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# ON A TRANSFORMATION OF ISOMETRIC SURFACES

1958

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**Abstract**

**Full Text**

**MATHEMATICS**

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## **ON A TRANSFORMATION OF ISOMETRIC SURFACES**

*(Presented by Academician V. I. Smirnov on 30 IV 1958)*

In this note a standard method will be given for assigning to each pair of isometric surfaces of a space of constant curvature  $K \neq 0$  a pair of isometric surfaces of Euclidean space, and conversely, to each pair of isometric surfaces of Euclidean space—a pair of isometric surfaces of a space of constant curvature. This gives a new approach to the problem of unique determination of convex surfaces in spaces of constant curvature.

Without loss of generality, we shall assume  $K = 1$  for elliptic space and  $K = -1$  for Lobachevsky space.

Let  $R$  be elliptic space. Introduce Weierstrass coordinates  $x_i$  ( $i = 0, 1, 2, 3$ ) in  $R$ , and associate with each point of the space  $R$  a pair of points of four-dimensional Euclidean space with Cartesian coordinates  $x_i$  and  $-x_i$ . These points fill the unit sphere, since the Weierstrass coordinates satisfy the condition

$$x^2 = x_0^2 + x_1^2 + x_2^2 + x_3^2 = 1.$$

Denote by  $E_0$  the three-dimensional Euclidean space  $x_0 = 0$ .

**Theorem 1.** *Suppose that in elliptic space  $R$  we have two isometric surfaces  $F'$  and  $F''$ , given by equations in Weierstrass coordinates*

$$x = x'(u, v), \quad x = x''(u, v),$$

*where the points of the surfaces corresponding under the isometry have the same coordinates  $u, v$ .*

*Then the equations in Cartesian coordinates  $y_i$*

$$y = \frac{x'(u, v) - e_0(x'(u, v)e_0)}{e_0(x'(u, v) \pm x''(u, v))},$$

$$y = \frac{x''(u, v) - e_0(x''(u, v)e_0)}{e_0(x'(u, v) \pm x''(u, v))} \quad (1)$$

define two isometric surfaces in the Euclidean space  $E_0$ .

In equations (1),  $e_0$  is the unit vector along the axis  $x_0$ , and the scalar product is expressed by the usual formula.

Let now  $R$  be Lobachevsky space ( $K = -1$ ). Introduce Weierstrass coordinates  $x_i$  in  $R$ , and associate with each point of  $R$  the point of four-dimensional Euclidean space with Cartesian coordinates  $x_i$ . Then  $R$  is mapped onto the two-sheeted hyperboloid

$$-x_0^2 + x_1^2 + x_2^2 + x_3^2 = -1.$$

**Theorem 2.** Suppose that in Lobachevsky space  $R$  we have two isometric surfaces  $F'$  and  $F''$ , given by equations in Weierstrass coordinates

$$x = x'(u, v), \quad x = x''(u, v).$$

Then the equations in Cartesian coordinates  $y_i$

$$\begin{aligned} y &= \frac{x'(u, v) + e_0(x'(u, v)e_0)}{e_0(x'(u, v) \pm x'(u, v))}, \\ y &= \frac{x''(u, v) + e_0(x''(u, v)e_0)}{e_0(x'(u, v) \pm x''(u, v))} \end{aligned} \quad (2)$$

define two isometric surfaces in the Euclidean space  $E_0$ .

In equations (2) the scalar product is taken with respect to the form

$$-x_0^2 + x_1^2 + x_2^2 + x_3^2.$$

**Theorem 3.** Let in the Euclidean space  $E_0$  there be two isometric surfaces  $\Phi'$  and  $\Phi''$ , given in Cartesian coordinates  $y_i$  by the equations

$$y = y'(u, v), \quad y = y''(u, v).$$

Then the equations in Weierstrass coordinates  $x_i$

$$\begin{aligned} x &= \rho\{2y'(u, v) \pm e_0(1 - y''^2(u, v) + y''^2(u, v))\}, \\ x &= \rho\{2y''(u, v) \pm e_0(1 - y''^2(u, v) + y'^2(u, v))\} \end{aligned} \quad (3)$$

define two isometric surfaces in the elliptic space  $R$  ( $K = 1$ ).

In equations (3)  $\rho$  is a normalizing factor, determined by the condition  $x^2 = 1$ , and the scalar product is determined by the usual formula for vectors of four-dimensional space.

**Theorem 4.** Let in the Euclidean space  $E_0$  there be two isometric surfaces  $\Phi'$  and  $\Phi''$ , given in Cartesian coordinates  $y_i$  by the equations

$$y = y'(u, v), \quad y = y''(u, v).$$

Then the equations in Weierstrass coordinates  $x_i$

$$\begin{aligned} x &= \rho\{2y'(u, v) \pm e_0(1 - y'^2(u, v) + y''^2(u, v))\}, \\ x &= \rho\{2y''(u, v) \pm e_0(1 - y'^2(u, v) + y''^2(u, v))\} \end{aligned} \quad (4)$$

define two isometric surfaces in Lobachevsky space  $R$  ( $K = -1$ ).

In equations (4) the scalar multiplication is taken with respect to the quadratic form

$$-x_0^2 + x_1^2 + x_2^2 + x_3^2,$$

and the normalizing factor  $\rho$  is determined by the condition  $x^2 = -1$ .

In all Theorems 1-4, if the given surfaces are simply congruent, i.e. can be brought into coincidence by a motion, then the surfaces obtained are also congruent.

We shall give an example of the use of Theorem 1 for proving the unique determination of closed convex surfaces in elliptic space.

Let  $F'$  and  $F''$  be closed isometric, equally oriented convex surfaces in elliptic space  $R$  ( $K = 1$ ). Place the surfaces  $F'$  and  $F''$  so that they do not intersect the plane  $x_0 = 0$ . Then the Weierstrass coordinates of the points of the surfaces can be normalized by the additional condition  $x_0 > 0$ . Move the given surfaces  $F'$  and  $F''$ , remaining in the region  $x_0 > 0$ , into such a position that the point  $(1, 0, 0, 0)$  lies inside each of the surfaces.

If we now take equations (1) with the plus sign in the denominator, then the corresponding surfaces of the Euclidean space  $E_0$  will be not only isometric but also convex. And such surfaces, as is known, are congruent. Consequently, the surfaces  $F'$  and  $F''$  are also congruent.

Received  
28 IV 1958

*Note: Figure translations are in progress. See original paper for figures.*

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