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Abstract

Full Text

MATHEMATICS

I. Ya. Bakelman

A PRIORI ESTIMATES AND REGULARITY OF GENERALIZED SOLUTIONS OF THE MONGE-AMPÈRE EQUATIONS

(Presented by Academician V. I. Smirnov on 26 IV 1957)

1. In the present paper we consider a priori estimates for solutions of the equations

$$rt - s^2 = \varphi(x, y, z, p, q), \quad (1)$$

where $\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$ is a function continuously differentiable m times ($m \geq 3$). These estimates are a generalization of estimates obtained by S. N. Bernstein ⁽¹⁾ for the equations $rt - s^2 = C$ ($C = \text{const} > 0$) and by A. V. Pogorelov for the equations $rt - s^2 = \varphi(x, y)$ ($\varphi(x, y) \geq \text{const} > 0$). The a priori estimates obtained make it possible to establish the regularity of generalized solutions of equations (1).

2. A priori estimates of the modulus of the solution and of its first derivatives. Consider in the disk $\Omega : x^2 + y^2 \leq R^2$ with boundary Γ an analytic solution $z(x, y)$ of equation (1), which on Γ turns into an analytic function $\psi(\theta)$ of the polar angle θ . The function $\varphi(x, y, z, p, q)$ is assumed analytic in Ω with respect to x, y and for all finite z, p, q . Further, we assume that $\varphi'_z(x, y, z, p, q) \geq 0$ for all functions $z(x, y)$ continuously differentiable in $\Omega + \Gamma^*$. Introduce the function

$$N_\varphi(\nu_1, \nu_2) = \sup \varphi(x, y, z, p, q),$$

where the exact upper bound is taken in the domain $x^2 + y^2 \leq R$, $|z| \leq \nu_1$, $\text{grad}^2 z \leq \nu_2$.

Let γ be the edge of the surface $z = z(x, y)$ and P an arbitrary point of γ . Denote by $\mu(P) = \inf(a^2 + b^2)$, where the exact lower bound is taken over all planes $z = ax + by + c$ passing through the point P and tangent to γ at this point and leaving the curve γ below them. Let

$$M(\psi) = \sup_{P \in \gamma} \mu(P).$$

An estimate for $M(\psi)$ was obtained by S. M. Bernstein ⁽¹⁾ in terms of $\psi(\theta)$ and its derivatives up to the third order. Below an estimate for $M(\psi)$ will be given from other considerations.

Theorem 1. *Let the conditions formulated above be fulfilled with respect to the solution $z(x, y)$ and the function $\varphi(x, y, z, p, q)$. Then, if*

$$4R^2 N_\varphi(\nu_1(R), \nu_2(R)) \leq 1, \quad (2)$$

where

$$\nu_1(R) = (2 - \sqrt{3})R + R^2 + 3 \max_{0 \leq \theta \leq 2\pi} |\psi(\theta)|, \quad \nu_2(R) = \frac{2}{3} + 4R^2 + 4M(\psi),$$

then the inequalities hold

$$\max_{\Omega+\Gamma} |z| \leq (2 - \sqrt{3})R + R^2 + 3 \max_{0 \leq \theta \leq 2\pi} |\psi(\theta)|,$$

$$\max_{\Omega+\Gamma} (\text{grad}^2 z) \leq \frac{2}{3} + 4R^2 + 4M(\psi).$$

* The condition $\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$, introduced in item 1, is assumed to be fulfilled.

Theorem 1 is valid if the condition $\varphi'_z(x, y, z, p, q) \geq 0$ is replaced by the condition $\varphi(x, y, z, p, q) \leq \Phi_0 \tilde{R}(p, q)$, where $\Phi_0 = \text{const} > 0$ and $\tilde{R}(p, q)$ is a continuously differentiable positive function, and condition (2) is replaced by the condition

$$4R^2 \Phi_0 \tilde{N}_R(\nu_2(R)) \leq 1/\Phi_0,$$

where

$$\tilde{N}_R(\nu_2) = \max_{p^2+q^2 \leq \nu_2} \tilde{R}(p, q).$$

3. A priori estimates of the second derivatives of solutions in a closed disk. Let, in equation (1), the right-hand side satisfy the inequality

