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**Abstract**

**Full Text**

## **Reports of the Academy of Sciences of the USSR**

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**MATHEMATICS**

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### **EIGENVALUES AND EIGENFUNCTIONS OF CERTAIN FOURTH-ORDER DIFFERENTIAL OPERATORS WITH A SMALL PARAMETER AT THE HIGHEST DERIVATIVE**

*(Presented by Academician I. G. Petrovsky on 17 VI 1958)*

Let two linear self-adjoint differential operators be given on the interval  $[0, 1]$ :

$$L_\eta = -\eta^2 \frac{d^2}{dx^2} \left( p_2(x) \frac{d^2}{dx^2} \right) + L_0, \quad \text{where } L_0 \equiv -\frac{d}{dx} \left( p_1(x) \frac{d}{dx} \right),$$

where the coefficients  $p_i(x)$  ( $i = 1, 2$ ) are strictly positive and  $i$  times continuously differentiable everywhere in  $0 \leq x \leq 1$ . We shall regard the parameter  $\eta$  as small.

In contrast to operators of this type considered in works <sup>(1-3)</sup>, here the signs of the coefficients at the highest derivatives in the full ( $L_\eta$ ) and degenerate ( $L_0$ ) operators are the same.

Consider the boundary-value problems

$$L_\eta(u) = \lambda u, \quad u(0) = u(1) = 0, \quad u^{(\sigma)}(0) = u^{(\sigma)}(1) = 0 \quad (\sigma = 1, 2); \quad (\text{I})$$

$$L_0(y) = \lambda y, \quad y(0) = y(1) = 0. \quad (\text{II})$$

1. Problem (I) has zero as its eigenvalue for certain exceptional values of the parameter  $\eta$ , since the following theorem holds.

**Theorem.** The problem

$$L_\eta(u) = 0, \quad u(0) = u(1) = 0, \quad u^{(\sigma)}(0) = u^{(\sigma)}(1) = 0 \quad (\sigma = 1, 2)$$

has nontrivial solutions, i.e. there exist eigenvalues  $\eta_{\sigma,n}$  of this problem, and they are equal to

$$\eta_{\sigma,n} = \frac{\nu}{(3-\sigma)n\pi} \quad (\sigma = 1, 2; n = 1, 2, \dots),$$

and, additionally, for the case  $\sigma = 1$ :

$$\eta_{1,n} = \eta_n^* \quad (n = 1, 2, \dots),$$

where

$$\nu = \int_0^1 \sqrt{\frac{p_1(x)}{p_2(x)}} dx,$$

$\eta_n^*$  are the roots of the transcendental equation

$$\tan \frac{\nu}{2\eta} = \int_0^1 \frac{dt}{p_1(t)} \bigg/ \eta \sum_{i=0}^1 \sqrt{\frac{p_2(i)}{p_1^3(i)}}.$$

2. We introduce the stability region  $R$  of the solution of problem (I), defining it by the relations

$$\left| \sin \frac{\nu}{\eta} \right| \geq \frac{1 + (-1)^n \delta_{1\sigma}}{3 - \sigma} M,$$

where  $0 < M \leq 1$ ,  $n$  is the number of the point  $\eta_n = \nu/n\pi$  ( $n = 1, 2, \dots$ ), and additionally, for the case  $\sigma = 1$ ,

$$\left| \operatorname{tg} \frac{\nu}{2\eta} - \int_0^1 \frac{dt}{p_1(t)} \bigg/ \eta \sum_{i=0}^1 \left| \sqrt{\frac{p_2(i)}{p_1^3(i)}} \right| \right| \geq N,$$

where  $0 < N < +\infty$ , i.e. the  $\eta_{\sigma,n}$  and a certain neighborhood of the values of  $\eta$  around them are excluded from consideration. The stability region  $R$  is the set of intervals lying between two adjacent values  $\eta_{\sigma,n}$ , which, as  $n \rightarrow \infty$  ( $\eta \rightarrow 0$ ), tend to the open interval  $(\eta_{\sigma,n}; \eta_{\sigma,n+1})$ , while at the same time tending to zero.

All further results are formulated only for  $\eta \in R$ .

3. The solution constructed in the stability region  $R$  of the problem

$$L_\eta(z) = f(x), \quad z(0) = z(1) = 0, \quad z^{(\sigma)}(0) = z^{(\sigma)}(1) = 0 \quad (\sigma = 1, 2),$$

where  $f(x)$  is a function continuous together with its two derivatives in  $0 \leq x \leq 1$ , satisfying the boundary condition  $f(0) = f(1) = 0$ , has the form

$$z(x, \eta) = v(x) + \eta^\sigma \omega(x, \eta) + \zeta(x, \eta),$$

where  $v(x)$  is the solution of the degenerate problem

$$L_0(v) = f(x), \quad v(0) = v(1) = 0;$$

$$|\omega(x, \eta)| < O(1), \quad |\omega'(x, \eta)| < \frac{1}{\eta} O(1),$$

and  $\zeta(x, \eta)$  is a function of order  $\eta^{\sigma+1}$ , with first derivative of order  $\eta^\sigma$ .

