary values of the functions J and \tilde{J} coincide and that

$$s \dim S_\alpha(\tilde{J}) \leq s \dim S_\alpha(J) + \dim F$$

(this follows from the relation $S_\alpha(\tilde{J}) = p^{-1}(S_\alpha(J))$).

The question remains open as to whether the equality

$$s \dim S_\alpha(\tilde{J}) = s \dim S_\alpha(J) + \dim F?$$

holds.

However, it can be shown that in the case when the fibration $p : E \rightarrow B$ is a regular covering, this relation holds under certain conditions. Namely, the following is true.

Theorem 3. *Let E be a smooth manifold; let G be a finite group of differentiable transformations of the manifold E , acting on E without fixed points; let \tilde{J} be a differentiable function on E invariant with respect to the group G ; and let J be the corresponding function on the space of trajectories E/G . If*

$$h \dim S_\alpha^*(J) = \dim S_\alpha(J) = k,$$

then

$$h \dim S_\alpha(\tilde{J}) = s \dim S_\alpha(\tilde{J}) = s \dim S_\alpha(J) = k.$$

Let A be a periodic operator in the Hilbert space H , mapping the unit sphere S of the space H into itself. Suppose that the operator A satisfies the Lipschitz condition and that every power of the operator A either is the identity transformation or has only one fixed point θ . Let $F(x)$ be a weakly continuous and uniformly differentiable functional defined on the unit ball T of the space H and satisfying the conditions: a) $F(Ax) = F(x)$, $x \in S$; b) $F(x) > 0$ for $x \neq \theta$; $F(\theta) = 0$; c) $\Gamma x \neq \theta$ for $x \neq \theta$, $\Gamma\theta = \theta$ (where Γ denotes the gradient operator of the functional $F(x)$, and θ denotes the zero of the space H).

Theorem 4. *The functional $F(x)$ has an infinite number of distinct stable stationary values.*

Stability of stationary values is understood here in the same sense as in ⁽²⁾.

The existence of an infinite set of distinct stationary values for a periodic functional under different assumptions was proved by V. I. Anosov ⁽³⁾, following the scheme proposed by M. A. Krasnosel' skii ⁽²⁾.

I take this opportunity to express my gratitude to M. A. Krasnosel' skii for the interest he showed in this work.

Voronezh State University

Received
11 XII 1959

REFERENCES

¹ L. A. Lyusternik, *Tr. Matem. inst. im. V. A. Steklova*, **19** (1947). ² M. A. Krasnosel' skii, *Topological methods in the theory of nonlinear integral equations*, 1956. ³ V. I. Anosov, *DAN*, **131**, No. 2 (1960).

Note: Figure translations are in progress. See original paper for figures.

Source: Math-Net.Ru and CyberLeninka. Machine translation. Verify with the original.