$$\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$$

for all continuously differentiable functions $z(x, y)$ in $\Omega + \Gamma$, and let this function still be analytic in $(x, y) \in \Omega$ and for all finite z, p, q ; the fulfillment of the inequality $\varphi_z(x, y, z, p, q) \geq 0$ is not required in the present section. Let, further, $\psi(\theta)$ be an analytic function and let $z(x, y)$ be an analytic solution of equation (1) satisfying the condition $z(x, y)|_\Gamma = \psi(\theta)$. Suppose that we know the estimates

$$\max_{\Omega+\Gamma} |z| \leq L_0, \quad \max_{\Omega+\Gamma} (\text{grad}^2 z) \leq L_1.$$

We set the problem of obtaining analogous estimates for the second derivatives of the function $z(x, y)$. The estimates of the second derivatives in the closed domain are carried out separately on the boundary and inside the disk. Let ρ, θ be polar coordinates in the x, y -plane. The estimate of $z_{\theta\theta}$ on Γ is trivial. The estimates for $z_{\rho\theta}$ and $z_{\rho\rho}$ on Γ depend on the following quantities: a) the maximum modulus of $\psi(\theta)$ and its derivatives up to and including the fourth order; b) the numbers L_0, L_1 , and k_0 ; c) the number

$$\Phi_0 = \max\{\sup |\varphi_\theta|, \sup |\varphi_z|, \sup |\varphi_{zp}|, \sup |\varphi_{z\theta}|\},$$

where the exact upper bound of each of the functions under consideration is taken in the domain

$$R/2 \leq \rho \leq R, \quad 0 \leq \theta \leq 2\pi, \quad |z| \leq L_0, \quad \text{grad}^2 z \leq L_1.$$

The estimates of the second derivatives inside Ω are obtained by the method of auxiliary functions introduced by S. N. Bernstein. For our purposes a construction introduced by A. V. Pogorelov in (2) is convenient; namely, the auxiliary functions for obtaining estimates of $r^2 + s^2$ and $s^2 + t^2$ have the form

$$w_1 = \lambda_1 r, \quad w_2 = \lambda_2 t,$$

where λ_1 and $\lambda_2 > 0$ are certain known functions of x, y . In our case we take

$$\lambda_1 = \lambda_2 = x^2 + y^2 + R^2,$$

where R is the radius of the disk Ω . If the radius of the disk Ω is sufficiently small, then estimates for $|r|, |s|, |t|$ can be obtained in terms of $\varphi(x, y, z, p, q)$ and its derivatives up to and including the second order in the domain

$$x^2 + y^2 \leq R^2, \quad |z| \leq L_0, \quad \text{grad}^2 z \leq L_1.$$

The final results concerning estimates of the second derivatives may be formulated as follows.

Theorem 2. *Let, with respect to the solution $z(x, y)$ and the function $\varphi(x, y, z, p, q)$, the conditions formulated in Section 3 be fulfilled. Then, if the radius R of the disk Ω satisfies the inequality $4R^2 A_0 \leq 1$, where*

$$A_0 = \max\{\sup |\varphi_{pp}|, \sup |\varphi_{pq}|, \sup |\varphi_{qq}|\},$$

the exact upper bounds of the indicated functions being taken in the domain $(x, y) \in \Omega$, $|z| \leq L_0$, $\text{grad}^2 z \leq L_1$, then for $|r|, |s|, |t|$ in $\Omega + \Gamma$ one can obtain estimates depending only on $\psi(\theta)$ and its derivatives up to the fourth order, and on the upper bounds of the moduli of $\varphi(x, y, z, p, q)$ and its partial derivatives with respect to all variables of the first two orders in the domain

$$x^2 + y^2 \leq R^2, \quad |z| \leq L_0, \quad \text{grad}^2 z \leq L_1.$$

Denote by

$$T_\varphi(\nu_1, \nu_2) = \max\{\sup |\varphi_{pp}|, \sup |\varphi_{pq}|, \sup |\varphi_{qq}|\},$$

where the exact upper bounds of $|\varphi_{pp}|, |\varphi_{pq}|, |\varphi_{qq}|$ are taken in the domain

$$(x, y) \in \Omega, \quad |z| \leq \nu_1, \quad \text{grad}^2 z \leq \nu_2.$$

From the results of S. N. Bernstein on the solvability of the Dirichlet problem for equations of elliptic type (1), and from Theorems 1 and 2, the following theorem follows.