4. Consider the problem of a more general form

$$L_\eta(J) = f(x), \quad J(0) = J(1) = 0, \quad J^{(\sigma)}(l, \eta) = S_{\sigma, l}(\eta)$$

$$(\sigma = 1, 2; l = 0, 1),$$

where  $f(x)$  satisfies the same conditions as the right-hand side of the equation of the problem considered in the preceding item;  $S_{\sigma, l}(\eta)$  is a constant satisfying the following condition:  $|S_{\sigma, l}(\eta)| \leq C$ , and may, in particular, be equal to zero. For its solution we obtain the estimate

$$|J(x, \eta)| < \max |f(x)| K_1(1 + \eta L_1) + \eta^\sigma S_\sigma(\eta) K_2(1 + \eta L_2),$$

$$|J'(x, \eta)| < \max |f(x)| K_3(1 + \eta L_3) + \eta^{\sigma-1} S_\sigma(\eta) K_4(1 + \eta L_4),$$

where

$$S_\sigma(\eta) = \max_l |S_{\sigma, l}(\eta)|;$$

$K_i, L_i$  ( $i = 1, 2, 3, 4$ ) are certain constants.

This estimate is used to determine the order of smallness of the remainder term  $\zeta(x, \eta)$  in the solution of the problem of the preceding item.

5. We construct the Green's function  $G(x, \xi, \eta)$  of the operator  $L_\eta$ . It turns out that, just as in work (1), the relations

$$G(x, \xi, \eta) = G_0(x, \xi) + \eta O(1) \quad \text{for } x, \xi \in [0, 1], \eta \in R;$$

$$\frac{\partial G}{\partial x}(x, \xi, \eta) = O(1) \quad \text{for } x, \xi \in [0, 1], \eta \in R,$$

hold, where  $G_0(x, \xi)$  is the Green's function corresponding to the degenerate differential operator  $L_0$ .

6. In the stability region  $R$ , for sufficiently small  $\eta$ , one can indicate the least positive eigenvalue  $\lambda$  of problem (I), which remains the least among the positive eigenvalues and does not

will merge with some other one upon a further decrease of  $\eta$ . We assign this eigenvalue the index 1. The corresponding normalized eigenfunction will be denoted by  $u_1(x, \eta)$ .

Similarly, for a sufficiently small value of the parameter  $\eta \in R$ , one can indicate a positive eigenvalue of problem (I), adjacent to  $\lambda_1(\eta)$ , which upon a subsequent decrease of  $\eta$  will remain the second (after  $\lambda_1(\eta)$ ) positive eigenvalue and will not merge with any other eigenvalue of this problem, etc.

Thus, in the stability region  $R$ , for sufficiently small  $\eta$ , all positive eigenvalues of problem (I) and the corresponding eigenfunctions can be numbered, i.e.,

$$\lambda_1(\eta), \lambda_2(\eta), \dots, \lambda_k(\eta), \quad \text{where } \lambda_k(\eta) > 0;$$

$$u_1(x, \eta), u_2(x, \eta), \dots, u_k(x, \eta).$$

We note that, as  $\eta$  decreases, the number of positive eigenvalues of problem (I) increases.

The eigenvalues and normalized eigenfunctions of problem (II) will be denoted respectively by  $\lambda_k$  and  $y_k(x)$ .

7. In the stability region  $R$ , on the basis of the results obtained in the preceding items, using the variational method, we obtain

$$\lim_{\eta^{(m)} \rightarrow 0} \lambda_k(\eta^{(m)}) = \lambda_k, \quad \lim_{\eta^{(m)} \rightarrow 0} u_k(x, \eta^{(m)}) = y_k(x) \quad (k = 1, 2, \dots),$$

where  $\{\eta^{(m)}\}$  is any sequence of values of the parameter  $\eta$ , taken from the stability region  $R$ .

8. Using (with account taken of the stability region  $R$ ) the method proposed in paper (1), we obtain representations for the positive eigenvalues and eigenfunctions of problem (I) in terms of the eigenvalues and eigenfunctions of the degenerate problem (II):

$$\lambda_k(\eta) = \lambda_k - \eta^\sigma \Phi_{\sigma, k} + \eta^{\sigma+1} O(1).$$

In particular, for  $k = 1$  we have

$$\Phi_{\sigma,1} = \begin{cases} R(0)R(1)D_1^{-1}(\eta) \left\{ \cos \frac{\nu}{\eta} \sum_{i=0}^1 \sqrt{p_1(i)p_2(i)y_1^2(i)} + \varkappa \prod_{i=0}^1 \sqrt[4]{p_1(i)p_2(i)y_1(i)} \right\}, & \text{for } \sigma = 1, \\ \int_0^1 p_2(\xi)y_1^2(\xi) d\xi, & \text{for } \sigma = 2, \end{cases}$$

where

$$D_1(\eta) = \sin \frac{\nu}{\eta} \int_0^1 \frac{dt}{p_1(t)} - \eta(h^2(0) + h^2(1)) \left( 1 - \cos \frac{\nu}{\eta} \right), \quad R(i) = \sqrt{\frac{p_1(i)}{p_2(i)}},$$

$$h(i) = \sqrt[4]{\frac{p_2(i)}{p_1^3(i)}} \quad (i = 0, 1), \quad \varkappa = \frac{1}{R(0)R(1)} \int_0^1 \frac{dt}{p_1(t)} \left( \frac{1}{R(0)R(1)} \int_0^1 \frac{dt}{p_1(t)} - 1 \right) \sin \frac{\nu}{\eta} - 2.$$

$$u_k(x, \eta) = y_k(x) + \eta^\sigma \chi_{\sigma,k}(x, \eta) + \eta^{\sigma+1} O(1),$$

where  $|\chi_{\sigma,k}(x, \eta)| < O(1)$ .

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## CITED LITERATURE

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