Theorem 3. *Consider in the disk $\Omega : x^2 + y^2 \leq R^2$ with boundary Γ the equation*

$$rt - s^2 = \varphi(x, y, z, p, q).$$

Let the function $\varphi(x, y, z, p, q)$ satisfy the following conditions: a) $\varphi(x, y, z, p, q)$ is an analytic function of $(x, y) \in \Omega$ and for all finite z, p, q ; b) $\varphi_z(x, y, z, p, q) \geq 0$

and $\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$ on all functions $z(x, y)$ continuously differentiable in $\Omega + \Gamma$. Let $\psi(\theta)$ be an analytic function of the polar angle θ , prescribed on Γ . Then, if the inequalities

$$4R^2 N_\varphi(\nu_1(R), \nu_2(R)) \leq 1, \quad 4R^2 T_\varphi(\nu_1(R), \nu_2(R)) \leq 1,$$

are satisfied, where

$$\nu_1(R) = (2 - \sqrt{3})R + R^2 + \frac{3}{0 \leq \theta \leq 2\pi} \max |\psi(\theta)|, \quad \nu_2(R) = \frac{2}{3} + 4R^2 + 4M(\psi),$$

then there exists an analytic solution $z(x, y)$ of the equation

$$rt - s^2 = \varphi(x, y, z, p, q),$$

turned with its convexity toward $z < 0$ and reducing on Γ to the function $\psi(\theta)$.

Theorem 3 remains valid if the condition $\varphi_z \geq 0$ is replaced by the condition

$$\varphi(x, y, z, p, q) \leq \Phi_0 \tilde{R}(p, q), \quad (3)$$

and the condition $4R^2 N_\varphi(\nu_1(R), \nu_2(R)) \leq 1$ by the condition $4R^2 N_{\tilde{R}}(\nu_2(R)) \leq 1/\Phi_0$.

We note that Leray ⁽³⁾ obtained a priori estimates for solutions of the equations

$$rt - s^2 + g(r, s, t, p, q, x, y, z) + h(r, s, t, p, q, x, y, z) = 0,$$

where $g(r, s, t, p, q, x, y, z)$ is a homogeneous function of the first degree with respect to r, s, t , and $h(r, s, t, p, q, z, x, y)$ and its derivatives are estimated by bounded functions of p, q, z, x, y . Namely, in ⁽³⁾ estimates were obtained for the first derivatives in the interior and for the second derivatives in the closed domain D , in terms of the boundary conditions, the properties of the function $g(r, s, t, p, q, z, x, y)$ and its derivatives, and also in terms of $\max |z|$ in the domain D and $\max(p^2 + q^2)$ on the boundary D . The estimates established in § 3 are obtained under conditions different from those in Leray' s work ⁽³⁾.

4. Let $z(x, y)$ be an m -times continuously differentiable solution ($m \geq 6$) of equation (1), turned with its convexity toward $z < 0$, and let, in the disk $\Omega : x^2 + y^2 \leq R^2$, where $z(x, y)$ is prescribed, the estimates

$$\max_{\Omega + \Gamma} |z| \leq L_0, \quad \max_{\Omega + \Gamma} (\text{grad}^2 z) \leq L_1$$

be known. The function $\varphi(x, y, z, p, q)$ is three times continuously differentiable with respect to $(x, y) \in \Omega$ and for all finite z, p, q . Further, $\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$ on all functions $u(x, y)$ continuously differentiable in $\Omega + \Gamma$.

Theorem 4. Let the conditions formulated in § 4 be satisfied with respect to the function $\varphi(x, y, z, p, q)$ and the solution $z(x, y)$ of equation (1). Then, if the radius R of the disk Ω satisfies the inequality $4R^2 T_\varphi(L_0, L_1) \leq 1$, estimates can be given for the second, third, and fourth derivatives of the function $z(x, y)$ in the disk

$$G_\delta : \quad x^2 + y^2 \leq (R - \delta)^2$$

depending only on the following quantities: $\delta > 0, k_0, L_0, L_1$, the upper bound of the moduli of the function $\varphi(x, y, z, p, q)$ and of its derivatives up to the third order inclusive in the domain

$$x^2 + y^2 \leq (R - \delta)^2, \quad |z| \leq L_0, \quad \text{grad}^2 z \leq L_1.$$

Theorem 5. Let, in the disk $\Omega : x^2 + y^2 \leq R^2$, the equation

$$rt - s^2 = \varphi(x, y, z, p, q)$$

be given, where the function $\varphi(x, y, z, p, q)$ is three times continuously differentiable with respect to $(x, y) \in \Omega$ and for all finite values z, p, q ; further, $\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$, $\varphi_z(x, y, z, p, q) \geq 0$ on all functions $u(x, y)$ continuously differentiable in $\Omega + \Gamma$. Let $\psi(\theta)$ be a continuously differentiable function of the polar angle θ , which admits a uniform approximation by analytic functions $\psi_n(\theta)$ together with the first derivatives and, moreover, such that the numbers $M(\psi_n)$ are uniformly bounded above by the number M_0 . Let the inequalities* be satisfied:

$$5R^2 N_\varphi(\nu_1(R), \nu_2(R)) \leq 1, \quad 5R^2 T_\varphi(\nu_1(R), \nu_2(R)) \leq 1. \quad (4)$$

Then there exists a function $z(x, y)$, three times continuously differentiable inside Ω , which satisfies inside Ω the equation

$$rt - s^2 = \varphi(x, y, z, p, q),$$

reduces on Γ to $\psi(\theta)$. The function $z(x, y)$ is turned with its convexity toward $z < 0$.

* The quantities $\nu_1(R), \nu_2(R)$ are defined in § 1; in the quantity $\nu_2(R)$ the number M_0 is substituted here in place of $M(\psi)$.

As above, the condition $\varphi_z \geq 0$ can be replaced by condition (3). Theorem 5 will then be valid if (4) is replaced by the inequality $5R^2 N_{\tilde{R}}(\gamma_2(R)) \ll 1/\Phi_0$.

5. As is known, every convex function has a second differential almost everywhere. We shall now understand by a generalized solution of equation (1), where $\varphi(x, y, z, p, q) \geq k_0 = \text{const} > 0$ is a continuous function of its variables, a convex function $z(x, y)$ satisfying equation (1) almost everywhere. Let D be a convex domain in which a generalized solution of equation (1) is given; then for every closed subdomain D_δ , separated from the boundary of D by a positive distance $\delta > 0$, the function $z(x, y)$ is continuously differentiable and $\sup_{D_\delta} \text{grad}^2 z < +\infty$. Let X be an interior point of D_δ , and let U be a circular neighborhood of the point X contained in D_δ . Then the continuously differentiable function $\psi(\theta) = z|_{\text{bd}U}$ admits a uniform approximation by analytic functions $\psi_n(\theta)$, together with their first derivatives, and in such a way that $M(\psi_n) \leq \sup_{D_\delta} (1 + \text{grad}^2 z)$.

Let the function $\varphi(x, y, z, p, q)$ satisfy the condition $\varphi'_z \geq a = \text{const} > 0$ on all continuously differentiable functions $u(x, y)$, or the condition $\varphi(x, y, z, p, q) \leq \Phi_0 \tilde{K}(p, q)$, where $\Phi_0 = \text{const} > 0$, $\tilde{K}(p, q) \geq R_0 = \text{const} > 0$. Then one can prove that if the generalized solutions $z_1(x, y)$ and $z_2(x, y)$ of equation (1), with convexity directed toward $z < 0$, coincide on the boundary of a convex domain D , then $z_1(x, y)$ and $z_2(x, y)$ coincide throughout the whole domain D (the functions $z_1(x, y)$ and $z_2(x, y)$ are considered to be defined and continuous in the closed domain \bar{D}).

From what has been set forth above, the following theorem follows.

Theorem 6. *Let the function $z(x, y)$ be a generalized solution of equation (1) in a convex domain D , and let the function $\varphi(x, y, z, p, q)$ satisfy the conditions formulated in § 5. Then, if the function $\varphi(x, y, z, p, q) \geq k_0 > 0$ is three times continuously differentiable with respect to x, y in the domain Ω and for all finite z, p, q , then the function $z(x, y)$ is at least four times continuously differentiable inside D .*

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